

Last time

因隔離無法來習題課交作業同學，請

$$F = \mathbb{Q}, \mathbb{R}, \mathbb{C}$$

將作業
照相後

email 給
助教)

V : vector space / F

• subspace

• $v_1, \dots, v_n \in V$, $\text{span}_F \{v_1, \dots, v_n\} \subset V$
subspace

• V is finite dimensional / F

$\Leftrightarrow V$ is generated by finitely many vectors / F

($V = \text{span}_F \{v_1, \dots, v_n\}$ for some

if $n=0$, we set $V = \{0\}$. ^{non-negative integer n}

$$\dim_F V = 0 \Leftrightarrow V = \{0\}$$

• Basis: A subset $\{v_1, \dots, v_n\} \subset V$ is called a basis of V if

(i) $V = \text{span}_F \{v_1, \dots, v_n\}$

(ii) $\{v_1, \dots, v_n\}$ is linearly independent.

• Replacement lemma:

if $V = \text{span}_F \{v_1, \dots, v_n\}$, let $\{u_1, \dots, u_k\}$ be a subset of V which is linearly independent,

then (i) $k \leq n$

(ii) \exists k vectors in $\{v_1, \dots, v_n\}$, say

v_1, \dots, v_k , such that

$$\text{span}_F \{v_1, \dots, v_k, v_{k+1}, \dots, v_n\} = \text{span}_F \{v_1, \dots, v_n\}$$

• If V is finite dimensional, then V must have a basis.

Define $\dim_F V$ = the cardinality of a basis.

(= the number of distinct elements
in a basis)

If V is not finite dimensional, then define $\dim_F V = \infty$.

Examples

① $V = F^n$

$$e_1 = (1, 0, \dots, 0) \quad e_2 = (0, 1, 0, \dots, 0) \quad \dots$$

$$e_n = (0, 0, \dots, 1)$$

Then $\{e_1, e_2, \dots, e_n\}$ is a basis of F^n .

$$\Rightarrow \dim_F F^n = n.$$

$$\begin{aligned}
\textcircled{2} \quad V &= \{ (x, y, z) \in F^3 \mid 3x + 2y + z = 0 \} \\
&= \{ (x, y, -3x - 2y) \mid x, y \in F \} \\
&= \{ x \cdot (1, 0, -3) + y \cdot (0, 1, -2) \mid x, y \in F \} \\
&= \text{span}_F \{ (1, 0, -3), (0, 1, -2) \}.
\end{aligned}$$

One checks that $\{ (1, 0, -3), (0, 1, -2) \}$

is linearly indep. in F , so

$$\dim_F V = 2.$$

$$\textcircled{3} \quad V = \left\{ (x_1, x_2, \dots) \mid \begin{array}{l} x_i \in F, \\ x_n + x_{n+1} = x_{n+2} \\ n = 1, 2, 3, \dots \end{array} \right\}$$

$$\underline{+}: (x_1, x_2, \dots) + (y_1, y_2, \dots) := (x_1 + y_1, x_2 + y_2, \dots)$$

Scalar product $\alpha \in F$

$$\alpha \cdot (x_1, x_2, \dots) := (\alpha x_1, \alpha x_2, \alpha x_3, \dots)$$

One checks (+, scalar product) equips V with a structure of vector space / F .

$\dim_F V = 2$. . . In fact,

$V \cong \text{span}_F \{ \underline{(0, 1, 1, 2, 3, \dots)} ; \underline{(1, 0, 1, 1, 2, 3, \dots)} \}$

Theorem \star Let V be a finite dimensional vector space / F with $\dim_F V = n$.

Let $\{v_1, \dots, v_m\}$ be a subset of V with $m > n$.

Then $\{v_1, \dots, v_m\}$ is linearly dependent.

proof: If $\{v_1, \dots, v_m\}$ is linearly indep.,

then $m \leq n$ by replacement lemma.

This is a contradiction..

□

Corollary. Consider the following system of

linear equations.

$$(*) \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1m}x_m = 0 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2m}x_m = 0 \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nm}x_m = 0 \end{cases}$$

$$a_{ij} \in F.$$

If $m > n$, then

(*) must have a non-trivial solution.

(非平凡解)

or 非自明

(The trivial solution to (*))

$$\text{is } x_1 = x_2 = \dots = x_m = 0.$$

$$\Leftrightarrow \exists (x_1, \dots, x_n) \neq (0, 0, \dots, 0)$$

satisfies (*).

proof: Consider

$$v_1 = (a_{11}, a_{21}, \dots, a_{n1}) \in F^n$$

$$v_2 = (a_{12}, a_{22}, \dots, a_{n2})$$

\vdots

$$v_m = (a_{1m}, a_{2m}, \dots, a_{nm}) \in F^n$$

$$\{v_1, \dots, v_m\} \subset F^n.$$

$$\dim_n F^n = n \quad ; \quad m > n.$$

By Theorem \textcircled{A} , ,

$\{v_1, \dots, v_m\}$ must be linearly dependent.

$\exists (x_1, \dots, x_m) \neq (0, \dots, 0)$ such that

$$x_1 v_1 + x_2 v_2 + \dots + x_m v_m = 0$$



$(*)$ holds with (x_1, \dots, x_m) . \square .

Example $V = F[x] =$ the space of polynomials / F .

Then $\dim_F V = \infty$.

If $\dim_F V < \infty$, then $\dim_F V = n$ for some n .

By Theorem \star , $\{1, x, x^2, \dots, x^n\}$ must

be linearly dependent. Namely, \exists

non-zero polynomial $a_n x^n + a_{n-1} x^{n-1} + \dots + a_0 \cdot 1 = 0$

$\Rightarrow f(x) := a_n x^n + a_{n-1} x^{n-1} + \dots + a_0 \cdot 1$ has

infinitely many roots in F . \rightarrow

Theorem $\star\star$

Let V be a finite dimensional vector space / F .

Let $W \subset V$ be a subspace.

Then • W is finite dimensional and

• $\dim_F W \leq \dim_F V$.

If $\dim_F W = \dim_F V$, then $W = V$.

proof Suppose W is not finite dimensional.

Then we can choose a sequence of subspaces of W .

$$\{0\} \subsetneq \text{span}_F \{w_1\} \subsetneq \text{span}_F \{w_1, w_2\} \subsetneq \dots$$

$$\subsetneq \text{span}_F \{w_1, w_2, w_3, \dots, w_n\} \subsetneq \dots \subsetneq W$$

$$(*) \quad w_n \notin \text{span}_F \{w_1, w_2, \dots, w_{n-1}\} \quad \forall n = 1, 2, \dots$$

Claim $\{w_1, \dots, w_n\}$ is linearly independent.

\therefore If $\{w_1, \dots, w_n\}$ is linearly dependent,

then

$$\alpha_1 w_1 + \alpha_2 w_2 + \dots + \alpha_i w_i = 0 \quad \begin{array}{l} \alpha_i \neq 0 \\ i \leq n. \end{array}$$

$$\alpha_1, \alpha_2, \dots, \alpha_i \in F$$

$$\Rightarrow w_i = \left(-\frac{\alpha_1}{\alpha_i}\right) \cdot w_1 + \left(-\frac{\alpha_2}{\alpha_i}\right) \cdot w_2 + \dots + \left(-\frac{\alpha_{i-1}}{\alpha_i}\right) \cdot w_{i-1}$$

$$\Rightarrow w_i \in \text{span}_F \{w_1, w_2, \dots, w_{i-1}\}$$

~~*~~ \Rightarrow *

This shows $\{w_1, \dots, w_n\}$ is linearly independent $\forall n$

Replacement lemma $\Rightarrow \dim_F V \geq n \quad \forall n$

$$\Rightarrow \dim_F V = \infty \quad \times \rightarrow$$

$\Rightarrow W$ is finite dimensional.

Let $\dim_{\mathbb{F}} W = m$. Then W has a basis

$\{w_1, \dots, w_m\}$ which is linearly indep. $/ \mathbb{F}$

$\Rightarrow m \leq \dim_{\mathbb{F}} V$ by Theorem ~~(*)~~.

$\dim_{\mathbb{F}} W$

Now we prove that if $\dim_{\mathbb{F}} W = \dim_{\mathbb{F}} V$,
then $W = V$.

Suppose $W \subsetneq V$. $\exists v \in V, v \notin W$.

$$W = \text{span}_{\mathbb{F}} \{w_1, \dots, w_m\}, \quad m = \dim_{\mathbb{F}} W \\ = \dim_{\mathbb{F}} V.$$

$v \notin W \Rightarrow \{w_1, \dots, w_m, v\}$ is linearly
independent $/ \mathbb{F}$.

$$\Rightarrow \dim_{\mathbb{F}} V \geq m+1 \quad \times \rightarrow \\ m \leq$$

This implies $W = V$. \square

Sum of subspaces

W_1, W_2 : two subspaces of V

Define $W_1 + W_2 := \left\{ w_1 + w_2 \mid \begin{array}{l} w_i \in W_i \\ i=1, 2 \end{array} \right\}$

$$W_1 + W_2 \subset V.$$

Then ^① $W_1 + W_2$ is also subspace of V .

$W_1 + W_2$ contains W_1 and W_2 .

(HW 2)

② $W_1 \cap W_2$ is also a subspace of V

$W_1 \cap W_2$ is contained in W_1 and W_2

(HW 2)

$$\dim_F(W_1 + W_2) + \dim_F(W_1 \cap W_2) = \dim_F W_1 + \dim_F W_2$$

2) Linear transformation

Let V and W be two vector spaces

We consider "morphisms" between
 V and W .

"morphism" = maps from V to W

which respect the structures

of V and W as vector spaces
 F .

Definition

A map $T: V \rightarrow W$ is a

linear transformation (^{or} homomorphism) if
morphism

$$(i) \quad T(v_1 + v_2) = T(v_1) + T(v_2) \quad \forall v_1, v_2 \in V$$

$$(ii) \quad T(\alpha \cdot v) = \alpha \cdot T(v) \quad \forall \alpha \in F, v \in V$$

By definition, $T(0) = 0$

$$\left(\because T(0+0) = T(0) + T(0) \right.$$

$$\Rightarrow T(0) = T(0) + T(0)$$

$$\Rightarrow T(0) = 0$$

Examples

$$\textcircled{1} V = \mathbb{F}^3, \quad W = \mathbb{F}^2$$

$$T: V \rightarrow W$$

$$T(a_1, a_2, a_3) := (a_1 + a_2 + 3a_3, 4a_1 - a_3)$$

Then T is a linear transformation

In terms of the standard basis

$$e_1 = (1, 0, 0), \quad e_2 = (0, 1, 0), \quad e_3 = (0, 0, 1)$$

$$f_1 = (1, 0), \quad f_2 = (0, 1)$$

$$T(a_1 e_1 + a_2 e_2 + a_3 e_3)$$

$$= a_1 \cdot (1, 4) + a_2 \cdot (1, 0) + a_3 \cdot (3, -1)$$

$$= a_1 \cdot (f_1 + 4f_2) + a_2 \cdot f_1 + a_3 \cdot (3f_1 - f_2)$$

② $V = F[x]$, $W = F[x]$

$$T: V \rightarrow W$$

$T(f(x)) := x \cdot f(x)$ is also a linear transformation.

$$T: V \rightarrow W$$

$T(f(x)) := f'(x)$ is a linear transformation.

③ W is a subspace of V .

Then $W \hookrightarrow V$
the inclusion map ($w \mapsto w$)

The inclusion map is a linear transformation.

Conversely, if $W \subset V$ is a subset

and W is a vector space / F ,

then W is a subspace of V

\Leftrightarrow the inclusion map $W \hookrightarrow V$

is a linear transformation.

④ $V = \mathbb{C}$ as vector space / \mathbb{R} .

$$\mathbb{C} = \text{span}_{\mathbb{R}} \{1, \sqrt{-1}\}$$

$$T: \mathbb{C} \rightarrow \mathbb{C}$$

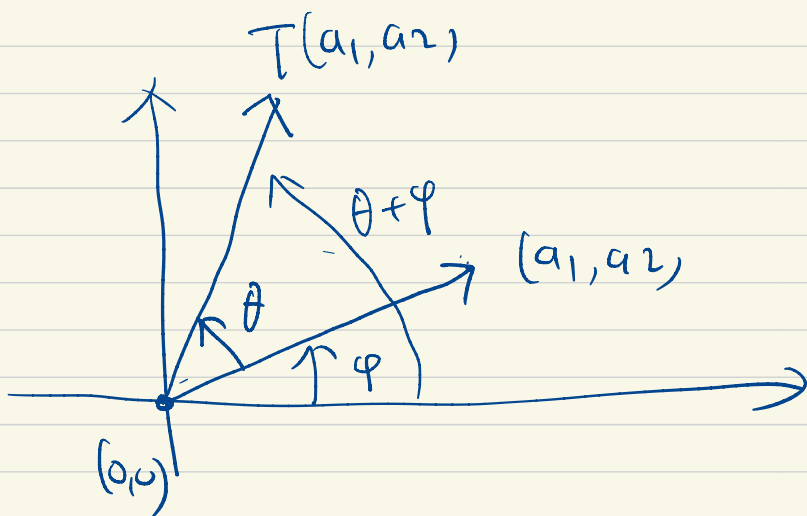
$$z \mapsto \bar{z} : \text{complex conjugation}$$

is a linear transformation.

$$\textcircled{5} \quad V = W = \mathbb{R}^2, \quad 0 \leq \theta \leq 2\pi$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad (\text{counterclockwise})$$

$(a_1, a_2) \mapsto T(a_1, a_2) :=$ the rotation of
 (a_1, a_2) by θ around
the origin $(0, 0)$



T is also a linear transformation.

We use the polar coordinate.

$$a_1 = r \cos \varphi, \quad a_2 = r \sin \varphi$$

$$T(a_1, a_2) = (r \cos(\varphi + \theta), r \sin(\varphi + \theta))$$

$$= (r(\cos\theta \cos\varphi - \sin\theta \sin\varphi), r(\cos\varphi \sin\theta + \sin\varphi \cos\theta))$$

$$= (\underbrace{r \cos\theta \cos\varphi} - \underbrace{r \sin\theta \sin\varphi}, \underbrace{r \cos\varphi \sin\theta} + \underbrace{r \sin\varphi \cos\theta})$$

$$= \cos\theta \cdot (\underbrace{r \cos\varphi}_{\parallel a_1}, \underbrace{r \sin\varphi}_{\parallel a_2}) + \sin\theta \cdot (\underbrace{-r \sin\varphi}_{\parallel a_2}, \underbrace{r \cos\varphi}_{\parallel a_1})$$

$$\Rightarrow T(a_1, a_2) = \cos\theta \cdot (a_1, a_2)$$

$$+ \sin\theta \cdot (-a_2, a_1)$$

Then one can easily verify T is a linear transformation.

$$\textcircled{6} T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$T(a_1, a_2) = (a_1^2, 0)$ is NOT

a linear transformation

$$T(2, 0) = (4, 0)$$

$$\not\parallel \quad (2, 0) = (1, 0) + (1, 0)$$

$$T(1, 0) + T(1, 0) = (1, 0) + (1, 0) = (2, 0)$$

• Isomorphism : (同構 = 相同結構)

A linear transformation $T: V \rightarrow W$

is an isomorphism if

$\exists S: W \rightarrow V$ linear transformation

such that $S \circ T = \text{Id}_V$ (:= the identity map $V \rightarrow V$)

and $T \circ S = \text{Id}_W$ (identity map of W)