

# Formal Deformation Theory

## and

## Examples of Deformation Functors

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### 0 Notations and basic definitions

**Notation 0.1.** We work over  $k = \bar{k}$ ; all schemes are over  $k$ . Let

$\mathcal{A}$  = the category of local artinian  $k$ -algebras with residue field  $k$ ;

$\hat{\mathcal{A}}$  = the category of complete local noetherian  $k$ -algebras with residue field  $k$ ;

$\mathcal{A}^*$  = the category of local noetherian  $k$ -algebras with residue field  $k$ . Note  $\mathcal{A} \supset \hat{\mathcal{A}} \supset \mathcal{A}^*$ . An algebraic schemes means a scheme over  $k$  of finite type.

**Definition 0.2.** Let  $X$  be an algebraic scheme. A deformation of  $X$  parametrized by  $S$  is a fiber product

$$\eta : \begin{array}{ccc} X & \longrightarrow & \mathcal{X} \\ \downarrow & & \downarrow \pi: \text{flat surj.} \\ k & \xrightarrow{s} & S \end{array}$$

Morphism between deformations is a  $\phi$  making a commutative diagram

$$\begin{array}{ccc} & X & \\ & \swarrow & \searrow \\ \mathcal{X} & \xrightarrow{\phi} & \mathcal{Y} \\ & \searrow & \swarrow \\ & S & \end{array}$$

We denote a deformation by  $(S, \eta)$ . A deformation is called infinitesimal if  $S = \text{Spec } A$  for some  $A \in \mathcal{A}$ ; it's called first-order if  $S = \text{Spec } k[\epsilon]$ .

**Remark 0.3.** Let  $(S, \eta)$  be a deformation. A morphism of algebraic schemes  $(S', s') \rightarrow (S, s)$  induces a fiber product digram:

$$\begin{array}{ccccc} X & \longrightarrow & \mathcal{X} \times_S S' & \longrightarrow & \mathcal{X} \\ \downarrow & & \downarrow \eta' & & \downarrow \eta \\ k & \xrightarrow{s'} & S' & \longrightarrow & S \end{array}$$

in particular  $(S', \eta')$  is a deformation of  $X$  over  $S'$ . When  $S' = k[\epsilon]$ , this construction yields a map  $\rho : T_{S,s} \rightarrow \text{Def}_X(k[\epsilon])$ . If  $X$  is a smooth variety,  $\text{Def}_X(k[\epsilon])$  coincides with  $H^1(X, T_X)$ , and in this case we call  $\rho : T_{S,s} \rightarrow H^1(X, T_X)$  the Kodaira-Spencer map.

**Remark 0.4.** (cf. Lemma 1.2.3 in [1]) Suppose  $Z_0 \subseteq_{\text{C.S.}} Z$  and  $\mathcal{I}_{Z_0}$  is nilpotent (where "C.S." stands for "closed subscheme"). Then the affineness of  $Z_0$  implies that of  $Z$ . Consequently, every infinitesimal deformation of an affine scheme is affine.

**Remark 0.5.** Suppose  $X = \text{Spec } B_0$  is affine and we have a morphism between infinitesimal deformation:

$$\begin{array}{ccc}
 & B_0 & \\
 & \nearrow & \nwarrow \\
 B & \xrightarrow{\phi} & B' \\
 & \nwarrow & \nearrow \\
 & A & 
 \end{array}$$

Then,  $B \otimes_A k \cong B_0 \cong B' \otimes_A k$  and so  $\tilde{\phi} : B/\mathfrak{m}_A B \rightarrow B'/\mathfrak{m}_A B'$  is an isomorphism. Using flatness and Nakayama lemma, one can show that  $\phi$  is an isomorphism as well.

## 1 Functor of Artin rings

**Notation 1.1.** For  $\Lambda \in \mathcal{A}^*$ , consider the following categories:

$\mathcal{A}_\Lambda$  = the category of local artinian  $\Lambda$ -algebras with residue field  $k$ ;

$\hat{\mathcal{A}}_\Lambda$  = the category of complete local noetherian  $\Lambda$ -algebras with residue field  $k$ ;

$\mathcal{A}_\Lambda^*$  = the category of local noetherian  $\Lambda$ -algebras with residue field  $k$ .

**Definition 1.2.** A functor of Artin rings is a covariant functor

$$F : \mathcal{A}_\Lambda \rightarrow (\text{Sets}), \text{ where } \Lambda \in \mathcal{A}^*.$$

We say  $F$  is prorepresentable if  $F \cong h_{R/\Lambda} : A \mapsto \text{Hom}_{\mathcal{A}_\Lambda}(R, A)$  for some  $R \in \hat{\mathcal{A}}_\Lambda$ .

(Of course, a representable functor is prorepresentable.)

**Remark 1.3.** A fiber product

$$\begin{array}{ccc}
 A' \times_A A'' & \longrightarrow & A'' \\
 \downarrow & & \downarrow \\
 A' & \longrightarrow & A
 \end{array}$$

in  $\mathcal{A}_\Lambda$  induces  $\alpha : F(A' \times_A A'') \rightarrow F(A') \times_{F(A)} F(A'')$ . If  $F(k) = *$  and  $\alpha$  is bijective when  $A = k$  and  $A'' = k[\epsilon]$ , then  $F(k[\epsilon])$  inherits a structure of  $k$ -vector space, as follows: The addition  $F(k[\epsilon]) \times F(k[\epsilon]) \rightarrow F(k[\epsilon])$  is induced by

$$\begin{aligned}
 k[\epsilon] \times_k k[\epsilon] &\rightarrow k[\epsilon] \\
 (a + b\epsilon, a + b'\epsilon) &\mapsto a + (b + b')\epsilon,
 \end{aligned}$$

the multiplication by  $c \in k$  is

$$\begin{aligned} k[\epsilon] &\rightarrow k[\epsilon] \\ a + b\epsilon &\mapsto a + (cb)\epsilon, \end{aligned}$$

and the zero element  $0$  is  $\text{im}(F(k) \rightarrow F(k[\epsilon]))$ .  $F(k[\epsilon]) =: t_F$  is called the tangent space of  $F$ . For a natural transformation  $f : F \rightarrow G$  between such functors,  $df : t_F \rightarrow t_G$  is called the differential of  $f$ . It is  $k$ -linear.

**Definition 1.4.** (formal element) A functor of Artin rings  $F : \mathcal{A}_\Lambda \rightarrow (\text{Sets})$  can be extended to  $\hat{F} : \hat{\mathcal{A}}_\Lambda \rightarrow (\text{Sets})$  by setting

$$\hat{F}(R) = \varprojlim F(R/m_R^{n+1}) \quad (n \geq 0)$$

and the morphism  $\hat{F}(\varphi)$  is given by  $\{F(R/m_R^{n+1}) \rightarrow F(R/m_S^{n+1})\}_{n \geq 0}$ .

An element  $\hat{u} = \{u_n \in F(R/m_R^{n+1})\} \in \hat{F}(R)$  is called a formal element.

**Proposition 1.5.** Let  $R \in \mathcal{A}_\Lambda$ . Then there exists a bijection

$$\{\hat{u} \in \hat{F}(R)\} \longleftrightarrow \{\text{natural transformations } h_{R/\Lambda} \rightarrow F\}.$$

**Definition 1.6.**

- (1)  $f : F \rightarrow G$  is smooth if  $\forall$  surjection  $B \rightarrow A$ ,  $F(B) \rightarrow F(A) \times_{G(A)} G(B)$  is also surjective.
- (2)  $F$  is smooth if  $\forall$  surjection  $B \rightarrow A$ ,  $F(B) \rightarrow F(A)$  is surjective (ie. the natural transformation from  $F$  to the trivial functor is smooth).

**Definition 1.7.** Fix  $\hat{u} \in \hat{F}(R)$ , where  $R \in \hat{\mathcal{A}}_\Lambda$ . Recall that  $\hat{u}$  induces  $\hat{u} : h_{R/\Lambda} \rightarrow F$ .

- (1) We call  $\hat{u}$  semi-universal if  $\hat{u} : h_{R/\Lambda} \rightarrow F$  is smooth, and  $t_{R/\Lambda} \rightarrow t_F$  is bijective (where  $t_{R/\Lambda}$  is the tangent space for  $h_{R/\Lambda}$ ).
- (2) We call  $\hat{u}$  universal if  $\hat{u} : h_{R/\Lambda} \rightarrow F$  is an isomorphism.

**Definition 1.8.** Let  $R$  be a local  $k$ -algebra with residue field  $k$ . A small extension of  $R$  is a  $k$ -extension of  $R$  by  $k$ :

$$0 \longrightarrow k \longrightarrow R' \longrightarrow R \longrightarrow 0$$

such that  $k^2 = 0$  in  $R'$ . In this case  $k \trianglelefteq R'$  can be proved to be principle.

**Theorem 1.9.** (Schelessinger) Suppose  $F(k) = *$ . Recall the notation

$$\alpha : F(A'' \times_A A') \rightarrow F(A') \times_{F(A)} F(A'')$$

(1)  $F$  has a semi-universal element if and only if the following three conditions hold:

- (i)  $(\bar{H})$   $\alpha$  is surjective for every small extension  $A'' \rightarrow A$ .
- (ii)  $(H_\epsilon)$   $\alpha$  is bijective when  $A = k$  and  $A'' = k[\epsilon]$ .
- (iii)  $(H_f)$   $\dim_k(t_F) < \infty$ .

(2)  $F$  has a universal element if and only if, moreover, the following condition  $(H)$  holds:

$$F(A' \times_A A') \rightarrow F(A') \times_{F(A)} F(A')$$

is surjective for every small extension  $A' \rightarrow A$ .

**Example 1.10.** For an algebraic scheme  $X$ , define

$$\begin{aligned} \text{Def}_X : \mathcal{A} &\rightarrow (\text{Sets}) \\ A &\mapsto \{\text{deformation of } X \text{ over } A\} / \text{isomorphism} \end{aligned}$$

Then  $\text{Def}_X(k) = *$ , and  $\text{Def}_X$  satisfies  $\bar{H}$  and  $H_\epsilon$ .

## 2 Formal/Algebraic deformations

In this section, we discuss when a series of infinitesimal deformation comes from a "true" deformation, that is, a deformation over some  $A \in \hat{\mathcal{A}}$ .

**Definition 2.1.** Let  $X$  be an algebraic scheme and  $A \in \hat{\mathcal{A}}$ . A formal deformation of  $X$  over  $A$  is  $\hat{\eta} \in \widehat{\text{Def}}_X(A)$ , ie.,

$$\hat{\eta} = \left\{ \eta_n : \begin{array}{ccc} X & \xrightarrow{f_n} & \mathcal{X}_n \\ \downarrow & & \downarrow \pi_n \\ k & \longrightarrow & \text{Spec } A_n \end{array} \right\}_{n \geq 0},$$

where  $A_n = A/m_A^{n+1}$ , each  $\eta_n$  is a fiber product, and the pullback  $\mathcal{X}_n \otimes_{A_n} A_{n-1}$  is isomorphic to  $\mathcal{X}_{n-1}$ .

A natural question is, is it true that all these fiber products are pullbacks of some deformation over  $A$ ? That is, we ask for the existence of a deformation  $\pi : \mathcal{X} \rightarrow A$ , making the fiber product diagram:

$$\begin{array}{ccccccccccc} X & \xrightarrow{f_0} & \cdots & \longrightarrow & \mathcal{X}_{n-1} & \longrightarrow & \mathcal{X}_n & \longrightarrow & \cdots & \longrightarrow & \mathcal{X} \\ \downarrow & & & & \downarrow \pi_{n-1} & & \downarrow \pi_n & & & & \downarrow \pi \\ k & \longrightarrow & \cdots & \longrightarrow & \text{Spec } A_{n-1} & \longrightarrow & \text{Spec } A_n & \longrightarrow & \cdots & \longrightarrow & \text{Spec } A \end{array}$$

**Definition 2.2.** If such a deformation

$$\begin{array}{ccc} X & \longrightarrow & \mathcal{X} \\ \downarrow & & \downarrow \pi \\ k & \longrightarrow & \text{Spec } A \end{array}$$

exists, we call  $(A, \eta_n)$  effective.

**Remark 2.3.** (Grothendieck) If  $X$  is a proper algebraic scheme, then two such "liftings" must be isomorphic.

**Remark 2.4.** A formal deformation is the same as giving a morphism of formal schemes

$$\bar{\pi} : \bar{\mathcal{X}} \rightarrow \text{Sepcf}(A)$$

where  $\bar{\mathcal{X}} = (X, \varprojlim \mathcal{O}_{\mathcal{X}_n})$  and  $\text{Sepcf}(A)$  is a formal spectrum;  $\text{Sepcf}(A) = \widehat{\mathcal{O}}_{\text{Spec } A} = (*, \varprojlim \text{Spec}(A/m_A^n))$ .

**Remark 2.5.** A formal deformation is effective is and only if there exists a deformation

$$\begin{array}{ccc} X & \longrightarrow & \mathcal{X} \\ \downarrow & & \downarrow \\ k & \longrightarrow & \text{Spec } A \end{array}$$

such that  $\bar{\mathcal{X}}$  is the completion of  $\mathcal{X}$  along  $X$ , ie.,  $\bar{\mathcal{X}} = \hat{\mathcal{X}} = (X, \lim_{\leftarrow} \mathcal{O}_{\mathcal{X}}/\mathcal{I}_X^n)$ . For example, for  $X = \mathbb{P}^r$ ,

the formal deformation  $\left\{ \eta_n : \begin{array}{ccc} \mathbb{P}^r & \longrightarrow & \mathbb{P}_{A_n}^r \\ \downarrow & & \downarrow \\ k & \longrightarrow & \text{Spec } A_n \end{array} \right\}$  is effective; the associated formal scheme is the

completion of  $\mathbb{P}_A^r$  along  $\mathbb{P}^r$ , denoted by  $\mathcal{P}_A^r := (\mathbb{P}^r, \lim_{\leftarrow} \mathcal{O}_{\mathbb{P}^r/A_n})$ .

**Theorem 2.6.** (Grothendieck) Let  $X$  be a projective scheme.

(1) Let  $A \in \hat{\mathcal{A}}$  and  $\bar{\pi} : \bar{\mathcal{X}} \rightarrow \text{Specf}(A)$  be a formal deformation of  $X$  over  $A$ . Assume  $\exists j$  such that the diagram

$$\begin{array}{ccc} \bar{\mathcal{X}} & \xleftarrow{j} & \mathcal{P}_A^r \\ & \searrow_{\bar{\pi}} & \downarrow p \\ & & \text{Specf}(A) \end{array}$$

is commutative, where  $p$  is the projection. Then  $\bar{\pi}$  is effective.

(2) When  $H^2(X, \mathcal{O}_X) = 0$ , every formal deformation of  $X$  is effective.

### 3 Obstruction space

We first define the space of extension classes, which inherits a module structure.

**Definition 3.1.** Given an  $A$ -algebra  $R$  and an  $A$ -module  $I$ , the space of isomorphism classes of  $A$ -extensions of  $R$  by  $I$  is denoted by  $\text{Ex}_A(R, I)$ ; we denote an extension

$$0 \longrightarrow I \longrightarrow R' \longrightarrow R \longrightarrow 0$$

by  $(R', \varphi)$  and its class by  $[R', \varphi]$ . Here, we always demand  $I^2 = 0$ .

**Definition 3.2.** Let  $F$  be a functor of Artin rings. An obstruction space for  $F$  is a vector space over  $k$ , denoted by  $v(F)$ , such that  $\forall A \in \mathcal{A}_\Lambda, \forall \zeta \in F(A)$ , there is a linear transformation  $\zeta_v : \text{Ex}_\Lambda(A, k) \rightarrow v(F)$ , with

$$\ker \zeta_v = \left\{ [ 0 \longrightarrow I \longrightarrow \tilde{A} \longrightarrow A \longrightarrow 0 ] \mid \zeta \in \text{im}(F(\tilde{A}) \rightarrow F(A)) \right\}.$$

**Remark 3.3.** Take  $F$  to be a deformation functor and consider an deformation  $\zeta \in F(A)$ . Intuitively, the kernel of  $\zeta_v$  collects all extension classes that lift  $\zeta$ .

#### 3.1 Module structure on $\text{Ex}_A(R, I)$

An extension is called trivial if it has a section, that is, it splits. A trivial extension can be constructed by considering the  $A$ -algebra  $R \tilde{\oplus} I$ , whose module structure is  $R \oplus I$ , and multiplication is given by  $(r, i) \cdot (s, j) := (rs, rj + si)$ . With the projection  $p : R \tilde{\oplus} I \rightarrow R$ ,  $(R \tilde{\oplus} I, p)$  is clearly a trivial extension.

**Remark 3.4.** In fact, every trivial extension  $(R', \varphi)$  is isomorphic to  $(R \tilde{\oplus} I, p)$ .

The module structure on  $\text{Ex}_A(R, I)$  is based on two operations.

**Definition 3.5.** (pullback) Given

$$(R', \varphi) : 0 \longrightarrow I \longrightarrow R' \xrightarrow{\varphi} R \longrightarrow 0 ,$$

and  $f : S \rightarrow R$  an  $A$ -algebra homomorphism, the pullback of  $(R', \varphi)$  by  $f$  is the  $A$ -extension  $f^*(R', \varphi)$ :

$$f^*(R', \varphi) : 0 \longrightarrow I \longrightarrow R' \times_R S \longrightarrow S \longrightarrow 0 \in \text{Ex}_A(S, I)$$

**Definition 3.6.** (pushout) Given  $(R', \varphi)$  and  $\lambda : I \rightarrow J$  an  $R$ -module homomorphism, the pushout of  $(R', \varphi)$  by  $\lambda$  is the  $A$ -extension  $\lambda_*(R', \varphi)$ :

$$\lambda_*(R', \varphi) : 0 \longrightarrow J \longrightarrow R' \amalg_I J \longrightarrow R \longrightarrow 0 \in \text{Ex}(R, J),$$

where

$$R' \amalg_I J := \frac{R' \tilde{\oplus} J}{\{(-\alpha(i), \lambda(i)) \mid i \in I\}}.$$

**Definition 3.7.** Given  $[R', \varphi]$  and  $[R'', \psi] \in \text{Ex}_A(R, I)$ , we have the following diagram:

$$\begin{array}{ccccccc}
& & 0 & & 0 & & 0 \\
& & \downarrow & & \downarrow & & \downarrow \\
& & I \oplus I & \longrightarrow & I & \xlongequal{\quad} & I \\
& & \searrow & & \downarrow & & \downarrow \\
0 & \longrightarrow & I & \longrightarrow & R' \times_R R'' & \longrightarrow & R' \longrightarrow 0 \\
& & \parallel & & \downarrow & \searrow & \downarrow \\
0 & \longrightarrow & I & \longrightarrow & R'' & \longrightarrow & R \longrightarrow 0 \\
& & & & \downarrow & & \downarrow \\
& & & & 0 & & 0
\end{array}$$

which defines  $(R' \times_R R'', \zeta) : 0 \longrightarrow I \longrightarrow I \longrightarrow R' \times_R R'' \xrightarrow{\zeta} R \longrightarrow 0$ . Let  $\delta : I \oplus I \rightarrow I$  be defined by  $(i, j) \mapsto i + j$ . Then the addition is

$$[R', \varphi] + [R'', \psi] := [\delta_* p(R' \times_R R'', \delta)].$$

On the other hand, for  $[R', \varphi] \in \text{Ex}_A(R, I)$ ,  $r \in R$ , let  $r : I \rightarrow I$  be the multiplication by  $r$ . Define  $r \cdot [R', \varphi] := [r_*(R', \varphi)]$ . The identity element in  $\text{Ex}_A(R, I)$  is the trivial extension  $[R \tilde{\oplus} I, p]$ .

## 4 More on $\text{Def}_{\mathcal{B}_0}$

Here we give more concrete examples of the deformation functor  $\text{Def}_{\mathcal{B}_0}$ .

**Definition 4.1.**  $\text{Ex}_A(R, R) =: T_{R/A}^1$  is the first cotangent module of  $R$  over  $A$ .

**Definition 4.2.** (*extension of schemes*) Let  $X$  be an  $S$ -scheme. An extension of  $X$  over  $S$  is

$$\mathcal{E} : 0 \rightarrow I \rightarrow \mathcal{O}_{X'} \rightarrow \mathcal{O}_X \rightarrow 0,$$

where  $I$  is an  $\mathcal{O}_X$ -module with  $I^2 = 0$  and  $\varphi$  is an  $\mathcal{O}_S$ -algebra homomorphism.

Define  $\text{Ex}(X/S, I)$  to be the isomorphism classes of extensions. The trivial extension  $\mathcal{O}_X \tilde{\oplus} I$  can be defined similarly as in the module case.

**Theorem 4.3.** Let  $X$  be a finite type  $S$ -scheme, and both are algebraic scheme. Suppose  $I$  is locally free with finite rank on  $S$ , and  $X$  is reduced and  $S$ -smooth on a dense open set. Then

$$\text{Ex}(X/S, I) \cong \text{Ext}_{\mathcal{O}_X}^1(\Omega_{X/S}, I)$$

*proof.* The maps are given by

$$\begin{aligned} \text{Ex}(X/S, I) &\rightarrow \text{Ext}_{\mathcal{O}_X}^1(\Omega_{X/S}, I) \\ (0 \rightarrow I \rightarrow \mathcal{O}_{X'} \rightarrow \mathcal{O}_X \rightarrow 0) &\mapsto (0 \rightarrow I \rightarrow \Omega_{X'/S}|_X \rightarrow \Omega_{X/S} \rightarrow 0) \end{aligned}$$

and

$$\begin{aligned} \text{Ext}_{\mathcal{O}_X}^1(\Omega_{X/S}, I) &\rightarrow \text{Ex}(X/S, I) \\ (0 \rightarrow I \rightarrow \mathcal{A} \rightarrow \Omega_{X/S} \rightarrow 0) &\mapsto (0 \rightarrow I \rightarrow \mathcal{A} \times_{\Omega_{X/S}} \mathcal{O}_X \rightarrow \mathcal{O}_X \rightarrow 0), \end{aligned}$$

where, the algebra structure on  $\mathcal{A} \times_{\Omega_{X/S}} \mathcal{O}_X$  is  $(a, f) \cdot (a', f') := (fa' + f'a, ff')$ . □

**Corollary 4.4.**  $T_X^1 \cong \text{Ext}_{\mathcal{O}_X}^1(\Omega_X^1, \mathcal{O}_X)$ .

**Proposition 4.5.** For a  $k$ -algebra  $B_0$ ,  $\text{Def}_{B_0}(k[\epsilon]) \cong T_{B_0}^1$ .

**Remark 4.6.** Suppose  $B_0 = k[x_1, \dots, x_d]/J$ , with  $J$  prime. Then there is an exact sequence:

$$0 \rightarrow \text{Hom}(\Omega_{B_0/k}, \Omega_{B_0}) \rightarrow \text{Hom}(\Omega_{k[x_1, \dots, x_d]/k} \otimes B_0, B_0) \rightarrow \text{Hom}(J/J^2, B_0) \rightarrow T_{B_0}^1 \rightarrow 0,$$

and thus  $T_{B_0}^1$  can be computed. The result is: If  $J$  is generated by a regular sequence, then

$$T_{B_0}^1 \cong \frac{k[x_1, \dots, x_d]^n}{\left( \begin{pmatrix} \frac{\partial f_1}{\partial x_1} \\ \vdots \\ \frac{\partial f_n}{\partial x_1} \end{pmatrix}, \dots, \begin{pmatrix} \frac{\partial f_1}{\partial x_d} \\ \vdots \\ \frac{\partial f_n}{\partial x_d} \end{pmatrix} \right)} \otimes_{k[x_1, \dots, x_d]} B_0.$$

For example,

$$(1) \text{ For hypersurface } B_0 = V(f), T_{B_0}^1 \cong \frac{k[x_1, \dots, x_d]}{(f, \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_d})}.$$

$$(2) \text{ For } f = x^2 - y^2, T_{B_0}^1 \cong \frac{k[x, y]}{(x^2 - y^2, x, y)} \cong k;$$

$$\text{For } f = y^3 - x^2, T_{B_0}^1 \cong \frac{k[x, y]}{(y^3 - x^2, y^2, x)} \cong k^2.$$

## 5 Obstruction space for a nonsingular algebraic variety

### Proposition 5.1.

- (1) For a nonsingular algebraic variety  $X$ ,  $H^2(X, T_X)$  is an obstruction space for  $\text{Def}_X$ .
- (2) Let  $e : 0 \rightarrow (t) \rightarrow \tilde{A} \rightarrow A \rightarrow 0$  be a small extension. Then, if  $o_\xi(e) = 0$ , there exists a transitive action of  $H^1(X, T_X)$  on  $\{\text{liftings to } \tilde{A}\}$ .

### Example 5.2.

- (1) Nonsingular curves are unobstructed.
- (2) Let  $X$  be nonsingular. Then  $H^1(X, T_X) = 0 \iff X$  is rigid. Indeed, for the "if" part, note that the first order deformation is trivial and use statement (2) in the proposition.  
In particular,  $\mathbb{P}^{n_1} \times \dots \times \mathbb{P}^{n_k}$  is rigid.

## 6 Second cotangent module and obstructions

In this section we introduce another obstruction space for  $\text{Def}_{B_0}$ , other than  $H^2(X, T_X)$ .  
Let  $B_0 = P/J$ , where  $P$  is a smooth  $k$ -algebra. Take

$$\eta : 0 \longrightarrow R \xrightarrow{\iota} F \xrightarrow{j} J \longrightarrow 0,$$

where  $F$  is free over  $P$ . Define  $\lambda : \bigwedge^2 F \rightarrow F$  by  $x \wedge y \mapsto (jx)y - (jy)x$ , and let  $R^{tr} := \text{im}(\lambda)$  be the module of trivial relations. The second cotangent module of  $B_0$  is the  $B_0$ -module defined by the exact sequence:

$$\text{Hom}_{B_0}(J/J^2, B_0) \rightarrow \text{Hom}_{B_0}(F \otimes_P B_0, B_0) \rightarrow \text{Hom}_{B_0}(R/R^{tr}, B_0) \rightarrow T_{B_0}^2 \rightarrow 0.$$

**Example 6.1.** If  $J = (f_1, \dots, f_n)$ , and  $F = P^n$ , then  $R/R^{tr} = H_1(K_\bullet(f_1, \dots, f_n))$ , i.e., the first cohomology group of the Koszul complex. Therefore, if  $J$  is generated by a regular sequence, then  $T_{B_0}^2 = 0$ , since  $R/R^{tr} = 0$ .

**Definition 6.2.** For an algebraic scheme  $X$ , let  $T_X^2$  be the sheaf glued by  $T_{B_0}^2$ . It's the "second cotangent sheaf".

**Proposition 6.3.**  $T_{B_0}^2$  is an obstruction space for  $\text{Def}_{B_0}$ .

**Remark 6.4.** Let  $X = \text{Spec } B_0$  and  $\dim_k(T_{B_0}^1) < \infty$ . By Schlessinger's theorem, there exists a semiuniversal element  $(R, \{\eta_n\})$ , and in fact we have the inequalities

$$\dim_k(T_{B_0}^1) \geq \dim(R) \geq \dim_k(T_{B_0}^1) - \dim_k(T_{B_0}^2).$$

Moreover, the first is an equality if and only if  $X_0$  is unobstructed; in particular if  $B_0$  is l.c.i., then  $X$  is unobstructed.



## 7 Local Hilbert functor

Let  $X \subseteq_{C.S.} Y$  be algebraic schemes. A family of deformations of  $X$  in  $Y$ , parametrized by  $S$ , is a fiber product

$$\begin{array}{ccccc} X & \longrightarrow & \mathcal{X} & \hookrightarrow & Y \times S \\ \downarrow & & \downarrow \pi: \text{flat} & \swarrow \pi & \\ k & \longrightarrow & S & & \end{array} .$$

This defines a functor

$$H_X^Y : \mathcal{A} \rightarrow (\text{Sets})$$

$$A \mapsto \{\text{deformations of } X \text{ in } Y \text{ over } A\} / \text{isomorphisms},$$

called the local Hilbert functor of  $X$  in  $Y$ .

### Proposition 7.1.

- (1)  $H_X^Y$  satisfies  $H_0$ ,  $H_\epsilon$ ,  $\bar{H}$  and  $H$  in Schlessinger's theorem.
- (2)  $H_X^Y(k[\epsilon]) = H^0(X, N_{X/Y})$ .

**Proposition 7.2.** *If  $X \subseteq Y$  is a regular closed embedding, then  $H^1(N_{X/Y})$  is an obstruction space for  $H_X^Y$ .*

## 8 Deformation of morphism leaving domain and target fixed

In this section we consider the following fiber product:

$$\begin{array}{ccc} X & \longrightarrow & X \times S \\ \downarrow f & & \downarrow F \\ Y & \longrightarrow & Y \times S \\ \downarrow & & \downarrow \pi: \text{projection} \\ k & \longrightarrow & S \end{array}$$

with  $\pi \circ F$  flat. This is a deformation of  $f$  wdat (with fixed domain and target). The associated deformation functor is  $\text{Def}_{X/f/Y} : \mathcal{A} \rightarrow (\text{Sets})$ .

**Proposition 8.1.** *Let  $f : X \rightarrow Y$  be a morphism between algebraic schemes, with  $X$  projective, reduced, and  $Y$  nonsingular. Then:*

- (1)  $\text{Def}_{X/f/Y} \cong H_{\Gamma_f}^{X \times Y}$
- (2)  $\text{Def}_{X/f/Y}(k[\epsilon]) = H^0(X, f^*T_Y)$
- (3)  $H^1(X, f^*T_Y)$  is an obstruction space for  $\text{Def}_{X/f/Y}$ .

**Remark 8.2.** *The reducibility and nonsingularity are used only in (2) and (3).*

**Example 8.3.** *Suppose  $\mathbb{P}^1 \cong R \subseteq S$ ,  $S$  is nonsingular, and  $E^2 = -n \leq -1$ , ie.  $\deg \mathcal{O}_E(E) = -n$ . Consider the SES*

$$0 \longrightarrow T_E \longrightarrow T_S|_E \longrightarrow N_{E/S} \longrightarrow 0 .$$

Note  $\text{Ext}_{\mathcal{O}_E}^1(N_{E/S}, T_E) \cong H^1(E, \mathcal{O}_E(2) \oplus \mathcal{O}_E(n)) = 0$ , and thus  $T_S|_E \cong \mathcal{O}_E(2) \oplus \mathcal{O}_E(-n)$  has  $h^0 = 3$ . This means, even though  $E$  is rigid in  $S$ , the inclusion  $i : R \rightarrow S$  has 3 dimensional family of deformations.

## 9 Deformation of morphism with target fixed

In this section, the fiber product diagram becomes more general:

$$\begin{array}{ccc} X & \longrightarrow & \mathcal{X} \\ \downarrow f & & \downarrow F \\ Y & \longrightarrow & Y \times S \\ \downarrow & & \downarrow \pi: \text{projection} \\ k & \longrightarrow & S \end{array}$$

again with  $\pi \circ F$  flat. This is a deformation of  $f$  with target  $Y$ . An isomorphism between such two deformations is commutative diagrams

$$\begin{array}{ccc} & X & \\ & \swarrow & \searrow \\ \mathcal{X} & \xrightarrow{\phi} & \mathcal{X}' \\ & \searrow & \swarrow \\ & S & \end{array}, \text{ and } \begin{array}{ccc} & \mathcal{X} & \\ & \swarrow & \searrow \\ \mathcal{X}' & \xrightarrow{\phi} & Y \times S \\ & \searrow & \swarrow \\ & Y & \end{array}.$$

The associated deformation functor is  $\text{Def}_{f/Y}$ . We say a deformation with target fixed is locally trivial, if the very deformation of  $X$

$$\begin{array}{ccc} X & \longrightarrow & \mathcal{X} \\ \downarrow & & \downarrow \\ k & \longrightarrow & S \end{array}$$

is locally trivial, ie. there exists an open cover  $\mathcal{U} = \{U_i\}_{i \in I}$  such that for all  $i$ ,  $\mathcal{X}|_{U_i}$  is a trivial deformation of  $U_i$ . The associated functor is denoted by  $\text{Def}_{f/Y}^{\ell}$ .

**Definition 9.1.** Let  $f : X \rightarrow Y$  be a morphism between algebraic schemes, with  $X$  projective, and let  $\mathcal{U} = \{U_i\}_{i \in I}$  be an open affine cover of  $X$ . Define

$$D_{X/Y} := \frac{\{(v, t) \in \mathcal{C}^0(\mathcal{U}, f^*T_Y) \times \mathcal{Z}^1(\mathcal{U}, T_X) \mid \delta v = df(t)\}}{(df(w), \delta w) \mid w \in \mathcal{C}^0(\mathcal{U}, T_X)} \text{ and}$$

$$D_{X/Y}^1 := \frac{\{(\zeta, s) \in \mathcal{C}^1(\mathcal{U}, f^*T_Y) \times \mathcal{Z}^2(\mathcal{U}, T_X) \mid \delta \zeta = df(s)\}}{(df(u), \delta u) \mid u \in \mathcal{C}^1(\mathcal{U}, T_X)},$$

where  $\delta$  is the coboundary map in Cech complex and  $d : T_X \rightarrow f^*T_Y$ .

**Theorem 9.2.** With the above settings,

- (1)  $\text{Def}_{f/Y}^{\ell}$  has a semiuniversal element.
- (2)  $\text{Def}_{f/Y}(k[\epsilon]) = D_{X/Y}$ ; an obstruction space is  $D_{X/Y}^1$ .

## 10 Reference

[1] Edoardo Sernesi, Deformations of Algebraic Schemes.