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**2.6. symmetry of the plane.** A map from plane itself is called a **rigid motion**, or an **isometry**, if it is distance-preserving. Let  $S$  be a subset of the plane. Then the subgroups of rigid motions preserving  $S$  is called the **symmetry of  $S$** . It's well-known that:

**Example 2.6.1.**

Let  $S$  be the regular  $n$ -gon centered at the origin. Then the symmetry of  $S$  is the group  $D_{2n}$ .  $\square$

In order to build this is a more solid foundation, we need to work a little bit more.

A list of rigid motions consists of:

1. Orientation-preserving motions:
  - a. Translation.
  - b. Rotation.
2. Orientation-reversing motions:
  - a. Reflection.
  - b. Glide reflection, i.e. reflecting about a line  $l$  and then translating by a non-zero vector  $a$  parallel to  $l$ .

**Theorem 2.6.2.** *The above list is complete.*

*Sketch.* We first fix some notations:

$t_a$ : translation by a vector  $a$ .

$\rho_\theta$ : rotation by an angle  $\theta$  about the origin.

$r$ : reflection about the  $x$ -axis.

**Step 1.** Orientation preserving motions that fix the origin are  $\{\rho_\theta\}$ .

**Step 2.** Let  $m$  be an orientation preserving motion. If  $m(o) = a$ , then  $t_{-a}m = \rho_\theta$  for some  $\theta$ . by Step 1. Thus  $m = t_a\rho_\theta$ .

**Step 3.** If  $m$  is not a translation, i.e.  $\theta \neq 0$ , then  $m$  is a rotation about a point  $p$ . To see this, first show that  $m$  has a fixed point, denoted  $p$ , if  $\theta \neq 0$ . A point on the plane can be written as  $p + x$ ,

$$m(p + x) = t_a\rho_\theta(p + x) = \rho_\theta(p + x) + a = \rho_\theta(p) + \rho_\theta(x) + a = p + \rho_\theta(x).$$

**Step 4.** Orientation reversing motions that fix the origin are  $\{\rho_\theta r\}$ . For given such  $m$ , it's clear that  $rm$  preserves the orientation and fixes the origin. So  $rm = \rho_\theta$  for some  $\theta$ . Thus  $m = r\rho_\theta = \rho_{-\theta}r$ . Also note that  $\rho_\theta r$  is the reflection about  $l$ , denoted  $r_l$ , which is the line obtained by rotating  $x$ -axis by  $\frac{1}{2}\theta$ .

**Step 5.** Let  $m$  be an orientation reversing motion. Then  $m(o) = a$  for some  $a$ . Thus  $t_{-a}m$  is an orientation reversing motion that fixes origin, hence  $t_{-a}m = r_l$ . Therefore,  $m = t_a r_l$  which is a glide reflection.  $\square$

Indeed, let  $O(2, \mathbb{R})$  be the subgroup of motions that fix the origin. Then  $O(2, \mathbb{R})$  is generated by  $\{\rho_\theta, r\}$ . Let  $M$  be the groups of plane

rigid motions, then there is a group action  $M \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$ . The orbit of  $o$  is the whole  $\mathbb{R}^2$  and the stabilizer of  $o$  is  $O(2, \mathbb{R})$ .

For readers who want to know more about symmetry, we refer [Artin], Chapter 5.

**2.7. abelian groups.** In this section, we are going to study a simple but important category of groups, the abelian groups.

Given an abelian group  $G$ , we usually use  $+$  to denote the operation. We say that  $G$  can be generated by  $X \subset G$ , denoted  $G = \langle X \rangle$ , if every element of  $G$  can be written as  $\sum n_i x_i$  for some  $n_i \in \mathbb{Z}$  and  $x_i \in X$ . Note that  $n_i \neq 0$  for all but finitely many  $i$ .

A **basis** of an abelian group  $G$  is a *linearly independent* generating subset  $X$ . That is for distinct  $x_1, \dots, x_k \in X$ ,  $\sum n_i x_i = 0$  implies that  $n_i = 0$  for all  $i$ .

An abelian group with a basis is called a **free abelian group**. And the rank, denoted  $rk(F)$ , is  $|X|$ .

It's easy to prove that an abelian group is free if and only if it's a direct sum of  $\mathbb{Z}$ .

On the other hand, given a set  $X$ , we can always construct a free abelian group on the set  $X$  by consider the set

$$F := \left\{ \sum n_x x \mid x \in X, n_x \in \mathbb{Z}, n_x = 0 \text{ for all but finitely many } x \right\}.$$

The group operation on  $F$  is nothing but  $\sum n_x x + \sum m_x x := \sum (n_x + m_x) x$ . It's clear that  $X$  is a basis of  $F$  in this construction.

**Example 2.7.1.**

This construction appeared, for example, in algebraic topology. The groups of 1-chains is the free abelian group on the set of simplicial 1-chains.  $\square$

**Example 2.7.2.**

Let  $X$  be a Riemann surface, then the group of divisors,  $Div(X)$ , is the free abelian group on the set  $X$ .  $\square$

It has the following universal property:

**Proposition 2.7.3.** *Let  $F$  be a free abelian group with basis  $X$ . For any function  $f : X \rightarrow G$  to an abelian group  $G$ . There exist a unique homomorphism  $\varphi : F \rightarrow G$  extending  $f$ .*

*Proof.* Let  $\varphi(\sum n_x x) = \sum n_x f(x)$ , then verify it.  $\square$

**Corollary 2.7.4.** *Every abelian group is a quotient of a free abelian group.*

*Proof.* Let  $G$  be an abelian group. Let  $F$  be the free abelian group on the set  $G$ . Consider  $f : G \rightarrow G$  the identity map. Then we are done.  $\square$

**Example 2.7.5.**

$\mathbb{Q}$  can be describe as following. Let  $X = \{x_1, \dots, x_n, \dots\}$  and  $F$  the free abelian group on the set  $X$ . Take  $f : X \rightarrow \mathbb{Q}$  by  $f(x_i) = \frac{1}{i}$ . Then  $\mathbb{Q}$  is a quotient of  $F$ .  $\square$

We are now ready to state develop to main theorem of this section. We need the following:

**Lemma 2.7.6.** *If  $\{x_1, \dots, x_n\}$  is a basis of  $F$ , then  $\{x_1, \dots, x_{j-1}, x_j + ax_i, x_{j+1}, \dots, x_n\}$  is also a basis of  $F$  for  $i \neq j$  and  $a \in \mathbb{Z}$ .*

**Theorem 2.7.7.** *Let  $F$  be a free abelian group of rank  $n$  and  $G$  is a non-zero subgroup of  $F$ , then there exists a basis  $\{x_1, \dots, x_n\}$  of  $F$ , an integer  $r$  ( $1 \leq r \leq n$ ) and positive integer  $d_1, \dots, d_r$  such that  $d_1 | d_2 | \dots | d_r$  and  $G$  is free abelian group with basis  $\{d_1x_1, \dots, d_rx_r\}$ .*

*Sketch.* If  $n = 1$ , this is easy.

By induction, we assume that the theorem is true for all abelian groups of rank  $\leq n - 1$ . Let

$$S := \{s \in \mathbb{Z} | sy_1 + \dots + k_n y_n \in G, \text{ for some basis of } F, y_1, \dots, y_n\}.$$

Let  $d_1$  be the smallest positive integer in  $S$ . By changing basis, we may have  $\{x_1, y_2, \dots, y_n\}$  basis of  $F$  and  $d_1x_1 \in G$ .

Let  $H = \langle y_2, \dots, y_n \rangle$ . It's clear that  $F = H \oplus \mathbb{Z}x_1$ . We claim that  $G = (H \cap G) \oplus \mathbb{Z}d_1x_1$ .

Apply induction hypothesis to  $G \cap H < H$ , then we are done.  $\square$

**Corollary 2.7.8** (fundamental theorem of finitely generated abelian groups). *Let  $G$  be a finitely generated abelian group. Then there exist an integer  $r$  and positive integers  $d_1 | d_2 | \dots | d_t$  such that*

$$G \cong \mathbb{Z}_{d_1} \oplus \dots \oplus \mathbb{Z}_{d_t} \oplus \mathbb{Z}^r.$$

*Proof.* Let  $X$  be a finite generating set of  $G$ . And let  $F$  be the free abelian group on the set  $X$ . Then there is a surjective homomorphism  $F \rightarrow G$ . Apply Theorem 2.7.7 to  $\ker <$   $F$ .  $\square$

Now we restrict ourselves to finite abelian groups. Let  $G$  be a finite abelian group, by Corollary 2.7.8,

$$G \cong \mathbb{Z}_{d_1} \oplus \dots \oplus \mathbb{Z}_{d_t}.$$

These  $d_1, \dots, d_t$  are called **invariant factors**. We consider the factorization of  $d_i$  into prime factors, then we have for all  $i$ ,

$$d_i = p_1^{a_{i,1}} \dots p_k^{a_{i,k}}.$$

By Chinese Remainder Theorem, we have for all  $i$ ,

$$\mathbb{Z}_{d_i} \cong \mathbb{Z}_{p_1^{a_{i,1}}} \oplus \dots \oplus \mathbb{Z}_{p_k^{a_{i,k}}}.$$

Therefore,

$$G \cong \bigoplus_{j=1}^k (\bigoplus_{i=1}^t \mathbb{Z}_{p_j^{a_{i,j}}}).$$

It's clear that  $\bigoplus_{i=1}^t \mathbb{Z}_{p_j^{a_{i,j}}}$  is the Sylow  $p_j$ -subgroup. And these  $p_j^{a_{i,j}}$  are called **elementary divisors**.

**Example 2.7.9.**

Let  $G = \mathbb{Z}_{100} \oplus \mathbb{Z}_{40}$ . By Chinese Remainder Theorem,  $\mathbb{Z}_{100} \cong \mathbb{Z}_4 \oplus \mathbb{Z}_{25}$  and  $\mathbb{Z}_{40} \cong \mathbb{Z}_8 \oplus \mathbb{Z}_5$ . Thus

$$G \cong \mathbb{Z}_4 \oplus \mathbb{Z}_8 \oplus \mathbb{Z}_5 \oplus \mathbb{Z}_{25} \cong \mathbb{Z}_{20} \oplus \mathbb{Z}_{200}.$$

So invariant factors are 20, 200 and elementary divisors are 4, 8, 5, 25.  $\square$

**Example 2.7.10.**

Let  $G = \mathbb{Z}_m \oplus \mathbb{Z}_n$ . Then invariant factors are  $(m, n)$ ,  $[m, n]$ , the gcd and lcm of  $m, n$ .  $\square$

Let  $G$  be an abelian group, there there is a natural important homomorphism  $m : G \rightarrow G$  by  $m(x) := mx$  for  $m \in \mathbb{N}$ . The image is denoted  $mG$  and kernel is denoted  $G[m]$ . Let  $G(p) = \{u \in G \mid o(u) = p^n \text{ for some } n \geq 0\}$ . One can show that  $G(p)$  is the Sylow  $p$ -subgroup of  $G$ . And  $G$  is a direct sum of Sylow subgroups. Thus it remains to study finite abelian  $p$ -groups. The only non-trivial part of classical theory is showing that a finite abelian  $p$ -group is a direct sum of cyclic  $p$ -groups.