

GEOMETRY

(Honor Course, NTU 2016 Fall)

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Course Manuscript

CONTENTS

(based on Modern Geometry I by Dubrovin, Fomenko and Novikov)

1. Curves and surfaces in Euclidean space (not provided)
2. Complex analysis in surface theory
3. Tensors, Lie derivatives and differential forms
4. Covariant differentiations, Riemann curvature, and Gauss—Bonnet
5. 1D variational problems, Hamiltonian formalism
6. Examples of HD variations from geometry and classical fields

Complex analysis in Surface theory

$$\mathbb{R}^m = \mathbb{C}^n \quad \begin{cases} x^k + \sqrt{-1} y^k = z^k \\ x^k - \sqrt{-1} y^k = \bar{z}^k \end{cases} \quad dl^2 = \sum_{k=1}^n dz^k d\bar{z}^k$$

$$\frac{\partial}{\partial z^k} := \frac{1}{2} \left(\frac{\partial}{\partial x^k} - i \frac{\partial}{\partial y^k} \right) \quad \text{s. mat} \quad \frac{\partial}{\partial z}(\tau) = 1 \quad \frac{\partial}{\partial z}(\bar{z}) = 0$$

$$\frac{\partial}{\partial \bar{z}^k} := \frac{1}{2} \left(\frac{\partial}{\partial x^k} + i \frac{\partial}{\partial y^k} \right) \quad \frac{\partial}{\partial \bar{z}}(\tau) = 0 \quad \frac{\partial}{\partial \bar{z}}(\bar{z}) = 1$$

Then: A C^1 diff function $f(x,y) = u + iv$ is diff in \mathbb{C}^n sense

is holomorphic $\Leftrightarrow \frac{\partial}{\partial \bar{z}} f = 0$ i.e. $u_x = v_y, v_x = -u_y$ (C-R eqⁿ)

Hard Thus: u is in $\Omega \subset \mathbb{C} \ni (\mathbb{C}^n)$ analytic in Ω .

fact: A real analytic $p(x^1, y^1, \dots, x^n, y^n) = q(z^1, \bar{z}^1, \dots, z^n, \bar{z}^n)$

is indep of $\bar{z}^k \Leftrightarrow \frac{\partial}{\partial \bar{z}^k} p = 0$ with at the lowest degree term!

Defⁿ: f is (\mathbb{C}^n) analytic in $\Omega \subset \mathbb{C}^n$

if f is real differentiable and analytic in each z^k .

\Rightarrow This notion of \mathbb{C}^n coordinate change

Lemma: for analytic $F, (z_1, \dots, z^n) \xrightarrow{F} (w^1(z_1, \dots, z^n), \dots, w^n(z_1, \dots, z^n))$ to be analytic

$$J_{\mathbb{R}} := \det(DF) = |J_{\mathbb{C}}|^2 \quad \text{where } J_{\mathbb{C}} = \det \left(\frac{\partial w^i}{\partial z^j} \right)$$

pf: $\det \begin{pmatrix} \frac{\partial w}{\partial z} & \frac{\partial \bar{w}}{\partial z} \\ \frac{\partial w}{\partial \bar{z}} & \frac{\partial \bar{w}}{\partial \bar{z}} \end{pmatrix} = \det \begin{pmatrix} A & 0 \\ 0 & \bar{A} \end{pmatrix} = |J_{\mathbb{C}}|^2$ " $A = D_{\mathbb{C}} F$

related to DF up to $(x^k, y^k) \leftrightarrow (z^k, \bar{z}^k)$ *

Corollary: Inverse and implicit function theorem for complex analytic functions.

pf: We only need to show the "real inverse" is \mathbb{C}^n analytic but this is clear since $D_{\mathbb{C}} F^{-1} = (D_{\mathbb{C}} F)^{-1} = \begin{pmatrix} A^{-1} & 0 \\ 0 & \bar{A}^{-1} \end{pmatrix}$ *

Example: 2D surfaces as \mathbb{C}^n curves in \mathbb{C}^2 :

$$C = \{ (w, z) \in \mathbb{C}^2 \mid f(w, z) = 0 \} \quad f \text{ } \mathbb{C}^n \text{ analytic}$$

$p = (w_0, z_0) \in C$ is non-singular if $\nabla_{\mathbb{C}} f := \left(\frac{\partial f}{\partial w}, \frac{\partial f}{\partial z} \right) \neq 0$ at p

say $f_w \neq 0$, then $w = w(z)$, uniquely near p s.t.

$$f(w(z), z) = 0. \quad f_w \frac{dw}{dz} + f_z = 0 \quad ; \quad \frac{dw}{d\bar{z}} = 0.$$

Most important (basic) case: $f \in \mathbb{C}[w, z]$ polynomials.

1st found from induced from \mathbb{C}^2 , Euclidean / Hermitian metric

$$dL^2 = |dw|^2 + |dz|^2 = \left(1 + \left|\frac{dw}{dz}\right|^2\right) |dz|^2 = h(z, \bar{z}) dz d\bar{z} = \lambda^2(x, y) (dx^2 + dy^2)$$

2D -

Lemma: Conformal coord change \Leftrightarrow holomorphic or anti-holomorphic.

pf: $(x, y) \xrightarrow{F} (u, v)$ DF = $\begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix}$ is a 2x2 conformal matrix

Cauchy-Riemann $\Leftrightarrow = \rho \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \Leftrightarrow u_x = v_y, v_x = -u_y \Leftrightarrow \frac{\partial F}{\partial \bar{z}} = 0$

or $\begin{pmatrix} \cos\theta & \sin\theta \\ \sin\theta & -\cos\theta \end{pmatrix} \Leftrightarrow u_x = -v_y, v_x = u_y \Leftrightarrow \frac{\partial F}{\partial z} = 0$

Cor: Under conformal coord, $dL^2 = \lambda^2 (du^2 + dv^2)$, get $K = -\frac{1}{AB} \left(\left(\frac{B_u}{A}\right)_u + \left(\frac{A_v}{B}\right)_v \right) = \frac{-1}{2\lambda^2} \Delta \log \lambda^2$
i.e. $A=B=\lambda$ in Ex 8.4 #7.

and $\sqrt{g} = \sqrt{EG - F^2} = \lambda^2$.

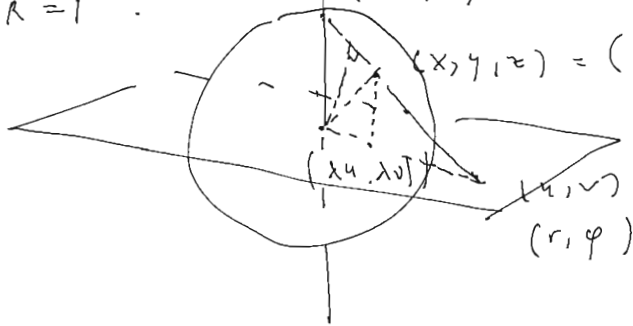
Now we are ready to analyze the

Non-Euclidean geometry on S^2 and L^2 more closely!

$S^2_{R=1}$:

$(0,0,1)$

λ : conformal factor



$(x, y, z) = (\lambda u, \lambda v, 1 - \lambda)$ solve $\Leftrightarrow \lambda = \frac{2}{4u^2 + 4v^2 + 1}$

$$dL^2 = d\sigma^2 + \rho^2 d\varphi^2 = 4\rho^4 \frac{e}{2} (dr^2 + r^2 d\sigma^2) = \frac{4}{(u^2 + v^2 + 1)^2} (du^2 + dv^2) = \frac{4|dz|^2}{(1+|z|^2)^2}$$

CA \Leftrightarrow Any analytic $w(z)$ on

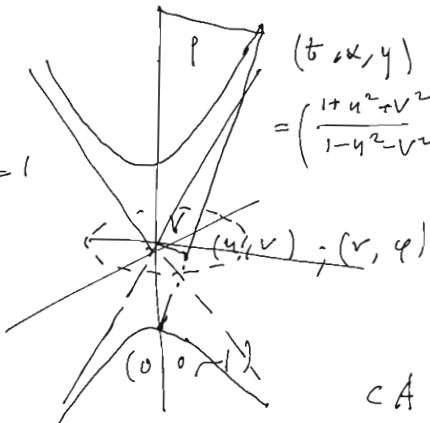
$S^2 \cong \mathbb{C}P^1 = \mathbb{C} \cup \{\infty\}$ is a Möbius transform $w = \frac{az+b}{cz+d}$ say $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = 1$

Easy to check: it preserves $dL^2 \Leftrightarrow \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SU(2)/\pm 1$

$L^2_{R=1}$:

$t^2 - (x^2 + y^2) = 1$

in $\mathbb{R}^{1,2}$



$(t, x, y) = \left(\frac{1+u^2+v^2}{1-u^2-v^2}, \frac{2u}{1-u^2-v^2}, \frac{2v}{1-u^2-v^2} \right)$ $dL^2 = dx^2 + \sinh^2 \chi d\varphi^2$ ($a + \chi \in \mathbb{R}$)

$K \equiv -1$ easily geodesic $\Leftrightarrow \chi = \omega t$
 $= \frac{4(du^2 + dv^2)}{(1-u^2-v^2)^2} = \frac{4|dz|^2}{(1-|z|^2)^2}$

in $\mathbb{D} = \{|z| < 1\}$ Poincaré model.

CA Schwarz lemma $\Leftrightarrow \text{Aut}(\mathbb{D}) = \left\{ e^{i\theta} \frac{z-a}{1-\bar{a}z} \right\}$

Easy to see this preserves dL^2 .

Q: geodesics in Poincaré model?

Möbius transf. $w = \frac{az+b}{cz+d} : \mathbb{P}^1 \rightarrow \mathbb{P}^1$ det by 3 pts
 $\alpha, \beta, \gamma \mapsto 0, 1, \infty$

Easy to see $\frac{4|dz|^2}{(1+|z|^2)^2} = \frac{4|dw|^2}{(1+|w|^2)^2} \Leftrightarrow \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SU(2)/\pm 1$

so the difficult part is: why $f: \mathbb{P}^1 \xrightarrow{\sim} \mathbb{P}^1 \neq f$ Möbius?

Thm (Liouville): f bounded hol on $\mathbb{C} \Rightarrow f = \text{const.}$

Pf: Cauchy $f'(a) = \frac{1}{2\pi i} \int_{C_R} \frac{f(z)}{(z-a)^2} dz \rightarrow 0$ as $R \rightarrow \infty$ *

Cor. Any meromorph on \mathbb{P}^1 is rational, degree 1 \neq Möbius.

Next we study $\text{Conf}^+(\mathbb{D})$: do this part is easier

Lemma: Möbius $f: \mathbb{D} \xrightarrow{\sim} \mathbb{D} \Leftrightarrow f = e^{i\theta} \frac{z-\alpha}{1-\bar{\alpha}z}$ $\alpha \in \mathbb{D}, \theta \in \mathbb{R}$

Pf: $|z-\alpha| < |1-\bar{\alpha}z| \Leftrightarrow |z|^2 + |\alpha|^2 < 1 + |\alpha|^2|z|^2$
 i.e. $(1-|\alpha|^2)(1-|z|^2) < 0$ *

Thm (Schwarz Lemma) (i) (ii)
 $f: \mathbb{D} \rightarrow \mathbb{D}, f(0)=0 \Rightarrow |f(z)| \leq |z|, |f'(0)| \leq 1, "=" \Leftrightarrow f = e^{i\theta} z.$

Pf: $\frac{f(z)}{z}: \mathbb{D} \rightarrow \mathbb{C}$ well defined at $z=0$ as $f'(0)$ $\left| \frac{f(z)}{z} \right|_{D_R} \leq \frac{1}{R} \forall R < 1$
by max principle

$R \rightarrow 1 \neq$ (i), for (ii) at $z_0 \in D_{R < 1}$

$\Rightarrow f(z) = az, |a|=1$ as expected *

Cor: $\text{Conf}^+(\mathbb{D}) = \left\{ e^{i\theta} \frac{z-\alpha}{1-\bar{\alpha}z} \right\} = \text{Isometry}(\mathbb{D}) = SU(1,1)/\pm 1$
 called oriented (directed, proper) isometries.

Klein model: $\mathbb{H} = \{ \text{Im } w > 0 \}, dl^2 = \frac{|dw|^2}{(\text{Im } w)^2}$
 \downarrow
 $\mathbb{D} \quad z = \frac{i-w}{i+w} \quad \text{Conf}^+(\mathbb{H}) = SL(2, \mathbb{R})/\pm 1$

Cor: $SU(1,1)/\pm 1 \cong SL(2, \mathbb{R})/\pm 1 \cong SO(1,2)^\circ$. (conn. component).

Thm: $dl^2 = E dp^2 + 2F dp dq + G dq^2 = f(u, v) (du^2 + dv^2)$
 assuming E, F, G are real analytic in p, q .

"pf:" We try to find $\lambda(p, q)$ st $(g := EG - F^2)$, $\exists u, v$ with

$$\lambda \left(\sqrt{E} dp + \frac{F + i\sqrt{g}}{\sqrt{E}} dq \right) = du + i dv$$

$$\text{ie. } \lambda \sqrt{E} = u_p + i v_p \quad (F + i\sqrt{g}) \cdot (u_p + i v_p)$$

$$\lambda \frac{F + i\sqrt{g}}{\sqrt{E}} = u_q + i v_q = E (u_q + i v_q)$$

$$\text{ie. } F u_p - \sqrt{g} v_p = E u_q \quad \& \quad \sqrt{g} u_p + F v_p = E v_q$$

so $u_p, u_q \leftrightarrow v_p, v_q$ determine each other

$$\text{eg. } v_p = \frac{1}{\sqrt{g}} (F u_p - E u_q)$$

$$v_q = \frac{\sqrt{g}}{E} u_p + \frac{F}{E} v_p = \frac{(EG - F^2) + F^2}{E\sqrt{g}} u_p - \frac{F}{\sqrt{g}} u_q = \frac{1}{\sqrt{g}} (G u_p - F u_q)$$

$$v_{pq} = v_{qp} \Rightarrow Lu = 0 \quad \text{where } L := \partial_q \left(\frac{F \partial_p - E \partial_q}{\sqrt{g}} \right) + \partial_p \left(\frac{F \partial_q - G \partial_p}{\sqrt{g}} \right)$$

is the Laplace-Beltrami operator \square

$$\text{Rmk: for general } dl^2, \Delta dl^2 := \sum_{i,j} \frac{1}{\sqrt{g}} \partial_i \left(\sqrt{g} g^{ij} \partial_j \right)$$

Liouville theory:

$$\text{for } dl^2 = e^\varphi |dz|^2, \quad K = -\frac{1}{2} \frac{1}{e^\varphi} \Delta \log e^\varphi \Rightarrow \Delta \varphi = -2K e^\varphi$$

Thm: A surface of constant K is locally isometrically to S_R^2, \mathbb{R}^2 , or L_R^2 , where $R = 1/\sqrt{|K|}$.

$$\text{pf: We compute } \frac{\partial}{\partial \bar{z}} \left(\varphi_{z\bar{z}} - \frac{1}{2} \varphi_z^2 \right) = \varphi_{z\bar{z}\bar{z}} - \varphi_z \varphi_{z\bar{z}} = -\frac{K}{2} \varphi_z e^\varphi + \frac{K}{2} \varphi_z e^\varphi = 0$$

$$\Rightarrow \psi(z) := \varphi_{z\bar{z}} - \frac{1}{2} \varphi_z^2 \text{ is analytic}$$

Lemma: Under $z = f(w)$ analytic change, get $\{f, z\}$

$$\tilde{\varphi} = \varphi + \log |f'|^2 \quad \& \quad \tilde{\psi} = \psi \cdot f'^2 + \left(\frac{f'''}{f'} - \frac{3}{2} \left(\frac{f''}{f'} \right)^2 \right)$$

Ex. Show that (i) $\{f, z\} = (f')^2 \{z, f\}$ and

$$(ii) \psi'' - I\psi = 0 \text{ sol } \psi_1, \psi_2 \Rightarrow \{\psi_1/\psi_2, z\} = \frac{1}{2} I.$$

Hence $\tilde{\psi} \equiv 0$ above is solvable by some f .

$$\text{Now } (e^{-\tilde{\psi}/2})_{ww} = (e^{-\tilde{\psi}/2} \frac{1}{2} \tilde{\psi}_w)_w = \frac{1}{2} (\tilde{\psi}_{ww} - \frac{1}{2} \tilde{\psi}_w^2) = \frac{1}{2} \tilde{\psi} \equiv 0$$

As a function in $w = u + iv$ this means that

$$(e^{-\tilde{\psi}/2})_{uu} = (e^{-\tilde{\psi}/2})_{vv} \text{ and } (e^{-\tilde{\psi}/2})_{uv} = 0$$

$$\text{ie. } e^{-\tilde{\psi}/2} = a(u^2 + v^2) + \beta u + \beta' v + c \quad a, \beta, \beta', c \in \mathbb{R}$$

$$= a w \bar{w} + b w + \bar{b} \bar{w} + c \quad b \in \mathbb{C}$$

$$\text{and } d\ell^2 = e^{\tilde{\psi}} |dw|^2 = \frac{|dw|^2}{(a|w|^2 + b w + \bar{b} \bar{w} + c)^2}$$

$$\Rightarrow K = -2 e^{-\tilde{\psi}} \frac{\partial^2}{\partial w \partial \bar{w}} \log \frac{1}{(\dots)^2} = 4 (\dots)^{-2} \cdot \partial_w \partial_{\bar{w}} \log(\dots) = 4(a c - |b|^2)$$

Now it's easy find Möbius transf to get the result \Rightarrow (Ex)

Transf. gp. as surfaces in \mathbb{R}^N (Classical Lie gps) or \mathbb{C}^N :

$$G_f := GL(n, \mathbb{R}) \hookrightarrow \mathbb{R}^{n^2} \text{ by } \det A \neq 0 \quad \left\{ \begin{array}{l} G \times G \longrightarrow G \quad (A, B) \mapsto AB \\ G \longrightarrow G \quad A \mapsto A^{-1} \end{array} \right.$$

$$|A|^2 = \sum |a_{ij}|^2$$

$$|A+B| \leq |A| + |B|$$

$$|A \cdot B| \leq |A| \cdot |B| : \sum_k \left| \sum_h a_{kh} b_{hj} \right|^2 \leq \sum_k \sum_h |a_{kh}|^2 \sum_h |b_{hj}|^2$$

$$(1-A)^{-1} = 1 + A + A^2 + A^3 + \dots \text{ if } |A| < 1 : \text{ in fact, abs.}$$

$\lim_{n \rightarrow \infty} B_n$ Cauchy in \mathbb{R}^{n^2} , converges

$$(1-A) \cdot B_n = 1 - A^{n+1} \rightarrow 1 \text{ hence } \lim B_n = (1-A)^{-1}.$$

Rank: I_n has nbd $I_n + X$ with $|X| < 1$ $X = (x_{ij})$

$$B_0 \text{ has nbd } B_0(I_n + X) = B_0 + B_0 X = B_0 + Y \Rightarrow |Y| < |B_0|$$

However for $|Y| < |B_0|$ it is NOT true that $|X| < 1$

From $X = B_0^{-1} Y$, we need $|Y| < |B_0^{-1}|^{-1}$ to get $|X| < 1$.

Prop: $GL(n, \mathbb{R}) \supset SL(n, \mathbb{R}) \supset SO(n)$ as non-singular surfaces with tangent plane at $e = I_n$: $\mathbb{R}^{n^2} \supset (\text{tr } X = 0) \supset (X^T + X = 0)$.

Prop: $GL(n, \mathbb{C}) \supset SL(n, \mathbb{C}) \supset SU(n)$ $\mathbb{C}^{n^2} \supset \text{tr } X = 0$
 $\supset U(n) \supset$

Exponential Map: $T_e G \xrightarrow{\exp} G$ $X \mapsto e^X := \sum_{n=0}^{\infty} \frac{X^n}{n!}$
 abs. conv.

Facts: $XY = YX \Rightarrow e^{X+Y} = e^X \cdot e^Y$
 $e^X \in G$, i.e. invertible, $(e^X)^{-1} = e^{-X}$.

Lemma: Behavior of exp on subgroups holds.

eg. $\det e^X = e^{\text{tr } X}$ for SL by Jordan form or upper Δ .
 for $O(n)$: $X^T + X = 0 \Rightarrow [X^T, X] = 0 \neq (e^X)^T e^X = e^{X^T + X} = I$

Lemma: $d \exp_0 = \text{Id}: T_e G \rightarrow T_e G \Rightarrow \exp$ 1-1, onto near e.

Pf: $d \exp_0 (X) = \left. \frac{d}{dt} e^{tX} \right|_{t=0} = X$ * \leftarrow 1 para. subgps.

Remark: Globally, exp might not be 1-1, nor onto, even for connected G ! (Ex. $G = SL(2, \mathbb{R})$)

$\mathbb{R}, \mathbb{C}, \mathbb{H} =$ Quaternions $\Rightarrow q = a + bi + cj + dk = z_1 + z_2 j$
 skew field $i^2 = j^2 = k^2 = -1$, $ij = k$

Lemma: $A: \mathbb{H} \rightarrow M(2, \mathbb{C})$ is a ring mono.
 $q \mapsto A(q) := \begin{pmatrix} z_1 & z_2 \\ -\bar{z}_2 & \bar{z}_1 \end{pmatrix}$

Pf: For basis $A(i) = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$, $A(j) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$, $A(k) = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}$

it's clear that $A(q_1 q_2) = A(q_1) A(q_2)$, hence done *

Fact: $\bar{q} := a - bi - cj - dk \Rightarrow \overline{z_1 z_2} = \bar{z}_2 \bar{z}_1$, $q \bar{q} = |q|^2$ norm
 $|q|^2 = 1 \Leftrightarrow |z_1|^2 + |z_2|^2 = 1$ i.e. $\mathbb{H}_1 \cong SU(2) (\cong S^3)$

Symplectic group $Sp(n)$ on \mathbb{H}^n , row vectors, acting on Right.

$A + Bj = \Lambda \in GL(n, \mathbb{H})$ which preserves $\langle \xi_1, \xi_2 \rangle_{\mathbb{H}^n} := \sum_{k=1}^n \xi_1^k \bar{\xi}_2^k$.

\downarrow $\downarrow c$
 $\begin{pmatrix} A & B \\ -\bar{B} & \bar{A} \end{pmatrix} = c(\Lambda) \in GL(2n, \mathbb{C})$
 $= \sum (x_1^k + y_1^k j) (\bar{x}_2^k + \bar{j} \bar{y}_2^k)$
 $= \sum (x_1^k \bar{x}_2^k + y_1^k \bar{y}_2^k) + \sum (y_1^k x_2^k - x_1^k y_2^k) j$
 i.e. $U(2n)$ and preserve symplectic form / \mathbb{C} .

Liouville's thm on conformal maps

$\varphi: (U, x, g_{\alpha\beta}(x)) \rightarrow (V, y, g'_{\alpha\beta}(y))$ is conformal

if $\varphi^* \sum g'_{\alpha\beta}(y) dy^\alpha dy^\beta = \rho^2(x) \sum \delta_{rs}(x) dx^r dx^s \leftarrow \text{Linear Alg fact: } |AV| = \rho |V|.$

$$\sum \left(\sum_{\alpha,\beta} g'_{\alpha\beta}(\varphi(x)) \frac{\partial \varphi^\alpha}{\partial x^r} \frac{\partial \varphi^\beta}{\partial x^s} \right) dx^r dx^s \quad (\text{or anti-})$$

dim = 1: no condition, dim = 2 $\Leftrightarrow \varphi$ analytic, \exists a lot!

Thm (Liouville)

for $\varphi: U \rightarrow V$ in $\mathbb{R}^n \ni 3$, $\varphi \in \langle \text{isometries, dilations, inversions} \rangle$

pf: Consider behavior of constant v.f.'s under φ .

Let $A =$ matrix function for $d\varphi = \left(\frac{\partial y^\alpha}{\partial x^r} \right) = (\varphi_1, \dots, \varphi_n)$

choose $e_1, \dots, e_n \perp \Rightarrow \varphi_1, \dots, \varphi_n \perp$. know $\langle A\eta, A\xi \rangle = \rho^2 \langle \eta, \xi \rangle$.

$$0 = \partial_k \langle \varphi_i, \varphi_j \rangle = \langle \varphi_{i,k}, \varphi_j \rangle + \langle \varphi_i, \varphi_{j,k} \rangle$$

$$+ 0 = \partial_j \langle \varphi_i, \varphi_k \rangle = \langle \varphi_{i,j}, \varphi_k \rangle + \langle \varphi_i, \varphi_{k,j} \rangle \Rightarrow \langle \varphi_{j,k}, \varphi_i \rangle = 0 \quad \forall i \neq j, k$$

$$- 0 = \partial_i \langle \varphi_j, \varphi_k \rangle = \langle \varphi_{j,i}, \varphi_k \rangle + \langle \varphi_j, \varphi_{i,k} \rangle \quad \text{i.e. } \varphi_{j,k} = \nu_j \varphi_i + \nu_k \varphi_i$$

$$\nu_j = \frac{\langle \varphi_{j,k}, \varphi_i \rangle}{\langle \varphi_j, \varphi_i \rangle} = \frac{1/2 \partial_k \langle \varphi_j, \varphi_i \rangle}{\langle \varphi_j, \varphi_i \rangle} = \frac{1}{2} \frac{\partial \rho}{\rho^2} \rho_k = (\log \rho)_k =: \mu_k \quad \text{j,k switches.}$$

($\mu := \log \rho$)

$$\varphi_{j,k} = \mu_k \varphi_j + \mu_j \varphi_k \quad \varphi_{j,ki} = \mu_{ki} \varphi_j + \mu_k \varphi_{ji} + \mu_{ji} \varphi_k + \mu_j \varphi_{ki}$$

$\Rightarrow \mu_{kj} \varphi_i + \mu_i \varphi_{jk}$ is sym in i, j, k

$$= \mu_{kj} \varphi_i + \mu_i \mu_j \varphi_k + \mu_i \mu_k \varphi_j = \mu_{ki} \varphi_j + \mu_j \mu_i \varphi_k + \mu_j \mu_k \varphi_i$$

$$\cdot \varphi_i \Rightarrow \mu_{kj} \rho^2 = \mu_j \mu_k \rho^2 \quad \text{i.e. } \mu_{kj} - \mu_k \mu_j = 0. \quad \text{From } \mu = \log \rho = -\log \rho^{-1}$$

$$\Rightarrow 0 = - \frac{(\rho^{-1})_k \cdot \rho^{-1} - (\rho^{-1})_k (\rho^{-1})_j}{(\rho^{-1})^2} - \frac{(\rho^{-1})_k \cdot (\rho^{-1})_j}{\rho^{-1}} = - \frac{(\rho^{-1})_k}{\rho^{-1}}$$

i.e. $D^2 \rho^{-1}(\nu_k, \nu_j) = 0$ for any 2 orthogonal vectors (preserving \perp)

As in the original linear algebra fact $\Rightarrow \rho_{\alpha\beta}^{-1}(x) = \sigma(x) g_{\alpha\beta}(x)$.

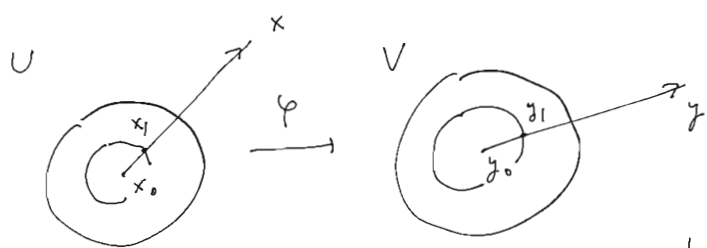
$$\rho_{\alpha\beta}^{-1} = \sigma_\beta g_{\alpha\alpha} = \sigma_\alpha g_{\beta\beta} \Rightarrow \sigma_\beta = 0 \Rightarrow \sigma = \text{const} \quad \begin{array}{l} \text{constant in } x \\ (\text{Euclidean}) \end{array}$$

$$\text{Hence } \rho^{-1} = a_1 |x - x_0|^2 + b_1$$

$$\text{Conversely, } \varphi^{-1} \text{ is conformal } \Rightarrow \rho = a_2 |y - y_0|^2 + b_2$$

$$\text{i.e. } (a_1 |x - x_0|^2 + b_1) (a_2 |y - y_0|^2 + b_2) = 1 \quad \Rightarrow \text{spheres at } x_0 \leftrightarrow \text{spheres at } y_0$$

algebraic dependence -7-



conformal \Rightarrow line to line

$$\varphi(\overrightarrow{x_1 x}) = \overrightarrow{y_1 y}$$

let τ = arc length in $\overrightarrow{x_1 x}$
 $\tau \in [t_1, t]$

$$|y - y_1| = \int_{t_1}^t \rho \, d\ell_U = \int_{t_1}^t (a_1 \tau^2 + b_1)^{-1} d\tau = \text{algebraic in } |x - x_0| = t - t_1$$

$$\Leftrightarrow a_1 = 0 \text{ or } b_1 = 0.$$

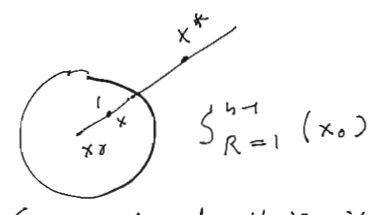
$a_1 = 0 \Rightarrow$ dilation

$$b_1 = 0 \Rightarrow \rho = a_1^{-1} \frac{1}{|x - x_0|^2}$$

this is the conformal factor arising from Mobius inversion:

$$M: x \mapsto x^* := \frac{x - x_0}{|x - x_0|^2}$$

By composing M first, we reduce to the dilation case. Done \square



Ex. check this is lozf. but with $J < 0$!

Remark: for $n=2$, $\mathbb{R}^2 \cong \mathbb{C}$, $z^* = \frac{\bar{z}}{|z|^2} = \frac{1}{\bar{z}}$.

Vector (= tangent vector to a curve)

$$v = \sum_i \frac{dx^i}{dt} e_i = \sum_{j,i} \frac{\partial x^i}{\partial y^j} \frac{dy^j}{dt} e_i = \sum_j \frac{dy^j}{dt} \left(\sum_i \frac{\partial x^i}{\partial y^j} e_i \right) = \sum_j \frac{dy^j}{dt} \tilde{e}_j$$

$\underbrace{\sum_i \frac{\partial x^i}{\partial y^j} e_i}_{\tilde{e}_j}$

co-vector (= gradient of a function, or total differential)

$$df = \sum_i \frac{\partial f}{\partial x^i} e^i = \sum_{j,i} \frac{\partial f}{\partial y^j} \frac{\partial y^j}{\partial x^i} e^i = \sum_j \frac{\partial f}{\partial y^j} \left(\sum_i \frac{\partial y^j}{\partial x^i} e^i \right) = \sum_j \frac{\partial f}{\partial y^j} \tilde{e}^j$$

$\underbrace{\sum_i \frac{\partial y^j}{\partial x^i} e^i}_{\tilde{e}^j}$

It will be very useful to set notations $e_i = \frac{\partial}{\partial x^i}$; $e^i = dx^i$

Duality : $df(v) = \sum \frac{\partial f}{\partial x^i} v^i$ $v = \sum v^i \frac{\partial}{\partial x^i}$ $df = \sum \frac{\partial f}{\partial x^i} dx^i$

can be interpreted as directional derivative of f in $v = v(f)$

Defⁿ : An (p, q) tensor on V is an element $T \in \otimes^p V \otimes \otimes^q V^*$; $e^j(e_i) = \delta^j_i$
 i.e. $T = \sum T_{i_1 \dots i_p}^{j_1 \dots j_q} e_{i_1} \otimes \dots \otimes e_{i_p} \otimes e^{j_1} \otimes \dots \otimes e^{j_q}$

For tensor fields T , it is a collection of functions $(T_{i_1 \dots i_p}^{j_1 \dots j_q}(x))$ in each cov. x which transform in the correct way

$$T_{i_1 \dots i_p}^{j_1 \dots j_q}(x) = \sum_{k_1 \dots k_p} \tilde{T}_{k_1 \dots k_p}^{l_1 \dots l_q}(y) \frac{\partial x^{i_1}}{\partial y^{k_1}} \dots \frac{\partial x^{i_p}}{\partial y^{k_p}} \frac{\partial y^{l_1}}{\partial x^{j_1}} \dots \frac{\partial y^{l_q}}{\partial x^{j_q}}$$

write $T = \sum_{\substack{p=1, \dots, q \\ q=1, \dots, p}} T^I_J(x) e_I \otimes e^J$

$\frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_p}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_q}$

contra-variant part \uparrow co-variant part

Examples :

(0,2) tensor field : $\sum g_{ij}(x) dx^i \otimes dx^j = \sum g_{ij} dx^i dx^j$ (notation when $g_{ij} = g_{ji}$)

(2,0) tensor field : let $(g^{ij}) = (g_{ij})^{-1}$ and define inner product of co-vectors as

$$\langle \xi, \eta \rangle := \langle \xi_i dx^i, \eta_j dx^j \rangle = \sum \xi_i \eta_j \langle dx^i, dx^j \rangle = \sum \xi_i \eta_j g^{ij}(x)$$

then $g^{ij} = \langle dx^i, dx^j \rangle = \langle \frac{\partial x^i}{\partial y^k} dy^k, \frac{\partial x^j}{\partial y^l} dy^l \rangle = \tilde{g}^{kl}(y) \frac{\partial x^i}{\partial y^k} \cdot \frac{\partial x^j}{\partial y^l}$ must transform covariantly -

Ex. This is how we identify $V \cong V^*$ under given \langle, \rangle . and a check \uparrow but why?

(1,1) tensor :

this is just a "field of" linear maps $A = \sum_{i,j} A^i_j e_i \otimes e^j$

Algebra on tensors :

(i) permutations $\sigma \in S_q \Rightarrow \sigma T := \left\{ \tilde{T}_{i_1 \dots i_p}^{j_1 \dots j_q} := T_{i_{\sigma(1)} \dots i_{\sigma(p)}}^{j_1 \dots j_q} \right\}$

(ii) contraction (trace) $\otimes^{p,q} V \rightarrow \otimes^{p-1, q-1} V$ sum over $i_k = j_l = i$

(iii) tensor product $\otimes^{p_1, q_1} V \otimes \otimes^{p_2, q_2} V \cong \otimes^{p_1+p_2, q_1+q_2} V$ order is important.

eg. $A^k_l, \xi^i \mapsto T^k_l \xi^i := A^k_l \xi^i$ $\cdot 1 \mapsto \sum_i A^k_i \xi^i =: \eta^k$ trivial example!

Tensors of type $(0, k)$: forms

$$T = \sum \tau_{i_1 \dots i_k} e^{i_1} \otimes \dots \otimes e^{i_k} = \sum T_I dx^{\otimes I} \quad (\text{ordered})$$

Most important special cases :

$$\text{Sym}^k V^* \subset \otimes^{0,k} V = \otimes^k V^* \ni T \text{ st. } \sigma(T) = T \quad \forall \sigma \in S_k$$

$$\Lambda^k V^* \subset \otimes^k V^* \ni T \text{ st. } \sigma(T) = \text{sgn}(\sigma) T$$

fact : for $k=2$, $\otimes^2 V^* \cong \text{Sym}^2 V^* \oplus \Lambda^2 V^* \quad T = T^{\text{sym}} + T^{\text{alt}} :$

$$\sum_{i,j} T_{ij} dx^i \otimes dx^j = \sum_{i,j} \frac{1}{2} (T_{ij} + T_{ji}) dx^i \otimes dx^j + \sum_{i,j} \frac{1}{2} (T_{ij} - T_{ji}) dx^i \otimes dx^j$$

$\begin{matrix} \text{Sym} & & \text{Alt} \\ \downarrow & & \downarrow \\ \sum_{i,j} T_{ij}^{\text{sym}} dx^i dx^j & & \sum_{i < j} T_{ij}^{\text{alt}} dx^i \wedge dx^j \end{matrix}$

st. $dx^i dx^j = dx^j dx^i$

for $\Lambda^2 V^*$: better basis $dx^i \wedge dx^j := dx^i \otimes dx^j - dx^j \otimes dx^i$

General $k \in \mathbb{N}$: $\text{Sym}^k V^* \cong$ polynomial of degree k in $v = \sum_{i=1}^n x^i e_i \in V$

\ni Set $P_T(x^1, \dots, x^n) := T(v, \dots, v)$. Q : converse ?

Ex. Derive the polarization formula for $P \mapsto T_P$

for $\Lambda^k V^*$: $dx^{i_1} \wedge \dots \wedge dx^{i_k} := \sum_{\sigma \in S_k} \text{sgn}(\sigma) e^{\sigma(i_1)} \otimes \dots \otimes e^{\sigma(i_k)}$

may choose $i_1 < \dots < i_k$ since $dx^{\tau(i_1)} \wedge \dots \wedge dx^{\tau(i_k)} = (-1)^{|\tau|} dx^{i_1} \wedge \dots \wedge dx^{i_k}$

Rank : notation $\text{sgn}(\sigma) = (-1)^{|\sigma|} = \epsilon_{\sigma(1) \dots \sigma(n)}$, $\epsilon_{i_1 \dots i_n} := 0$ if not in S_n

Defⁿ : exterior product $T = \sum T_I dx^I \in \Lambda^p$, $S = \sum S_J dx^J \in \Lambda^q$,

$$T \wedge S := \sum T_I S_J dx^I \wedge dx^J = \sum_{k_1 < \dots < k_{p+q}} R_{k_1 \dots k_{p+q}} dx^{k_1} \wedge \dots \wedge dx^{k_{p+q}}$$

$$\text{where } R_{k_1 \dots k_{p+q}} = \sum_{\sigma \in S_{p+q}} \frac{(-1)^{|\sigma|}}{p! q!} T_{\sigma(k_1 \dots k_p)} S_{\sigma(k_{p+1} \dots k_{p+q})}$$

Fact : $T \wedge S = (-1)^{pq} S \wedge T$. $(\Lambda(V^*), \wedge)$ is called the exterior algebra.

The Art of Raising / Lowering indices

Given non-deg $(0,2)$ tensor g_{ij} (Sym \ni Riemannian or pseudo-Riem metric)

$$b : \otimes^{p,q} V \rightarrow \otimes^{p-1, q+1} V \quad \text{via } \underline{g_{ij}}^k T_{j_1 \dots j_q}^{i_1 \dots i_p} =: T_{i_1 \dots i_p}^{j_1 \dots j_q}$$

Then

$$\# : \otimes^{p,q} V \rightarrow \otimes^{p+1, q-1} V \quad \text{via } \underline{g_{ij}}^k T_{k j_2 \dots j_q}^{i_1 \dots i_p} =: T_{j_2 \dots j_q}^{i_1 \dots i_p}$$

$b, \#$ are inverse since $g^{ik} g_{kj} = \delta^i_j$

Lemma : $b : V \rightarrow V^*$ is an isometry .

pf : Let $v = \sum v^i e_i$, $w = \sum w^j e_j$, then $v_b = \sum \underline{g_{ik}} v^k e_i$ etc.

$$\ni \langle v_b, w_b \rangle = g^{ij} v_i w_j = g^{ij} g_{ik} v^k g_{jl} w^l = \delta^j_k g_{je} v^k w^l = \langle v, w \rangle$$

Example: $A = (a_{ij}^k)$ vs. $a_{ij} = g_{ik} a_{jk}^k$.

• A is self-adjoint $\Leftrightarrow a_{ij}$ is sym. since $\langle Av, w \rangle = g_{ik} a_{jk}^i v^j w^k = a_{kj} v^j w^k$

• eigenvalues: $(a_{ij}^k - \lambda g_{ij}^k) v^j = 0 \Leftrightarrow (a_{ij} - \lambda g_{ij}) v^j = 0$

For $(b_{ij}^k) =$ matrix for $-dN$ then b_{ij}^k is the 2nd fund. form.

In particular, $K = \det(b_{ij}^k) = \frac{\det(b_{ij}^k)}{\det(g_{ij}^k)}$

$$H = \text{tr}(b_{ij}^k) = b_{ij}^i = g^{ij} b_{ij}^k$$

holds for any hypersurfaces in \mathbb{R}^n .

Volume form and Hodge * operator on Riem, pseudo-Riem "spaces"

Thm: $d\sigma = \sqrt{|g|} dx^1 \wedge \dots \wedge dx^n$ $g := \det(g_{ij})$ is a top form ONLY among cov. change with $J > 0$.

Pf: $g_{ij} = \tilde{g}_{ke} \frac{\partial y^k}{\partial x^i} \frac{\partial y^e}{\partial x^j} \Rightarrow g = \tilde{g} J^2 \Rightarrow \sqrt{|g|} = \sqrt{|\tilde{g}|} |J|$

but $dx^1 \wedge \dots \wedge dx^n = \left(\sum \sigma_i \tau_i \right) \left(\prod \frac{\partial x^i}{\partial y^{\sigma(i)}} \dots \frac{\partial x^i}{\partial y^{\tau(n)}} \right) dy^1 \wedge \dots \wedge dy^n = J dy^1 \wedge \dots \wedge dy^n$

Def: Hodge * (orthogonal comp): $\Lambda^k \rightarrow \Lambda^{n-k}$ linear op st

$$(*T)_{i_1, \dots, i_{n-k}} := \frac{1}{k!} \sqrt{|g|} \varepsilon_{i_1, \dots, i_n} T^{i_1, \dots, i_k} \quad " g^{i_1 j_1} \dots g^{i_k j_k} T_{j_1, \dots, j_k}$$

The idea is:

for (V, \langle, \rangle) an inner product space with ONB e_1, \dots, e_n

V^* has ONB e^1, \dots, e^n and $\Lambda^k(V^*)$ has ONB $e^{i_1} \wedge \dots \wedge e^{i_k}$ $i_1 < \dots < i_k$

Then $*$: $\Lambda^k \rightarrow \Lambda^{n-k}$ simply sends $e^1 \wedge \dots \wedge e^k \mapsto e^{k+1} \wedge \dots \wedge e^n$ and

extends by linearity.

Proposition: (Exercise) Let $T, S \in \Lambda^k$

$$(1) *(*T) = (-1)^{k(n-k)} \text{sgn}(g) T$$

$$(2) T \wedge *S = \langle T, S \rangle d\sigma \quad \text{where } \langle, \rangle \text{ is the induced inner}$$

product on Λ^k . Hence $*$: $\Lambda^k \rightarrow \Lambda^{n-k}$ is an isometry of v.s.

Will develop differential/integral calculus of forms in the whole course. Nevertheless, as a side remark; it is also useful to study:

Integrals wrt Fermion (i.e. anti-commuting) variables on \mathbb{R}^n

Differential Calculus of tensors (Lie aspect)

Problem: Given $\xi = \xi^i \frac{\partial}{\partial x^i}$, $\frac{\partial}{\partial x^j} \xi^i =: \xi^i_j$. Does not form a (1,1) tensor
 since in cov. transf get 2nd derivatives! WHAT HAPPENS?!

Pull back (restriction) of forms under a map

$$f: (V, y^1, \dots, y^m) \rightarrow (U, x^1, \dots, x^n), \quad (0, k) \text{ tensor field on } U \xrightarrow{f^*} (0, k) \text{ on } V$$

$$f^* T := f^* (T_{i_1 \dots i_k}(x) dx^{i_1} \otimes \dots \otimes dx^{i_k}) \\ = T_{i_1 \dots i_k}(f(y)) \frac{\partial x^{i_1}}{\partial y^{j_1}} \dots \frac{\partial x^{i_k}}{\partial y^{j_k}} dy^{j_1} \otimes \dots \otimes dy^{j_k}$$

Push forward of tangent vectors, i.e. tangent map f_{*p} : in text book.

$$f_{*p}: T_p V \rightarrow T_{f(p)} U : T^i \mapsto T^i \frac{\partial x^i}{\partial y^i} \quad \text{it prefers notation: } y^j = "x^i"$$

However, vector field \mapsto vf only if

f is a diffeomorphism at p , i.e. f^{-1} exists locally and C^∞ at p .

In that case, we may pull back vf's, in fact any tensors!

Fundamental Theorem of ODE: Smooth dependence

Given a C^∞ v.f. ξ on $U \subset \mathbb{R}^n$, consider integral curve $x(t)$

$$\begin{cases} x'(t) = \xi(x(t)) \\ x(0) = x_0 \end{cases} \text{ defines } F_t(x_0) = x(t, x_0) \text{ is } C^\infty \text{ in } (t, x_0)$$

Defⁿ (Flow): At any x_0 , $\exists (-\epsilon, \epsilon) \ni t$ st F_t is a local diffeomorphism

Moreover, $\{F_t\}$ form a local 1-param. gp. of diffeos

$$F_{t+s} = F_t \circ F_s, \quad F_{-t} = F_t^{-1} \quad (\text{easy part, uniqueness})$$

Differentiability $\Rightarrow x(t, x_0) = x_0 + t x'(0) + o(t) = x_0 + T \xi(x_0) + o(t)$

Proposition (Jacobian): $\frac{\partial x^i(t)}{\partial x_0^j} = \delta^i_j + t \frac{\partial \xi^i}{\partial x_0^j} + o(t)$. Take inverse get

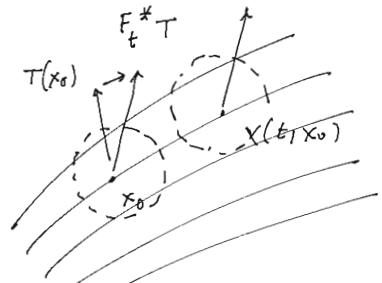
$$\frac{\partial x_0^i}{\partial x^j} = \delta^i_j - t \frac{\partial \xi^i}{\partial x_0^j} + o(t)$$

Lie Derivative on tensors along v.f. ξ :

$T \in \otimes^p \xi \Rightarrow F_t^* T \in \otimes^p \xi$ is well-defined

via "pull back" to coord system x_0 :

$$(F_t^* T)_{i_1 \dots i_p}^{j_1 \dots j_p} = T_{\alpha_1 \dots \alpha_p}^{k_1 \dots k_p} \frac{\partial x^{\alpha_1}}{\partial x_0^{i_1}} \dots \frac{\partial x^{\alpha_p}}{\partial x_0^{i_p}} \cdot \frac{\partial x_0^{k_1}}{\partial x^{j_1}} \dots \frac{\partial x_0^{k_p}}{\partial x^{j_p}}$$



Then $L_\xi T := \frac{d}{dt} (F_t^* T) \Big|_{t=0}$ (at the space $V = T_{x_0} \mathbb{R}^n$)

it can be computed component-wise: $(L_\xi T)_J^I = \frac{d}{dt} (F_t^* T)_J^I \Big|_{t=0}$

Explicit formulae: up to $o(t)$,

$$(F_t^* T)_{j_1 \dots j_p}^{i_1 \dots i_p} = T_{l_1 \dots l_p}^{k_1 \dots k_p}(x) \left(\delta_{i_1}^{l_1} + t \frac{\partial \xi^{l_1}}{\partial x_0^{j_1}} \right) \dots \left(\delta_{i_p}^{l_p} + t \frac{\partial \xi^{l_p}}{\partial x_0^{j_p}} \right) \left(\delta_{k_1}^{j_1} - t \frac{\partial \xi^{j_1}}{\partial x_0^{l_1}} \right) \dots \left(\delta_{k_p}^{j_p} - t \frac{\partial \xi^{j_p}}{\partial x_0^{l_p}} \right)$$

$$= T_{j_1 \dots j_p}^{i_1 \dots i_p}(x) + t \left(T_{l_1 \dots l_p}^{i_1 \dots i_p} \frac{\partial \xi^{l_1}}{\partial x_0^{j_1}} + \dots + T_{j_1 \dots j_{p-1} l}^{i_1 \dots i_p} \frac{\partial \xi^l}{\partial x_0^{j_p}} - T_{j_1 \dots j_p}^{k_1 \dots k_2 i_1} \frac{\partial \xi^{k_1}}{\partial x_0^{l_1}} - \dots - T_{j_1 \dots j_p}^{i_1 \dots k} \frac{\partial \xi^{i_1}}{\partial x_0^{l_1}} \right)$$

Thm: $(L_\xi T)_J^I = \frac{\partial T_J^I}{\partial x^s} \xi^s + T_{l \dots}^I \frac{\partial \xi^l}{\partial x^{j_1}} + \dots + T_{\dots l}^I \frac{\partial \xi^l}{\partial x^{j_p}} - T_J^{k \dots} \frac{\partial \xi^{i_1}}{\partial x^k} \dots - T_J^{\dots k} \frac{\partial \xi^{i_p}}{\partial x^k}$
 in low dimension $x = x_0$.

Example: (a) $L_\xi f = \xi^i \frac{\partial f}{\partial x^i} = \xi f \equiv \partial_\xi f$ no correction needed.

(b) On vector field η , " $L_\xi \eta^i$ " = $(L_\xi \eta)^i = \xi^j \frac{\partial \eta^i}{\partial x^j} - \eta^j \frac{\partial \xi^i}{\partial x^j}$. ($= -L_\eta \xi$!)

Thm: $L_\xi \eta = [\xi, \eta] := \xi \eta - \eta \xi$ as bracket of diff ops.

$$\text{pf: } [\xi^i \partial_i, \eta^j \partial_j] f = \xi^i \partial_i (\eta^j \partial_j f) - \eta^j \partial_j (\xi^i \partial_i f)$$

$$= \xi^i (\partial_i \eta^j) \partial_j f + \xi^i \eta^j \partial_i \partial_j f - \eta^j (\partial_j \xi^i) \partial_i f - \eta^j \xi^i \partial_j \partial_i f$$

$$(\partial_i \eta^j) \leftrightarrow (\partial_j \eta^i) = \left(\xi^j \frac{\partial \eta^i}{\partial x^j} - \eta^j \frac{\partial \xi^i}{\partial x^j} \right) \frac{\partial}{\partial x^i} f = (L_\xi \eta) f \quad *$$

Constructing coord system with given "directions"

Cor: Given ξ_1, \dots, ξ_m vfs in \mathbb{R}^n . If \exists coord system y^1, \dots, y^m st ξ_j is tangent to coord axis y^j , $j=1, \dots, m$, then $[\xi_j, \xi_k] = \alpha_{jk} \xi_j + \beta_{jk} \xi_k$.

pf: $\xi_j = f_j \partial_j \Rightarrow [\xi_j, \xi_k] = f_j (\partial_j f_k) \partial_k - f_k (\partial_k f_j) \partial_j$ *

Rmk: The converse holds (Frobenius thm). A simplified version $[X_i, X_j] = 0$ i, j, \dots, n is given in Exercise.

General properties of L_ξ : Leibniz' rule on \otimes, \wedge etc (Exercise)

(c) On one forms $T = T_j dx^j$, $(L_\xi T)_j = \xi^l \partial_l T_j + T_l \frac{\partial \xi^l}{\partial x^j}$.

In particular, for $T = df$, get $L_\xi df = d(L_\xi f)$ comm. with d

Rmk: After we introduce exterior derivative d , will see this in general.

(d) For (0,2) tensor g_{ij} . Say the metric.

$$"L_\xi g_{ij}" = \xi^s \partial_s g_{ij} + g_{kj} \partial_i \xi^k + g_{ik} \partial_j \xi^k$$

measures the change of g_{ij} in the small deformation F_t along ξ .

ξ is a Killing vector field if $L_\xi g = 0$

For Euclidean case, $g_{ij} = \delta_{ij}$, $L_\xi g_{ij} = \partial_i \xi^j + \partial_j \xi^i$

Q: What are all the solutions?

Examples of (0,2) tensor in $\mathbb{R}^{1,3}$

① $F = F_{ij} dx^i \wedge dx^j =: E_2 dx^0 \wedge dx^2 + H^1 dx^2 \wedge dx^3 + H^2 dx^2 \wedge dx^1 + H^3 dx^1 \wedge dx^2$
 skew-sym case (\mathbb{E}, \mathbb{H}) = (E_2, H^P) is the "classical notation" with Euclidean product

Defⁿ: The invariants of F are coefficients of $P(\lambda) := \det(F_{ik} - \lambda g_{ik}) = -\lambda^4 + (|\mathbb{E}|^2 - |\mathbb{H}|^2)\lambda^2 + \langle \mathbb{E}, \mathbb{H} \rangle^2$

Fact: They are inv. under Lorentz transf. (i.e. isometry of $\mathbb{R}^{1,3}$)

Lemma: $*F = -(E_1 dx^2 \wedge dx^3 + E_2 dx^3 \wedge dx^1 + E_3 dx^1 \wedge dx^2) + \sum_{\alpha=1}^3 H^\alpha dx^0 \wedge dx^\alpha$

Pf: Using $\omega \wedge * \omega = |\omega|^2 d\sigma$ and $dx^i \wedge dx^j$ form ONB of $\Lambda^2(\mathbb{R}^{1,3})$ or by direct computations:

$$(*F)_{ik} = \frac{1}{2} \epsilon_{ikem} F^{em} = \frac{1}{2} \epsilon_{ikem} g^{ip} g^{mq} F_{pq} \quad \text{since } \epsilon_{emik} = \epsilon_{ikem}$$

$$\Rightarrow (*F)_{01} = \frac{1}{2} \epsilon_{0123} g^{22} g^{33} F_{23} + \frac{1}{2} \epsilon_{0132} g^{33} g^{22} F_{32} = \frac{1}{2} H_1 - \frac{1}{2} (-H_1) = H^1$$

Lemma: $*^2 = -1$ on Λ^2 , hence a \mathbb{C} -v.s. str. is defined via

$$(a + b\sqrt{-1})\omega := a\omega + b*\omega$$

Then F is identified with $F = \mathbb{H} + \sqrt{-1}\mathbb{E}$ since $*F = -\mathbb{E} + \sqrt{-1}\mathbb{H}$

Let $z^\alpha := H^\alpha + \sqrt{-1}E_\alpha$, $\alpha=1,2,3$.

$$\langle F, F \rangle := -*(F \wedge *F) + \sqrt{-1} F \wedge F = -\frac{1}{2} (F_{ik} F^{ki} + \sqrt{-1} \epsilon^{ijkl} F_{ij} F_{kl}) = (|\mathbb{H}|^2 - |\mathbb{E}|^2) + 2\sqrt{-1} \langle \mathbb{E}, \mathbb{H} \rangle = (z^1)^2 + (z^2)^2 + (z^3)^2$$

This leads to $SO(1,3) \hookrightarrow O(3, \mathbb{C})$ and \exists canonical form of skew-sym (0,2) tensor F , cf. Thm 21.1.5, in $\mathbb{R}^{1,3}$. (Ex. Read it)

② Sym case. $T = T_{ik} dx^i dx^k$. Fact: $(T_{ik} - \lambda g_{ik}) \xi^k = 0$

Q: canonical form of T in $\mathbb{R}^{1,3}$?

Set $P(\lambda) = \det(T_{ik} - \lambda g_{ik})$
 eigen values $\lambda_0, \lambda_1, \lambda_2, \lambda_3$
 vectors ξ_i are still orthogonal.

Thm ($\mathbb{R}^{1,1}$ case): (Thm 21.2.2)

(i) $\lambda_0 \neq \lambda_1$ real $\Rightarrow T \sim \begin{pmatrix} \lambda_0 & \\ & -\lambda_1 \end{pmatrix}$

(ii) $\lambda_0, \lambda_1 = \alpha \pm \beta i$, $\beta \neq 0 \Rightarrow T \sim \begin{pmatrix} \alpha & \beta \\ \beta & -\alpha \end{pmatrix}$

(iii) $\lambda_0 = \lambda_1 = \lambda \Rightarrow T \sim \begin{pmatrix} \lambda + \mu & -\mu \\ -\mu & -\lambda + \mu \end{pmatrix}$ in any coord system, some μ .

\sim means under $O(1,1)$ Lorentz transformation.

The pf is straight forward, (ii) occurs since g 's T_{jk} might not be sym.

e.g. Given F_{ik} anti-sym, define

$$T_{ik} := \frac{1}{4\pi} \left(-g^{\ell m} F_{i\ell} F_{km} + \frac{1}{4} F_{\ell m} F^{\ell m} g_{ik} \right) \text{ a sym tensor}$$

If F is the electromagnetic field, T is called its energy-stress tensor

Lie Algebra $(V, [,])$ st. $[a, [b, c]] + [b, [c, a]] + [c, [a, b]] = 0$
 vector space skew-sym Jacobi identity

Remark: if we define $(\text{ad}(a))x := [a, x]$ then this is equiv to

$$\text{ad}(a)[b, c] = [\text{ad}(a)b, c] + [b, \text{ad}(a)c] \quad \text{i.e. } \text{ad}(a) \text{ is a Derivation.}$$

Examples: (a) \times product in \mathbb{R}^3

(b) A space of linear operators like "matrices" or "vector fields"
 $[a, b] := a \circ b - b \circ a$ or in fact any associative alg.

(c) Killing vfs form a Lie subalgebra:

$$[L_\xi, L_\eta] \zeta = L_\xi L_\eta \zeta - L_\eta L_\xi \zeta = 0 - 0 = 0 \text{ obviously!}$$

(d) classical Lie alg = matrix sub Lie alg of $\mathfrak{gl}(n, F)$.

$$\text{with } [A, B] = AB - BA \text{ as in (b)}$$

$F = \mathbb{R} \text{ or } \mathbb{C}$.

Lemma: For $G \subset GL(n, F)$, $\mathfrak{g} := T_e G$ is closed under $[,]$.

$$\text{pf: } A, B \in \mathfrak{g} \Rightarrow f(s) := e^{sA} e^{sB} e^{-s(A+B)} \in G \Rightarrow \mathfrak{g} \ni f'(0) = e^A B e^{-A} - B e^{-A} e^A = e^A B e^{-A} - B$$

with $f(0) = e$

$$\text{Now } h(t) := e^{tA} B e^{-tA} \in \mathfrak{g} \Rightarrow \mathfrak{g} \ni h'(0) = AB - BA$$

Example (1): $SU(2) \simeq SO(3, \mathbb{R}) \simeq (\mathbb{R}^3, \times)$ as Lie algebras over $F = \mathbb{R}$.

of course this follows from $SU(2) \simeq SO(3)$ as Lie group.

Explicitly. $SU(2)$ is spanned by

$SO(3, \mathbb{R})$ is spanned by

$$s_1 = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}, s_2 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, s_3 = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix};$$

$$x_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}, x_2 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}, x_3 = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$[s_1, s_2] = 2s_3, [s_2, s_3] = 2s_1, [s_3, s_1] = 2s_2 \quad [x_1, x_2] = x_3, [x_2, x_3] = x_1, [x_3, x_1] = x_2$$

Example (2): $\mathfrak{al}(2, \mathbb{R}) \simeq \mathfrak{so}(1, 2)$.

pf: This again was seen from isometry gp of $\mathbb{H} \simeq L^2$ (non-Euclidean geom)

Alternatively, use adjoint representation $\text{ad}: \mathfrak{g} \rightarrow \text{End}(\mathfrak{g})$

$$\text{which comes from } \text{Ad}: G \rightarrow \text{Aut}(\mathfrak{g}) \quad Y \mapsto g Y g^{-1}$$

$\text{Ad}(g)$ preserve the quadratic form, under basis Y_i :

$$Y_0 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, Y_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, Y_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

which is the Minkowski-Lorentz metric!

$$|Y|^2 := \det Y = \det(\delta^i_j Y_i)$$

$$= \begin{vmatrix} Y_1 & Y_2 + Y_0 \\ Y_2 - Y_0 & -Y_1 \end{vmatrix} = Y_0^2 - Y_1^2 - Y_2^2$$

Taking $g = \exp(tX) \Rightarrow \text{ad}(X) \in \mathfrak{so}(1, 2)$

Relation between Lie bracket of matrices & of differential operators

Defⁿ: Denote T_X the liouv. v.f. $T_X(x) := -Xx \equiv -X_k^i x^k \frac{\partial}{\partial x^i}$.

Thm: $[T_X, T_Y] = T_{[X, Y]}$.

Pf: $[T_X, T_Y]^i = X_k^i x^k \frac{\partial}{\partial x^i} (Y_l^i x^l) - Y_k^i x^k \frac{\partial}{\partial x^i} (X_l^i x^l)$
 $= X_k^i x^k Y_j^i - Y_k^i x^k X_j^i = -([X, Y]x)^i$ *

This applies to general left inv. v.f.s on a Lie group:

Prefⁿ: Let $X \in \mathfrak{g} = \text{Lie } G$, for $A \in G$ get $\lambda_A : G \rightarrow G : g \mapsto Ag$

hence $d\lambda_{A,e} : T_e G \rightarrow T_A G$ is simply $X \mapsto AX$

This defines a v.f. L_X on G via $L_X(A) = AX$

L_X is left inv: $d\lambda_B * (L_X(A)) = d\lambda_B * d\lambda_A * X = d(\lambda_B \lambda_A) * X = BAX = L_X(BA)$.

Cor: The integral curve $A'(t) = L_X(A(t)) = A(t)X$ is $A(t) = A(0) e^{tX}$.

Also, $[L_X, L_Y] = L_{[X, Y]}$. (same pf.) "notion [↑] left/right"

ie. The Lie alg. $\mathfrak{g} = \text{Lie } G \cong \text{Lie alg of l.i.v.f. on } G$.

Now we may extend any bi-linear form $\langle \cdot, \cdot \rangle_e$ on $\mathfrak{g} = T_e G$

to any $T_A G$, $A \in G$ by $\langle v, w \rangle_A := \langle d\lambda_{A^{-1}}^* v, d\lambda_{A^{-1}}^* w \rangle_e$.

ie. for $v = L_X(A)$, $w = L_Y(A) \in T_A G$, we set $\langle v, w \rangle_A = \langle L_X(A), L_Y(A) \rangle_A = \langle X, Y \rangle_e$

if $\langle \cdot, \cdot \rangle_e$ is non-degenerate, we get left-inv metric on G : $Ad^2 = \langle A^{-1}dA, A^{-1}dA \rangle_e$.

Key Example: $G = SO(n, \mathbb{R}) \hookrightarrow M_n(\mathbb{R}) \cong \mathbb{R}^{n^2}$

Euclidean metric on \mathbb{R}^{n^2} : $\langle X, Y \rangle = \sum x_j^i y_j^i = \text{tr}(XY^T)$

then $X \in SO(n) \Rightarrow |X|^2 = \text{tr}(XX^T) = \text{tr}(I_n) = n \Rightarrow SO(n) \hookrightarrow S_{\sqrt{n}}^{\frac{n^2-1}{2}}$.

It induces a metric $\langle \cdot, \cdot \rangle$ on $T_A G$, $\forall A \in G$.

Claim: $\langle \cdot, \cdot \rangle$ is bi-invariant: let $X, Y \in so(n, \mathbb{R})$, $A \in SO(n, \mathbb{R})$:

pf: $\langle L_X(A), L_Y(A) \rangle = \text{tr}(AX(AY)^T) = \text{tr}(AXY^T A^T) = \text{tr}(XY^T A^T A) = \text{tr}(XY^T)$. ρ_X the same *

Definition (Remark): A quad. form $\langle \cdot, \cdot \rangle_0$ on \mathfrak{g} satisfies

$\langle [X, Y], Z \rangle_0 + \langle Y, [X, Z] \rangle_0 = 0$ is called a Killing form (or metric)

A standard choice is $\langle X, Y \rangle_0 := -\text{tr}(\text{ad } X \text{ ad } Y)$. \mathfrak{g} is semi-simple if $\langle \cdot, \cdot \rangle_0$ is non-deg.

Thm: $\langle \cdot, \cdot \rangle$ on $so(n, \mathbb{R})$ is a Killing form, and non-degenerate.

pf: $X^T = -X$, $\forall X \in so(n, \mathbb{R})$, hence $\langle X, Y \rangle = \text{tr}(XY^T) = -\text{tr}(XY)$.

$\langle [X, Y], Z \rangle + \langle Y, [X, Z] \rangle = -\text{tr} \underline{XYZ} + \text{tr} \underline{YXZ} - \text{tr} \underline{YXZ} + \text{tr} \underline{YZX} = 0$.

Ex (i) via $u(n) \subset so(2n, \mathbb{R})$, we get Killing form $\langle X, Y \rangle = \text{Re } \text{tr } X\bar{Y}^T = -\text{Re } \text{tr } XY$.

(ii) compare the defⁿ via $\text{ad } X$. -8-

Cartan's d operator on Λ^k

$$df: d\omega = d(h dx^{i_1} \wedge \dots \wedge dx^{i_k}) \\ = dh \wedge dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

Recall we pull back f^* :

$$F^* d\omega = F^*(dh \wedge dx^{i_1} \wedge \dots \wedge dx^{i_k}) \\ = d(h \circ F) \wedge d(x^{i_1} \circ F) \wedge \dots \wedge d(x^{i_k} \circ F)$$

basic properties: d satisfies

(1) $df =$ total differential

(2) $d^2 = 0$

(3) Leibniz' rule $d(\omega \wedge \eta) = (d\omega) \wedge \eta + (-1)^p \omega \wedge d\eta$

d on function is map of cov.
 if $w \in \Lambda^p$ $df = \sum \frac{\partial f}{\partial x^i} dx^i = \sum \frac{\partial f}{\partial y^j} dy^j$

" $\sum \frac{\partial f}{\partial y^j} \frac{\partial y^j}{\partial x^i} dx^i$ "

In fact, d is unique under (1), (2), (3).

The pf is easy. But the key point is "why does it map of coord system?"

Then (Functoriality) for $F: (U, \sigma) \rightarrow (V, \tau)$, $d^2 F^* \omega = F^* d^2 \omega$ holds.

pf: $F^* \omega = (h \circ F) d(x^{i_1} \circ F) \wedge \dots \wedge d(x^{i_k} \circ F)$

$$d F^* \omega = d \left[(h \circ F) \frac{\partial x^{i_1}}{\partial y^{j_1}} \dots \frac{\partial x^{i_k}}{\partial y^{j_k}} \right] dy^{j_1} \wedge \dots \wedge dy^{j_k}$$

$$= d(h \circ F) \wedge d(x^{i_1} \circ F) \wedge \dots \wedge d(x^{i_k} \circ F)$$

this term gives $F^* d^2 \omega$ as recalled above.

$$+ (h \circ F) d \left(\frac{\partial x^{i_1}}{\partial y^{j_1}} \dots \frac{\partial x^{i_k}}{\partial y^{j_k}} \right) \wedge dy^{j_1} \wedge \dots \wedge dy^{j_k}$$

Now, a typical term is $d \left(\frac{\partial x^{i_1}}{\partial y^{j_1}} \right) \wedge dy^{j_1} \wedge dx^{i_2} \wedge \dots \wedge dx^{i_k}$

skew-sym $\Rightarrow \sum_{l, j_1} \frac{\partial^2 x^{i_1}}{\partial y^{j_1} \partial y^l} dy^l \wedge dy^{j_1} = 0$

Then: Cartan's intrinsic formula: for sum v.f.s x_0, \dots, x_k

$$(d\omega)(x_0, \dots, x_k) = \sum_{i=0}^k (-1)^i \partial_{x_i} (\omega(x_0, \dots, \hat{x}_i, \dots, x_k)) + \sum_{i < j} (-1)^{i+j} \omega([x_i, x_j], x_0, \dots, \hat{x}_i, \dots, \hat{x}_j, \dots, x_k)$$

eg. $k=0$, $df(x) = \partial_x f$ OK.

Remark: The sign and $(k+1)$ in the book is wrong!

$k=1$, $\omega \in \Lambda^1$, $d\omega(x, Y) = X\omega(Y) - Y\omega(x) - \omega([X, Y])$?

let $\omega = h dx^k$ $d\omega = \frac{\partial h}{\partial x^j} dx^j \wedge dx^k$ (we do not set $j < k$!)

for $x = a^i \partial_i$ $Y = b^j \partial_j \Rightarrow d\omega(x, Y) = \partial_j h a^j b^k - \partial_j h b^j a^k =$ LHS

RHS = $a^l \partial_l (h b^k) - b^l \partial_l (h a^k) - h (a^i \partial_i b^j - b^j \partial_j a^i) \partial_i$ = LHS.

Q: A pf for general k is similar but lengthy !!

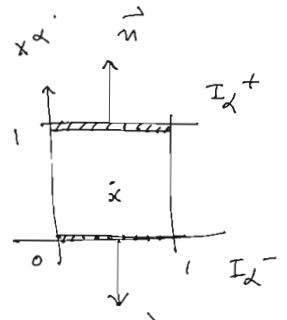
Remark: (Tensor notation) for $\omega = \sum T_{i_1 \dots i_k} dx^{i_1} \wedge \dots \wedge dx^{i_k}$; $(d\omega)_{i_1 \dots i_{k+1}} = \sum_{j=1}^{k+1} (-1)^{j-1} \partial_{x^{i_j}} T_{i_1 \dots \hat{i}_j \dots i_{k+1}}$

Stokes' Fund. Thm. of Calculus

Defⁿ: $f: U \subset \mathbb{R}^k \rightarrow \mathbb{R}^n$, $\omega \in \Lambda^k$ then

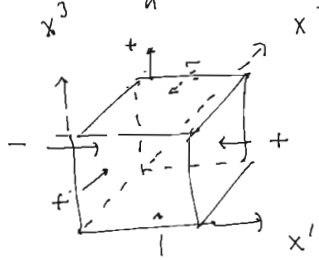
$$\int_{f(U)} \omega := \int_U f^* \omega := \int_U \left(\sum T_{i_1 \dots i_k} J_{i_1 \dots i_k}^{j_1 \dots j_k} \right) dx^1 \wedge \dots \wedge dx^k$$

as Riem integral in \mathbb{R}^k .



"singular" cube $\sigma: I^k \rightarrow \mathbb{R}^n$ C^∞
 $[0,1]^k \quad \partial I^k := \bigcup_{\alpha=1}^k (I_\alpha^+ \cup I_\alpha^-)$

Set orientation at $(\vec{n}, v_1, \dots, v_{k-1})$ is the same as the one in $x \in \text{Int } I^k$.
 Ex. when \vec{v} is in the α -th direction get $(-1)^{\alpha-1}$ sign:



Thm: $\varphi \in \Lambda^{k-1}(\Omega)$, $\sigma: I^k \rightarrow \Omega \subset \mathbb{R}^n$.

Then $\int_{\partial \sigma} \varphi = \int_{\sigma} d\varphi$.

if: this is just $\int_{\partial I^k} \sigma^* \varphi = \int_{I^k} \sigma^* d\varphi = d(\sigma^* \varphi)$ in \mathbb{R}^k .

so we may assume $\varphi = h dx^1 \wedge \dots \wedge \widehat{dx^\alpha} \wedge \dots \wedge dx^k$
 $d\varphi = \frac{\partial h}{\partial x^\alpha} (-1)^{\alpha-1} dx^1 \wedge \dots \wedge dx^k$

Fubini $\Rightarrow \int_{I^k} d\varphi = (-1)^{\alpha-1} \left(\int_{I_\alpha^+} \varphi - \int_{I_\alpha^-} \varphi \right) = \int_{\partial I^k} \varphi$

sign: $+, -, +, \dots$
 $\alpha = 1, 2, 3, \dots$

$x^\beta = 0$ or 1
 $\Rightarrow dx^\beta = 0$
 get zero contribution from other $\beta \neq \alpha$.

Corollary (Stokes' Thm): $\int_{\partial S} \varphi = \int_S d\varphi$ holds for general k -dim'l surface by partitioning S into union of singular cubes.

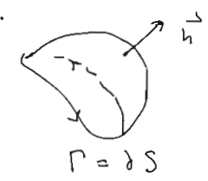


Remark: No metric is involved in the defⁿ. Called integral of 2nd kind. S integral of 1st kind means volume element $d\sigma$ is used.

Example 1. In \mathbb{R}^3 , All integral (of 2nd kind) can be viewed as 1st kind.

$\varphi \in \Lambda^0$: $\int_\gamma dh = h \Big|_{\gamma(a)}^{\gamma(b)}$ for $\gamma: [a,b] \rightarrow \mathbb{R}^n$ h any function.

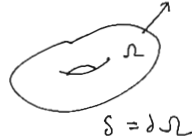
$\varphi \in \Lambda^1$: $\int_S d\varphi = \int_{\partial S} \varphi = \int_{\partial S} P dx + Q dy + R dz = \int_{\partial S} \vec{F} \cdot d\vec{r}$
 $= \int_S (Ry - Qz) dy \wedge dz + (Pz - Rx) dz \wedge dx + (Qx - Py) dx \wedge dy$



$= \int_S \begin{vmatrix} i & j & k \\ \partial_x & \partial_y & \partial_z \\ P & Q & R \end{vmatrix} \cdot \vec{n} d\sigma = \int_S \langle \text{Curl } \vec{F}, \vec{n} \rangle d\sigma$

Fact: $\vec{n} d\sigma = (y dz - z dy) dx + (z dx - x dz) dy + (x dy - y dx) dz$

$\varphi \in \Lambda^{k-1}$: $\int_{\partial \Omega} \varphi = \int_{\partial \Omega} P dy \wedge dz + Q dz \wedge dx + R dx \wedge dy = \int_S \vec{F} \cdot \vec{n} d\sigma$
 $= \int_{\Omega} (Px + Qy + Rz) dx \wedge dy \wedge dz = \int_{\Omega} \text{Div } \vec{F} d\text{Vol}$



Example 2. In $\mathbb{R}^{1,3}$, Maxwell eqⁿ: $\nabla \cdot \mathbf{H} = 0 = \text{curl } \mathbf{E} + \frac{1}{c} \frac{\partial \mathbf{H}}{\partial t}$

$\delta \mathbf{F} := \nabla \wedge \mathbf{F} = \frac{4\pi}{c} (\rho, \vec{v})$ i.e. $\text{div } \mathbf{E} = 4\pi \rho$; $\text{curl } \mathbf{H} + \frac{1}{c} \frac{\partial \mathbf{E}}{\partial t} = \frac{4\pi}{c} \rho \vec{v}$
 $\rho = \text{charge density}$

Ex. Explain meaning after \int .

Covariant Differentiation / Christoffel symbol

Def¹: \textcircled{T} (Gauge transf). In z^1, \dots, z^4 : $\Gamma_{ij}^k(z') = \frac{\partial z^k}{\partial z^i} \Gamma_{ij}^k + \frac{\partial z^k}{\partial z^i} \frac{\partial z^l}{\partial z^j} \frac{\partial z^m}{\partial z^l} \Gamma_{ij}^m + \frac{\partial z^k}{\partial z^i} \frac{\partial z^l}{\partial z^j} \frac{\partial z^m}{\partial z^l} \Gamma_{ij}^m$
 In particular, Γ is NOT a tensor of type (1,2). Only the difference is.

Then: Given $\Gamma_{ij}^k(x)$ in any coord x , the modified "co-variant derivative"

$$T^k_{ij} := \frac{\partial T^k}{\partial x^j} + \Gamma_{ij}^k T^i \text{ is a (1,1) tensor } \iff \textcircled{T} \text{ holds.}$$

$$\begin{aligned} \text{Pf: } T^k_{ij} &= \frac{\partial x^{j'}}{\partial x^j} \frac{\partial x^{k'}}{\partial x^k} \left(T^{k'} \frac{\partial x^k}{\partial x^{j'}} \right) + \Gamma_{ij}^k T^{i'} \frac{\partial x^{i'}}{\partial x^i} \\ &= \frac{\partial T^{k'}}{\partial x^{j'}} \frac{\partial x^{j'}}{\partial x^j} \frac{\partial x^k}{\partial x^k} + T^{k'} \frac{\partial x^{j'}}{\partial x^j} \frac{\partial^2 x^k}{\partial x^{j'} \partial x^{k'}} + \Gamma_{ij}^k T^{i'} \frac{\partial x^{i'}}{\partial x^i} \quad k \leftrightarrow i' \text{ in the middle} \\ &= \frac{\partial x^{j'}}{\partial x^j} \frac{\partial x^k}{\partial x^k} \left[\frac{\partial T^{k'}}{\partial x^{j'}} + T^{i'} \left(\frac{\partial x^{k'}}{\partial x^k} \frac{\partial x^k}{\partial x^{j'}} + \Gamma_{ij}^k \frac{\partial x^i}{\partial x^i} \frac{\partial x^{k'}}{\partial x^k} \frac{\partial x^j}{\partial x^{j'}} \right) \right] \quad * \end{aligned}$$

Cor: Let $\{\Gamma_{ij}^k\}$ be a Christoffel symbol (or connection, or co-var. der.)

Then $T_{ij}^k := \Gamma_{ij}^k - \Gamma_{ji}^k$ is a (1,2) tensor, called the torsion tensor.

Def²: Given Γ_{ij}^k is equiv. to say $\nabla_i \frac{\partial}{\partial x^j} = \Gamma_{ji}^k \frac{\partial}{\partial x^k}$ notice the (i,j) order

$$\text{i.e. } \nabla_i (T^j_{jk}) = (\partial_i T^j) \partial_j + T^j \partial_i \Gamma_{jk}^k = (\partial_i T^k + \Gamma_{ij}^k T^j) \partial_k$$

(i) By duality, $\nabla_i dx^j = -\Gamma_{ki}^j dx^k$

$$0 = \partial_i (dx^j \frac{\partial}{\partial x^k}) = (\nabla_i dx^j, \frac{\partial}{\partial x^k}) + (dx^j, \Gamma_{ki}^l \frac{\partial}{\partial x^l}) = \Gamma_{ki}^j$$

Remark:

← This is also Leibniz' rule for contraction of tensors

(ii) Extending by Leibniz' rule get ∇_i on all (p,q) tensors.

$$\begin{aligned} \nabla_i T &= \nabla_i \left(T^{i_1 \dots i_p}_{j_1 \dots j_q} \frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_p}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_q} \right) \\ &= \frac{\partial T^I}{\partial x^i} + T^{i_1 \dots i_p}_{j_1 \dots j_q} \Gamma_{i i_1}^{k_1} \frac{\partial}{\partial x^{k_1}} \otimes \dots - T^{i_1 \dots i_p}_{j_1 \dots j_q} \frac{\partial}{\partial x^i} \otimes \Gamma_{k i}^{j_1} dx^{k_1} \otimes \dots \\ &= \left(\partial_i T^I + \sum_{s=1}^p T^{i_1 \dots i_p}_{j_1 \dots j_q} \Gamma_{k i}^{i_s} - \sum_{s=1}^q T^{i_1 \dots i_p}_{j_1 \dots j_q} \Gamma_{j_s i}^k \right) \frac{\partial}{\partial x^i} \otimes dx^J \quad * \end{aligned}$$

Parallel Transport of Tensors along a curve:

for $X \in T_p S$, define $\nabla_X T = \sum_k \xi^k \nabla_{\partial_k} T$ for any tensor (field) T

for $\gamma: (a,b) \rightarrow S$ be a curve $\nabla_{\gamma'} T$ is defined, with $\xi^k = \frac{dx^k}{dt}$.

ODE \Rightarrow Given $T_a \in \otimes P^i \mathbb{R}^n (T_{r(a)} S)$, $\exists!$ T along γ st $\nabla_{\gamma'} T = 0$

eg. for vector fields: $(\nabla_{\gamma'} T)^i = \frac{dx^k}{dt} \left(\frac{\partial T^i}{\partial x^k} + \Gamma_{jk}^i T^j \right) = \frac{dT^i}{dt} + \Gamma_{jk}^i \frac{dx^k}{dt} T^j = 0$

Def³ (Geodesic): γ is a geodesic wrt given conn. Γ_{ij}^k iff $\nabla_{\gamma'} \gamma' = 0$.

i.e. $\frac{d^2 x^i}{dt^2} + \Gamma_{jk}^i \frac{dx^k}{dt} \frac{dx^j}{dt} = 0$ non-linear 2nd order ODE

det. by initial condi. $\gamma(0), \gamma'(0)$.

It depends only on $\Gamma_{(j)k}^i := \Gamma_{jk}^i + \Gamma_{kj}^i$, which is a torsion-free conn.

Notice that: Parallel transport / geodesics all notions indep. of coord. systems.

Question: Do connection really exist? say on a surface $S^m \hookrightarrow \mathbb{R}^n$?

Answer: YES. for any ∇ on \mathbb{R}^n (say $\Gamma_{ij}^k \equiv 0$, or any matrix function)

Set $\bar{\nabla}_x := \nabla_x^T$ the tangent part. since there is only one chart.

The standard $\nabla_i := \partial_i$ has a better property: $X(Y, Z) = \langle \nabla_x Y, Z \rangle + \langle Y, \nabla_x Z \rangle$ (*)

for $X, Y, Z \in C^\infty(TS) \Rightarrow X(Y, Z) = \langle \bar{\nabla}_x Y, Z \rangle + \langle Y, \bar{\nabla}_x Z \rangle$ as well. This motivates:

Connection ∇ compatible with $g_{ij} dx^i \otimes dx^j \triangleq g_{ij}$ is parallel, i.e. $\nabla_k g_{ij} \equiv 0$.

That is, $\nabla_k g_{ij} \equiv g_{ij;k} = \partial_k g_{ij} - \partial_j \Gamma_{ik}^l - \partial_i \Gamma_{jk}^l = 0$ (**)

equivalently, (*) holds for ∇ .

Fundamental Thm of metric geom (Levi-Civita):

$\exists!$ torsion-free conn ∇ comp. with given metric. called ∇^{LC} .

In fact: $\Gamma_{ij}^k = \frac{1}{2} g^{kl} (\partial_i g_{jl} + \partial_j g_{il} - \partial_k g_{ij})$. Pf: cyclic trick for (**)

∇ unique. Check \oplus holds

Cor.1: All other connections are $\nabla^{LC} + T$ where T is any (1,2) tensor. *

Cor.2: $\langle S, T \rangle = \text{const}$ along $r(t)$ if S, T parallel along $r(t)$.

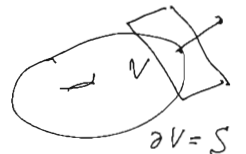
In particular, $|T| = \text{const}$. eg. r geodesic $\Rightarrow |r'| = c$, constant speed.

Example 1. Divergence of a v.f.: $\text{div} T = \nabla_i T^i = \frac{\partial T^i}{\partial x^i} + \Gamma_{ki}^i T^k$

$$\Gamma_{ki}^i = \frac{1}{2} g^{il} (\partial_i g_{lk} + \partial_k g_{li} - \partial_l g_{ki}) = \frac{1}{2g} \partial_k g = \partial_k \log \sqrt{|g|} \quad \vec{n}$$

$$\nabla T = \partial_i T^i + \frac{1}{2g} (\partial_k g) T^k = \frac{1}{\sqrt{|g|}} \frac{\partial}{\partial x^k} (\sqrt{|g|} T^k)$$

\Rightarrow Thm (Divergence thm for Riem space) (Ex 29.5 #14)

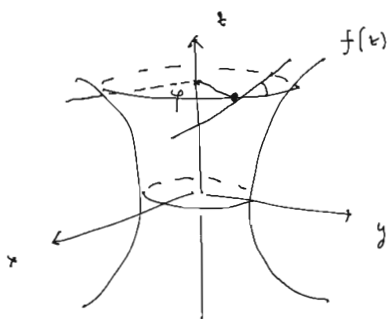


$$\int_{\partial V} \langle T, \vec{n} \rangle dS = \int_V \text{div} T dV. \quad * Q: \text{ why is this true?}$$

$$\text{pf: LHS} \stackrel{*}{=} \int_{\partial V} T^i dS_i \quad \text{with } dS_i := (-1)^{i-1} \sqrt{|g|} dx^1 \wedge \dots \wedge \widehat{dx^i} \wedge \dots \wedge dx^n$$

$$= \int_{\partial V} T^i (-1)^{i-1} \sqrt{|g|} dx^1 \wedge \dots \wedge \widehat{dx^i} \wedge \dots \wedge dx^n = \int_V \frac{\partial}{\partial x^i} (T^i \sqrt{|g|}) dx^1 \wedge \dots \wedge dx^n = \text{RHS} \quad \#$$

Example 2: Geodesics on surface of revolution. i.e. $r(t), \nabla_{r'} r' = (r'')^T = 0$.



$$r(\varphi, z) = (f(z) \cos \varphi, f(z) \sin \varphi, z) \quad \begin{cases} r_1 = (-f \sin \varphi, f \cos \varphi, 0) \\ r_2 = (f' \cos \varphi, f' \sin \varphi, 1) \end{cases}$$

$$ds^2 = f^2 d\varphi^2 + (1 + (f')^2) dz^2 \quad \text{i.e. } 1 = f^2 \dot{\varphi}^2 + (1 + f'^2) \dot{z}^2$$

$$\ddot{\varphi} + \frac{2ff'}{f^2} \dot{\varphi} \dot{z} = 0 \Rightarrow (f^2 \dot{\varphi})' = f^2 \ddot{\varphi} + 2ff' \dot{z} \dot{\varphi} = 0$$

$$\text{i.e. } f^2 \dot{\varphi} = \text{constant} \Rightarrow \text{Clairaut relation: } f \cos \varphi = c$$

$$= \langle r_1 \dot{\varphi} + r_2 \dot{z}, r_1 \rangle = \langle \dot{r}, r_1 \rangle = f \cos \varphi$$

$$\text{Also, } c = f^2 \frac{d\varphi}{dz} \dot{z} = f^2 \frac{d\varphi}{dz} \sqrt{\frac{1 - f^2 \dot{\varphi}^2}{1 + f'^2}} = f \frac{d\varphi}{dz} \sqrt{\frac{f^2 - c^2}{1 + f'^2}} \Rightarrow \frac{d\varphi}{dz} = \frac{c}{f} \sqrt{\frac{1 + f'^2}{f^2 - c^2}} \Rightarrow \varphi = \int \frac{c}{f} \sqrt{\frac{1 + f'^2}{f^2 - c^2}} dz \quad \#$$

Riemann's Curvature Tensor R^i_{jke} :

let $T = T^i \partial_i$ be a v.f. want to compare $\nabla_k \nabla_e T^i - \nabla_e \nabla_k T^i$

$$\begin{aligned} \nabla_k (\nabla_e T^i) &= \nabla_k (\partial_e T^i + \Gamma_{ge}^i T^g) \equiv \nabla_k T^i_{;e} \quad \text{ie. } T^i_{;ek} - T^i_{;k e} \\ &= \partial_k (\partial_e T^i + \Gamma_{ge}^i T^g) + \Gamma_{pk}^i T^p_{;e} - \Gamma_{ek}^p T^i_{;p} \\ &= \underbrace{\partial_k \partial_e T^i} + \underbrace{\partial_k \Gamma_{ge}^i T^g} + \Gamma_{ge}^i \partial_k T^g + \underbrace{\Gamma_{pk}^i (\partial_e T^p + \Gamma_{gl}^p T^g)} - \underbrace{\Gamma_{ek}^p (\partial_p T^i + \Gamma_{gp}^i T^g)} \end{aligned}$$

$$\begin{aligned} \nabla_k \nabla_e T^i - \nabla_e \nabla_k T^i &= (\underbrace{\partial_k \Gamma_{ge}^i} - \partial_e \Gamma_{gk}^i + \underbrace{\Gamma_{jk}^i \Gamma_{gl}^p} - \Gamma_{pe}^i \Gamma_{gk}^p) T^g \\ &\quad + \Gamma_{ge}^i \partial_k T^g - \Gamma_{pk}^i \partial_e T^p - (\Gamma_{ek}^p - \Gamma_{ke}^p) T^i_{;p} \\ &\quad - \Gamma_{gk}^i \partial_e T^g + \Gamma_{pe}^i \partial_k T^p \\ &=: R^i_{jke} T^j + T^p_{ke} T^i_{;p} \quad \mathcal{T} = \text{torsion tensor} \end{aligned}$$

Rmk: the sign in the book is wrong!

Def/Thm: For any conn, $R^i_{jke} := \frac{\partial \Gamma_{ge}^i}{\partial x^k} - \frac{\partial \Gamma_{gk}^i}{\partial x^e} + \Gamma_{pk}^i \Gamma_{ge}^p - \Gamma_{pe}^i \Gamma_{gk}^p$

Coordinate free formulas / defⁿ:

is a (1,3) tensor *

$$\mathcal{T}(X, Y) := \nabla_X Y - \nabla_Y X - [X, Y]$$

$$R(X, Y)Z := [\nabla_X, \nabla_Y]Z - \nabla_{[X, Y]}Z \quad \text{for any } C^\infty \text{ v.f. } X, Y, Z$$

The correction terms are added so that they are "function-linear" (check!)

so can compute RHS using any frame, eg. cor. frame ∂_i .

$$\textcircled{1} \quad \mathcal{T}(\partial_i, \partial_j) = \nabla_{\partial_i} \partial_j - \nabla_{\partial_j} \partial_i - [\partial_i, \partial_j] = (\Gamma_{ji}^k - \Gamma_{ij}^k) \partial_k = -T^k_{ij} \partial_k \quad *$$

$$\begin{aligned} \textcircled{2} \quad R(\partial_k, \partial_e) \partial_g &= \nabla_k \nabla_e \partial_g - \nabla_e \nabla_k \partial_g = \nabla_k (\Gamma_{ge}^i \partial_i) - \nabla_e (\Gamma_{gk}^i \partial_i) \\ &= \partial_k \Gamma_{ge}^i \partial_i + \Gamma_{ge}^i \Gamma_{ik}^j \partial_j - \partial_e \Gamma_{gk}^i \partial_i - \Gamma_{gk}^i \Gamma_{ie}^j \partial_j \\ &= R^i_{jke} \partial_i \quad * \end{aligned}$$

Thm (Symmetries)

Compare the sign convention with the book.

(i) $R^i_{jke} = -R^i_{jek}$ for any ∇

(ii) (1st Bianchi identity) $\nabla \text{sym} \Rightarrow R^i_{[jke]} := R^i_{jke} + R^i_{kej} + R^i_{ekj} = 0$

(iii) ∇ compatible with metric $\Rightarrow R_{ijke} := g_{ip} R^p_{jke}$ skew-sym in (i,j)

(iv) $\nabla = \nabla^{LC} \Rightarrow R_{ijke} = R_{keij} \quad \equiv \langle R(\partial_k, \partial_e) \partial_g, \partial_i \rangle$

pf: (i) is by defⁿ. (ii): By $\textcircled{2}$, equiv to: $0 = [\nabla_k, \nabla_e] \partial_g + [\nabla_e, \nabla_g] \partial_k + [\nabla_g, \nabla_k] \partial_e$

expand out: $\nabla_k \nabla_e \partial_g - \nabla_e \nabla_k \partial_g + \nabla_e \nabla_g \partial_k - \nabla_g \nabla_e \partial_k + \nabla_g \nabla_k \partial_e - \nabla_k \nabla_g \partial_e = 0$.

since sym (torsion free) $\Leftrightarrow \nabla_e \partial_g = \nabla_g \partial_e \quad *$

(iii) $\langle [\nabla_k, \nabla_l] \xi, \xi \rangle = \langle [\nabla_k, \nabla_l] (\xi^i \partial_i), \xi^j \partial_j \rangle \quad \xi \text{ any } C^\infty \text{ v.f.}$

$= \langle R_{p k l}^i \partial_i, \xi^j \partial_j \rangle = g_{ij} R_{p k l}^i \xi^j = R_{p k l}^i \xi^i$
 use the fact that $R(X, Y)Z$ is function-linear (tensor). Rmk: The sign and pf in the book is wrong!

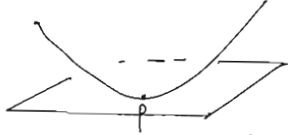
Now $\partial_k \partial_l \langle \xi, \xi \rangle = 2 \partial_k \langle \nabla_l \xi, \xi \rangle = 2 \langle \nabla_k \nabla_l \xi, \xi \rangle + 2 \langle \nabla_l \xi, \nabla_k \xi \rangle$
 $\Rightarrow 0 = \partial_k \partial_l \langle \xi, \xi \rangle - \partial_l \partial_k \langle \xi, \xi \rangle = 2 \langle [\nabla_k, \nabla_l] \xi, \xi \rangle$

(iv) Exercise : (i) + (ii) + (iii) \Rightarrow (iv).

Defⁿ: (Let $\nabla = \nabla^{LC}$) Ricci curvature $R_{ge} := R_{g k e}^k = g^{ik} R_{i g k e}$.
 scalar curvature $R := g^{e g} R_{g e} = g^{i e} g^{j k} R_{i g k e}$.

Example 1. Thm: 2D $\Rightarrow R = 2K$.

For $S \hookrightarrow \mathbb{R}^{n+1}$ hyp. surface $z = f(x^1, x^2), \nabla f|_p = 0$
 $\delta_{ij} = g_{ij} + f_i f_j \quad \nabla^{LC} = (D^{\mathbb{R}^3})^T$
 $\partial_k g_{ij}|_p = 0 \neq \Gamma_{ij}^k|_p = 0$
 $g_{ij}|_p = g_{ij} \text{ (normal cov at } p \text{)}$
 $r(x^1, x^2) = (x^1, x^2, f)$
 $r_1 = (1, 0, f_1)$
 $r_2 = (0, 1, f_2)$



$R_{g k e}^i = \partial_k \Gamma_{p e}^i - \partial_e \Gamma_{p k}^i = \frac{1}{2} (\partial_k \partial_g g_{i e} + \partial_k \partial_x f_i f_e - \partial_k \partial_i g_{g e} - \partial_e \partial_g g_{i k} - \partial_e \partial_k f_i f_g + \partial_e \partial_i g_{g k})$

Now for $n=2, R_{1212} = R_{212}^1 = \frac{1}{2} (\partial_1 \partial_2 g_{12} - \partial_1^2 g_{22} - \partial_2^2 g_{11} + \partial_2 \partial_1 g_{21})$
 $= \frac{1}{2} (2(f_1^2 + f_1 f_{22}) - 2 f_2^2 - 2 f_1^2) = f_{11} f_{22} - f_{12}^2 = K(p)$

Hence $R = g^{g e} R_{g e}^i = R_{1212}^1 + R_{212}^2 = 2K$

Rmk: It is clear that $R_{ij} = R g_{ij}, R = 2 \frac{R_{1212}}{g_{11} g_{22} - g_{12}^2}$
 $\partial_1 \partial_2 (f_1 f_2) = \partial_1 (f_2) f_2 + f_1 \partial_2 (f_2) = f_2^2 + f_{11} f_{22}$
 $\partial_2 \partial_1 (f_2 f_2) = 2 f_2 \partial_1 f_2 = 2 f_1 f_{22}$

In general for a plane $\sigma = \langle X, Y \rangle \subset T_p S$
 sectional curvature $K(\sigma) := \frac{\langle R(X, Y)Y, X \rangle}{\|X \wedge Y\|^2}$
 generalizes Gauss K.

(Thm: All $K(\sigma)$ at $T_p S$ determine $R(X, Y, Z, W)$.) $R(X, Y, Z, W) := \langle R(X, Y)W, Z \rangle$

Example 2: 3D, EX. Thm: $R_{\alpha \beta \gamma \delta} = -\frac{R}{2} (g_{\alpha \gamma} g_{\beta \delta} - g_{\alpha \delta} g_{\beta \gamma}) + R_{\alpha \gamma} g_{\beta \delta} - R_{\alpha \delta} g_{\beta \gamma} + R_{\beta \delta} g_{\alpha \gamma} - R_{\beta \gamma} g_{\alpha \delta}$
 def: $R_{i g k e} = R [i, g] c k e] = R_{AB}$ quad form on $\Lambda^2(T_p S)$ $[i, g] \leftrightarrow e^i \wedge e^g \quad rk = 3$
 $R_{AB} = R_{BA} \Rightarrow$ only 6 components. R_{ij} also has 6 comp. sym.

Example 3: 4D. Einstein's field Eqⁿ: $R_{ij} - \frac{1}{2} R g_{ij} = \lambda T_{ij}; \nabla_j T_i^j = 0$

Ex. 2nd Bianchi identity $R_{ij} [k l i m] = 0$ (Ex 30.5 #7)
 (30.5 #7 + #8) Also, Einstein eqⁿ in dim $n \geq 3$, Riem case, $R_{ij} = \lambda g_{ij} \Rightarrow \lambda = \text{const.}$

Example 4 : Lie gp G with bi-invariant metric $\langle \cdot, \cdot \rangle$.

$X, Y \in \mathfrak{g}$, L_X, L_Y l.i.v.f. Let $\nabla_{L_X} L_Y := \frac{1}{2} L_{[X, Y]} = \frac{1}{2} [L_X, L_Y]$

Lemma : $\nabla = \nabla^{LC}$! super easy !!

Q : why does it

pf: $T(L_X, L_Y) = \nabla_{L_X} L_Y - \nabla_{L_Y} L_X - [L_X, L_Y] = 0$ for-free enough to check just for l.i.v.f.'s ?

$L_X \langle L_Y, L_Z \rangle - (\langle \nabla_{L_X} L_Y, L_Z \rangle + \langle L_Y, \nabla_{L_X} L_Z \rangle) = 0$
 " $\frac{1}{2} [L_X, L_Y]$ $\frac{1}{2} [L_X, L_Z]$ by defⁿ of Killing condition

cor: for such (G, ∇) , $R(X, Y)Z = -\frac{1}{4} [[X, Y], Z]$ at $\mathfrak{g} = T_e G$.

Hence $R(X, Y, Z, W) = \frac{1}{4} \langle [X, Y], [Z, W] \rangle$ and $R(X, Y, X, Y) = \frac{1}{4} |[X, Y]|^2 \geq 0$.

The formula hold at every $T_A G$ via l.i.v.f.s.

pf: $R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z$
 $= \frac{1}{4} [X, [Y, Z]] - \frac{1}{4} [Y, [X, Z]] - \frac{1}{2} [[X, Y], Z] = -\frac{1}{4} [[X, Y], Z]$ by Jacobi id.

$R(X, Y, Z, W) = \langle R(X, Y)W, Z \rangle = -\frac{1}{4} \langle [[X, Y], W], Z \rangle = \frac{1}{4} \langle (ad W)[X, Y], Z \rangle$
 $= -\frac{1}{4} \langle [X, Y], (ad W)Z \rangle = \frac{1}{4} \langle [X, Y], [Z, W] \rangle$ *

Cor: For such (G, ∇) , geodesics thr e \equiv 1-parameter subgroups.

In particular, the exp maps defined in both cases coincide.

pf: $A(t) = e^{tX} \Rightarrow A'(t) = AX = L_X \Rightarrow \nabla_{A'} A' = \nabla_{L_X} L_X = \frac{1}{2} [L_X, L_X] = 0$

Conversely eqⁿ $\nabla_{A'} A' = 0$ with $A'(0) = X$ always has (unique) sol $A(X) = e^{tX}$ *

Remark: for such (G, ∇) , it is geod. complete. Hopf-Rinow \Rightarrow any 2 pt can be joined by a geod, ie exp is onto. Hence $SL(2, \mathbb{R})$ does not.

Gauss-Codazzi Equations:

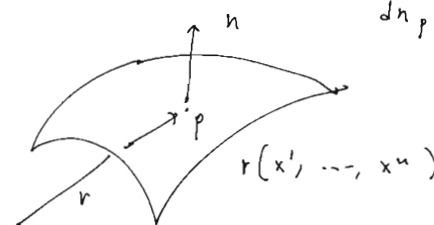
For $S \subset \mathbb{R}^{n+1}$ cov y^1, \dots, y^{n+1}
 n -dim

$r_{ij} = (D_j r_i)^T + (D_j r_i)^N$
 $= \nabla_j r_i + \langle r_{ij}, n \rangle n$ 2nd fund form
 $=: \sum_{k=1}^n \Gamma_{ij}^k r_k + b_{ij} n$

$dh_p : T_p S \rightarrow T_{ncp} S^n \cong T_p S$

So $b_{ij} = \langle r_{ij}, n \rangle = -\langle r_i, n_j \rangle \equiv -\langle r_j, n_i \rangle$

$dh_p : n_i = a_i^j r_j \Rightarrow a_i^j a_j^k = \langle n_i, r_k \rangle = -b_{ik}$
 $= -b_{ij}^k r_j$



compatibility:

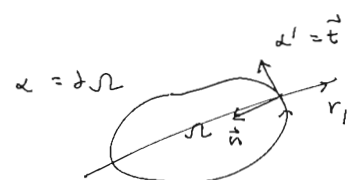
$r_{ijk} = \partial_k \Gamma_{ij}^l r_l + \Gamma_{ij}^s \Gamma_{sk}^l r_l + \partial_k b_{ij} n - b_{ij} b_k^l r_l$ due to satisfy
 $= (\partial_k \Gamma_{ij}^l + \Gamma_{ij}^s \Gamma_{sk}^l - b_{ij} b_k^l) r_l + (\Gamma_{ij}^s b_{sk} + \partial_k b_{ij}) n \stackrel{\downarrow}{=} r_{ikj}$

Thm: $\partial_k \Gamma_{ij}^l - \partial_j \Gamma_{ik}^l + \Gamma_{ij}^s \Gamma_{sk}^l - \Gamma_{ik}^s \Gamma_{sj}^l = b_{ij} b_k^l - b_{ik} b_j^l$ (Gauss eqⁿ)

Frobenius integrability] $\partial_k b_{ij} - \partial_j b_{ik} = -\Gamma_{ij}^s b_{sk} + \Gamma_{ik}^s b_{sj}$ (Codazzi) det. $S \subset \mathbb{R}^{n+1}$ upto \mathbb{R}^n -motion *

Gauss-Bonnet for surfaces

Lemma: Orthogonal curv exists in dim 2. (for elementary pt. using level functions)



$$f=0 \Rightarrow K = -\frac{1}{\sqrt{EG}} \left[\left(\frac{\sqrt{E} E_2}{\sqrt{G}} \right)_2 + \left(\frac{\sqrt{G} G_1}{\sqrt{E}} \right)_1 \right]$$

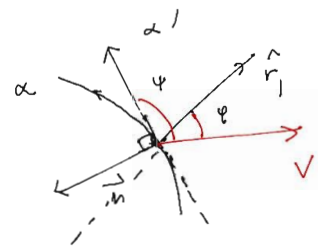
pick any $e_1 \perp e_2$ then
 $\frac{1}{2} \frac{1}{\sqrt{EG}} (E_2 x' - G_1 y')$
 || Q : what is it?

$$\int_{\Omega} K dA = \int_{\Omega} (Q_x - P_y) dx dy = \int_{\partial\Omega} \left(\frac{\sqrt{E} E_2}{\sqrt{G}} x' - \frac{\sqrt{G} G_1}{\sqrt{E}} y' \right) dl$$

Def: $\alpha' = r_1 x' + r_2 y'$ by arc length s , geodesic curvature $\nabla_{\alpha'} \alpha' =: k_g \vec{n}$.
 idea: k_g is the change rate of certain angle, as in the \mathbb{R}^2 case.

① let V be a parallel v.f. along α : $\nabla_{\alpha'} V = 0$; $|V| = 1$.
 $\langle V, \alpha' \rangle' = \langle V, \nabla_{\alpha'} \alpha' \rangle = k_g \langle V, \vec{n} \rangle = \cos(\frac{\pi}{2} + \psi) = -\sin \psi \Rightarrow k_g = \psi'$
 $(\cos \psi)' = -\sin \psi \cdot \psi'$ notice the "+", not "-".

② other choice of unit v.f.'s. eg. $\hat{r}_1 = r_1 / |r_1| \approx r_1 / \sqrt{E}$: let $\nabla_{\alpha'} \hat{r}_1 = \lambda \hat{r}_2$.
 then similarly $\lambda = \varphi'$ when $\cos \psi = \langle \hat{r}_1, \alpha' \rangle$.
 of course ψ', φ' are all indep of choices of V .



$$\nabla_{\alpha'} \hat{r}_1 = x' \nabla_1 \frac{r_1}{\sqrt{E}} + y' \nabla_2 \frac{r_1}{\sqrt{E}} \quad \hat{r}_2 \text{ component } \left(\frac{x'}{\sqrt{E}} \Gamma_{11}^2 + \frac{y'}{\sqrt{E}} \Gamma_{12}^2 \right) r_2$$

$$\Gamma_{11}^2 = \frac{1}{2} g^{22} (-g_{22})_{,11} = \frac{1}{2} \frac{-E_2}{G} \quad ; \quad \Gamma_{12}^2 = \frac{1}{2} g^{22} \partial_1 g_{22} = \frac{1}{2} \frac{G_1}{G} \quad \theta_{\alpha} = \int_{\Omega} K dA$$

$$\Rightarrow \lambda = \langle \nabla_{\alpha'} \hat{r}_1, \hat{r}_2 \rangle = \frac{1}{2} \frac{1}{\sqrt{EG}} (E_2 x' - G_1 y')$$



$$\Rightarrow \int_{\Omega} K dA = -\int_{\partial\Omega} \lambda dl = \int_{\partial\Omega} \psi' dl = (-\psi) \Big|_0^L =: \text{Holonomy angle } \theta_{\alpha}$$

③ let $\Theta := \psi - \varphi = \text{angle}(\hat{r}_1, \alpha')$

$$\Rightarrow \int_{\partial\Omega} \Theta' = \int_{\partial\Omega} \psi' + \int_{\partial\Omega} (-\varphi)' = \int_{\alpha} k_g + \int_{\Omega} K dA$$

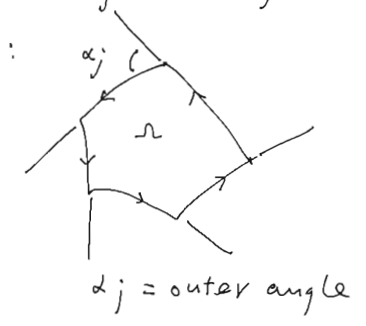
Hopf: See $\textcircled{*} \quad 2\pi - \sum \alpha_j \Rightarrow 2\pi = \sum \alpha_j + \int_{\alpha} k_g + \int_{\Omega} K$
 0-dim curvature 1-dim curvature 2-dim curvature

Theorem (Gauss-Bonnet)

$$2\pi \cdot \chi(\Omega) = \sum \alpha_j + \int_{\partial\Omega} k_g + \int_{\Omega} K. \quad (\text{ex. Prove it by triangulations})$$

Applications: (1) geodesic Δ
 $\theta_1 + \theta_2 + \theta_3 - \pi = \int_{\Omega} K$

- (2) $K < 0 \Rightarrow$ 2 geodesics intersects at most once.
- (3) $K > 0$ opt \Rightarrow any 2 geodesics intersect.



pf: $g(s) = 0$. if $\textcircled{O} \approx \textcircled{X}$ then $0 = \int K > 0$.

1-dim'l variational problems: Action functional via Lagrangian.

$$S[\gamma] = \int_P^Q L(x(t), \dot{x}(t)) dt \quad L(t, x, \dot{x}) \text{ a function in } (t, x, \dot{x}) \in [a, b] \times U \times \mathbb{R}^n$$

Q: find γ with least action. $\gamma: x: [a, b] \rightarrow U \quad x(a) = P, x(b) = Q$

Thm: If γ_0 attains minimum among sm curves from P to Q

then the "variational derivative" $\frac{\delta S}{\delta x^i} := \frac{\partial L}{\partial x^i} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^i} \right) = 0, \forall i = 1, \dots, n$

pf: For any $\eta \in C^1([a, b], U), \eta(a) = 0 = \eta(b)$: (Euler-Lagrange eq'n)

$$\begin{aligned} 0 = \frac{d}{d\epsilon} S[\gamma_0 + \epsilon \eta] \Big|_{\epsilon=0} &= \int_a^b \left(\frac{\partial L}{\partial x^i} \eta^i(t) + \frac{\partial L}{\partial \dot{x}^i} \dot{\eta}^i(t) \right) dt \\ &= \int_a^b \frac{\partial L}{\partial x^i} \eta^i dt + \left. \frac{\partial L}{\partial \dot{x}^i} \eta^i \right|_a^b - \int_a^b \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^i} \right) \eta^i dt = \int_a^b \left(\frac{\partial L}{\partial x^i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}^i} \right) \eta^i dt \end{aligned}$$

Set $\eta^i = f \frac{\delta S}{\delta x^i}$ with $f \in C^\infty, f(a) = f(b) = 0, \text{ o.w. } > 0 \Rightarrow \frac{\delta S}{\delta x^i} \equiv 0 \forall i$

Def'n: Write E-L eq'n as $\dot{p}_i = f_i$ where $p_i := \frac{\partial L}{\partial \dot{x}^i}$, $f_i := \frac{\partial L}{\partial x^i}$.

Also, $E := \dot{x}^i \frac{\partial L}{\partial \dot{x}^i} - L$: energy. momentum force

Example (a) $L = \frac{1}{2} m |\dot{x}|^2 - U(x) \Rightarrow \vec{f} = \nabla^{(x)} L = -\nabla U, \vec{p} = \nabla^{(\dot{x})} L = m \dot{x} = m \dot{x}$

so E-L \Leftrightarrow Newton's equation $m \ddot{x} = -\nabla U$. Also $E = m \dot{x}^2 - L = \frac{1}{2} m \dot{x}^2 + U$.

(b) Energy of a curve in a space with metric g_{ij} :

$$L = \frac{1}{2} |\dot{x}|^2 = \frac{1}{2} g_{ij}(x) \dot{x}^i \dot{x}^j \Rightarrow p_k = g_{kj} \dot{x}^j = \dot{x}_k; f_k = \frac{1}{2} (\partial_k g_{ij}) \dot{x}^i \dot{x}^j; E = L!$$

$$E-L \Leftrightarrow \frac{d}{dt} p_k = \partial_i g_{kj} \dot{x}^i \dot{x}^j + g_{kj} \ddot{x}^j = f_k = \frac{1}{2} \partial_k g_{ij} \dot{x}^i \dot{x}^j$$

$$g^{km} \Rightarrow \ddot{x}^m + g^{km} (\partial_i g_{kj} - \frac{1}{2} \partial_k g_{ij}) \dot{x}^i \dot{x}^j = \text{sym in } \Sigma_{ij} \quad \ddot{x}^m + p_{ij}^m \dot{x}^i \dot{x}^j = 0$$

ie. the extremal curve γ_0 is a geodesic, so with parameter prop. to l .

(c) Length of a curve in $dl^2 = g_{ij} dx^i dx^j$:

$$L = |\dot{x}| = \sqrt{g_{ij} \dot{x}^i \dot{x}^j}. \text{ Then } E-L \Leftrightarrow \frac{d}{dt} \left(\frac{\sum \partial_k g_{ij} \dot{x}^i \dot{x}^j}{2 \sqrt{g_{ij} \dot{x}^i \dot{x}^j}} \right) = \frac{(\partial_k g_{ij}) \dot{x}^i \dot{x}^j}{2 \sqrt{g_{ij} \dot{x}^i \dot{x}^j}}$$

This could be complicated, but if we set $t = \mu l$, then $|\dot{x}| = |\dot{x}| = \mu$ and E-L eq'n goes back to case (b). ie. geodesic.

Prmk: arc length l is the "natural parameter" since it is inv. under parametrization.

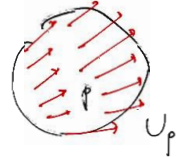
Conservation Laws: preliminary cases.

$$\frac{dE}{dt} = \frac{d}{dt} \left(\dot{x}^i \frac{\partial L}{\partial \dot{x}^i} - L \right) = \ddot{x}^i \frac{\partial L}{\partial \dot{x}^i} + \dot{x}^i \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^i} \right) - \frac{\partial L}{\partial t} - \frac{\partial L}{\partial x^i} \dot{x}^i - \frac{\partial L}{\partial \dot{x}^i} \ddot{x}^i = -\frac{\partial L}{\partial t}$$

Thm: Along an extremal $\gamma_0(t)$, the energy E is indep of t iff L is indep of t .

Similarly, and easier, $\dot{p}_i \equiv 0$ along $\gamma_0 \Leftrightarrow L$ is indep of x^i (ie. $\frac{\partial L}{\partial x^i} \equiv 0$).

General case: Suppose that \exists 1 parameter local gp of local transformations $\forall p \in \mathbb{R}^n, \exists S_\tau: U_p \rightarrow \mathbb{R}^n \subset \mathbb{C}^\infty, \forall \tau \in (-\delta_p, \delta_p)$
 s.t. $S_0 = \text{id}, S_{\tau_1 + \tau_2} = S_{\tau_1} \circ S_{\tau_2}, S_{-\tau} = S_\tau^{-1}$ over the region,
 Had seen, $\{S_\tau\}$ is gen. by a v.f. $\mathbb{X}(p) := \frac{d}{d\tau} S_\tau(p) \Big|_{\tau=0}$ that they are defined.



Defⁿ: (time-indep case)

$\{S_\tau\}$ preserves $L(x, \dot{x})$ if $S_\tau^* L(x, \dot{x}) := L(S_\tau(x), S_{\tau*}(\dot{x})) \equiv L$.

Write $x(\tau) := S_\tau(x)$. Then this is equiv. to

$$0 = \frac{\Delta L}{\Delta \tau} = \frac{\partial L}{\partial x^i} \dot{x}^i(\tau) + \frac{\partial L}{\partial \dot{x}^i} \frac{d \dot{x}^i(\tau)}{d\tau} \quad \text{where } \dot{x}^i(\tau) = \frac{\partial x^i(\tau)}{\partial x^j} \dot{x}^j \quad \text{tangent map } x=x(0) \text{ to } x(\tau)$$

$$(At \tau=0) = \mathbb{X}^i \frac{\partial L}{\partial x^i} + \frac{\partial \mathbb{X}^i}{\partial x^j} \dot{x}^j \frac{\partial L}{\partial \dot{x}^i} \quad (*)$$

Theorem (E. Noether): If L is preserved by S_τ gen. by \mathbb{X} , then the momentum in the \mathbb{X} direction is conserved, i.e., $\mathbb{X}^i p_i = \text{constant}$.

Pf: $\frac{d}{dt} (\mathbb{X}^i p_i) = \frac{d}{dt} \left(\mathbb{X}^i \frac{\partial L}{\partial \dot{x}^i} \right) = \frac{d}{dt} \left(\mathbb{X}^i(x) \frac{\partial L}{\partial \dot{x}^i} + \mathbb{X}^i \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^i} \right) \right)$ Notice: \mathbb{X} does not dep on t , but $x(t)$ does!

$$= \frac{\partial \mathbb{X}^i}{\partial x^j} \dot{x}^j \frac{\partial L}{\partial \dot{x}^i} + \mathbb{X}^i \frac{\partial L}{\partial x^i} = 0 \quad \text{by } (*) \text{ and E-L}$$

Example: 2-particle system in \mathbb{R}^3 . (Example (c)+(d) in §32.2)

Lagrangian $L = \sum_{i=1}^n \frac{1}{2} m_i |\dot{x}_i|^2 - \frac{1}{2} \sum_{i \neq j} V(x_i, x_j)$ in \mathbb{R}^{3n} . $x_i = (x_i^1, x_i^2, x_i^3) \in \mathbb{R}^3$
 translation invariance $\nRightarrow V(x_i, x_j) = V(x_i - x_j)$

Cor. $P_{\text{total}} := \sum_{i=1}^n m_i \dot{x}_i \in \mathbb{R}^3$ is const. in t .

pf: $x^1 \mapsto x^1 + \tau$ in \mathbb{R}^3 induces a v.f. in \mathbb{R}^{3n} : $\mathbb{X} = (1, 0, 0; 1, 0, 0; \dots)^T$
 $\Rightarrow \sum_{i=1}^n m_i \dot{x}_i^1$ is const. in t . Similarly for x^2 and x^3 components

Case $n=2$: $m_1 \dot{x}_1 + m_2 \dot{x}_2 = \vec{c} = 0$ (may assume this under unif. moving frame)
 then may even assume $m_1 x_1 + m_2 x_2 = 0$ by choosing $\vec{0}$ = center of mass.

$$\Rightarrow x_2 = -\frac{m_1}{m_2} x_1 \quad ; \quad V(x_1 - x_2) = V\left(\left(1 + \frac{m_1}{m_2}\right) x_1\right) =: U(x_1)$$

set $m^* = 1 + m_1/m_2$. Let $x = x_1, r = |x|$.

$$\Rightarrow \text{The E-L eqⁿ reduced to 1 particle case: } m^* \ddot{x} = -\frac{\partial U(x)}{\partial x}$$

If L is SO(3) inv, then $V(x_1 - x_2) = V(|x_1 - x_2|)$, hence $-\nabla U(r) \parallel x$

"Angular momentum" $[x, p] = m[x, \dot{x}]$ is const since $[x, \dot{x}] = 0$.

i.e. central force field \Rightarrow plane motion.

$$L \text{ ind. of } t \Rightarrow E = \frac{1}{2} m^* |\dot{x}|^2 + U = \text{const (1st integral)}$$

Ex. Show (1) This is completely integrable (Get eqⁿ),

(2) \exists closed orbit for $U(r) = \frac{\alpha}{r}$ ($\alpha < 0, E < 0$), αr^2 ($\alpha > 0, E \geq 0$)
 i.e. periodic

(*) Remark: There are the only 2 cases s.t. \exists open set in phase space which is filled in by periodic orbits.

Hamiltonian Formalism : < From tangent bundle to cotangent bundle >

Defⁿ: Legendre transform: $(x, \dot{x}) \mapsto (x, p)$ is non-singular (i.e. loc. invertible)

if $\det \left(\frac{\partial^2 L}{\partial \dot{x}^i \partial \dot{x}^j} \right) \neq 0$. It is strongly non-singular (i.e. invertible)

if $p_\alpha = \frac{\partial L}{\partial \dot{x}^\alpha}(x, \dot{x})$ determines $\dot{x} = v(x, p)$ uniquely C^∞ , in the region.

Phase space for $L := \{(x, p)\}$. Energy E in this coord system $(x, p) : E(x, \dot{x}) = H(x, p)$

$H(x, p) := p_i v^i - L(x, v)$ is called Hamiltonian.

Thm: For L strongly non-singular

$$\left(\begin{array}{l} E-L \text{ Eq}^n: \dot{x} = \frac{\partial L}{\partial p} \text{ with } p = \frac{\partial L}{\partial \dot{x}} \\ \text{in coord } (x, \dot{x}) \end{array} \right) \simeq \left(\begin{array}{l} \text{Hamilton Eq}^n: \dot{x} = \frac{\partial H}{\partial p} \text{ \& } \dot{p} = -\frac{\partial H}{\partial x} \\ \text{in coord } (x, p) \end{array} \right).$$

Pf: \Rightarrow : $\frac{\partial H}{\partial p} = v + p \frac{\partial v}{\partial p} - \frac{\partial L}{\partial v} \frac{\partial v}{\partial p} = v = \dot{x}$

$-\frac{\partial H}{\partial x} = -p \frac{\partial v}{\partial x} + \frac{\partial L}{\partial x} + \frac{\partial L}{\partial v} \frac{\partial v}{\partial x} = \frac{\partial L}{\partial x} = \dot{p}$ *

\Leftarrow : Conversely, $\frac{\partial L}{\partial x} = \frac{\partial}{\partial x} (p \dot{x} - H) = \frac{\partial p}{\partial x} \dot{x} - \frac{\partial H}{\partial x} - \frac{\partial H}{\partial p} \frac{\partial p}{\partial x} = \dot{p}$

$L(x, \dot{x}) := p(x, \dot{x}) \dot{x} - H(x, p)$: $\frac{\partial L}{\partial \dot{x}} = \frac{\partial p}{\partial \dot{x}} \dot{x} + p - \frac{\partial H}{\partial p} \frac{\partial p}{\partial \dot{x}} = p$ *

Remark: In fact, Hamilton eqⁿ is exactly the E-L eqⁿ for

$L(x, p, \dot{x}, \dot{p}) := p \dot{x} - H(x, p)$ in the 2n dim'l phase space.

Cor. Along any trajectory $(x(t), p(t))$ of Hamilton eqⁿ, $H = \text{const.}$ (= energy E).

Thm (Maupertuis' Principle) let $H(x, p)$ be a Hamiltonian

Any $(x(t), p(t))$ extremizing $S = \int L dt = \int (p \dot{x} - H) dt$ also extremizes the truncated action $S_0 = \int p \dot{x} dt = \int p dx$ among curves of same energy.

Examples (a) $L = \frac{1}{2} m |\dot{x}|^2 - U(x)$. Then $H(x, p) = \frac{|p|^2}{2m} + U(x)$ where $p = m \dot{x}$.

\Rightarrow Any extremal of energy E has $|p| = \sqrt{2m(E - U(x))}$, is also extremal for

$S_0 = \int p \dot{x} dt = \int |p| |\dot{x}| dt = \int \sqrt{g_{ij} \dot{x}^i \dot{x}^j} dt$ where $g_{ij} = 2m(E - U(x)) \delta_{ij}$.
i.e. a geodesic but with non-natural parameter t .

(b) Fermat's principle on light in continuous isotropic medium:

"choose" $H(x, p) = c(x) |p|$. Among energy level E , $|p| = E/c(x)$

$\dot{x} = \frac{\partial H}{\partial p} = c(x) \frac{p}{|p|}$, so $|\dot{x}| = c(x)$ along the trajectory γ_0 .

Among all γ with E :

$p \dot{x} = |p| |\dot{x}| = \frac{E}{c(x)} |\dot{x}| \Rightarrow S_0 = \int p \dot{x} dt = E \int \frac{|\dot{x}|}{c(x)} dt = E \int \sqrt{g_{ij} \dot{x}^i \dot{x}^j} dt$

where $g_{ij} = \frac{1}{c^2(x)} \delta_{ij}$ (conformally Euclidean). γ_0 is a geodesic of it.

for anisotropic medium, the metric will not be conformally Euclidean.

Geometric Theory of phase Space (cotangent bundle $T^*\mathbb{R}^n$)

consider gradient flow $\dot{y} = \nabla f(y)$ where $\nabla f = df^\#$ i.e. $f_i = g^{ij} f_j$
 in $\mathbb{R}^m \ni (y^1, \dots, y^m)$ with non-deg metric g_{ij} (not nec. sym)

Lemma: for any $h(y)$, $\dot{h} := \frac{d}{dt} h(y(t)) = \lambda h(\nabla f) = \frac{\partial h}{\partial y_i} g^{ij} \frac{\partial f}{\partial y_j} = \langle dh, df \rangle$
 chain rule \downarrow
 $= \langle \nabla h, \nabla f \rangle$

Now set $m=2n$, $g_{ij} = -g_{ji}$
 $\Omega = \sum_{i < j} g_{ij} dy^i \wedge dy^j$ $g := \det g_{ij} \neq 0$ since $= h_i f_j = g_{ji} h^i f^j$ *

Lemma: $\frac{1}{n!} \Omega^n = \sqrt{g} dy^1 \wedge \dots \wedge dy^{2n}$, $g > 0$

$\Rightarrow \sqrt{g}$ is a polynomial of g_{ij} , called the "Pfaffian".

pf: for each $p \in \mathbb{R}^m$, work on $T_p \mathbb{R}^m \cong \mathbb{R}^m$. Linear algebra \Rightarrow

\exists basis $(x^1, p_1, x^2, p_2, \dots, x^n, p_n) = (z^1, \dots, z^{2n})$ st $y = Az$ has $A \in SO(2n)$

$\tilde{g}_{ij}(p) = A^T(g_{ij}(p))A = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \dots & \\ & & & \lambda_n \\ & & & & -\lambda_n & \\ & & & & & \dots \\ & & & & & & -\lambda_2 & \\ & & & & & & & -\lambda_1 \end{pmatrix}$, i.e. $\Omega = \sum_{i=1}^n \lambda_i dx^i \wedge dp_i$ at p

$\Rightarrow \Omega^n = \Omega \wedge \dots \wedge \Omega = n! \prod_{i=1}^n \lambda_i dx^1 \wedge dp_1 \wedge \dots \wedge dx^n \wedge dp_n$. Since $\tilde{g} = \lambda_1^2 \dots \lambda_n^2$, done *

Defⁿ: \mathbb{R}^{2n} with basis $(x^i, p_i)_{i=1}^n$ and $\Omega = dx^1 \wedge dp_1 + \dots + dx^n \wedge dp_n$

is called an abstract phase space, (x^i, p_i) the canonical coordinates.

in this space, the gradient flow for $f = H(x^1, p_1, \dots, x^n, p_n)$ becomes Hamilton's eqⁿ:

$$\dot{y} = \nabla H(y) \iff \dot{x}^i = \frac{\partial H}{\partial p_i} \quad \& \quad \dot{p}_i = -\frac{\partial H}{\partial x^i} \quad i=1, \dots, n.$$

The Poisson Bracket: on phase space

$$\text{Def: } \{f, g\} := \langle \nabla f, \nabla g \rangle \equiv g^{ij} f_i g_j \stackrel{\downarrow}{=} \sum_{i=1}^n \left(\frac{\partial f}{\partial x^i} \frac{\partial g}{\partial p_i} - \frac{\partial f}{\partial p_i} \frac{\partial g}{\partial x^i} \right).$$

The defⁿ applies to any g_{ij} .

Thm: (i) $\{f, g\}$ is \mathbb{R} -bilinear, skew-sym,

(ii) Jacobi identity,

(iii) $\{fs, h\} = f\{s, h\} + s\{f, h\}$, \Rightarrow Get a Lie algebra of functions!

(iv) $\nabla \{f, g\} = -[\nabla f, \nabla g]$.

pf: (i), (iii) by defⁿ, (iv) \Rightarrow (ii). Only (iv) is important! But it is straight forward *

Thm: Given g_{ij} skew-sym. The Poisson bracket on $C^\infty(\mathbb{R}^{2n})$ forms a Lie algebra
 $\Leftrightarrow \Omega$ is symplectic, i.e. $d\Omega = 0 \Leftrightarrow$ locally an abstract phase space. (Darboux thm)

pf (sketch): Jacobi for $\{, \}$ $\Leftrightarrow g^{ik} \partial_k g^{jl} (\partial_p f_1 \partial_i f_2 \partial_j f_3 + [2,3,1] + [3,1,2]) = 0$

$$\Leftrightarrow \partial_p f_1 \partial_i f_2 \partial_j f_3 (g^{ik} \partial_k g^{jl} + g^{ik} \partial_k g^{jl} + g^{jk} \partial_k g^{il}) = 0 \quad \forall f_1, f_2, f_3$$

$$\text{sum over } g_{rp} g_{sj} g_{ti} \Leftrightarrow \partial_r g_{ts} - \partial_s g_{tr} + \partial_t g_{sr} = 0 \quad \text{i.e. } (d\Omega)_{rst} = 0 \quad *$$

Now any $f(x, p)$ leads to $\dot{f} = \langle \nabla f, \nabla H \rangle = \{f, H\}$ along $\dot{y} = \nabla H(y(t))$.

Defⁿ: f is an integral function if $\dot{f} = 0$ along any trajectory, i.e. $\{f, H\} = 0$.

Cor: Int. functions form a Lie subalgebra.

Proof of Darboux Thm:

Step 1. (Moser's lemma) ω_t symplectic. $\frac{d}{dt} \omega_t = d\sigma_t \Rightarrow \Psi_t^* \omega_t = \omega_0$ for some Ψ_t local diffeomorphism

pf: If \exists time-depend. v.f. X_t generates Ψ_t then must have

$$0 = \frac{d}{dt} \omega_0 = \frac{d}{dt} \Psi_t^* \omega_t = \Psi_t^* \left(\frac{d}{dt} \omega_t + L_{X_t} \omega_t \right) = \Psi_t^* (d\sigma_t + d(L_{X_t} \omega_t)) \quad \Delta: \text{Ex.}$$

ie. $L_{X_t} \omega_t = -\sigma_t + d\tau$. can solve X_t since ω_t is non-degenerate.

Step 2. At $T_p S$, ω is equiv to ω_0 , the standard one.

set $\omega_t = t\omega + (1-t)\omega_0 = d(t\sigma + (1-t)\sigma_0)$ by Poincaré lemma

need to pick $U \ni p$ small st ω_t is non-degenerate on $U \forall t \in [0,1]$ *

Comparison in Riemann and symplectic geometry: symplectic has only "global inv".

Thm A: Along any integral curve, $\mathcal{L} = L \circ H \mathcal{L} = 0$.

pf: $L \circ H \mathcal{L} = (L \circ H d + d L \circ H) \mathcal{L} = d L \circ H \mathcal{L} = (d L \circ H \mathcal{L})(X, Y)$

(Ex. 25.3 #3) Cartan's homotopy formula $= X \mathcal{L} \circ H \mathcal{L}(Y) - Y \mathcal{L} \circ H \mathcal{L}(X) - \mathcal{L} \circ H \mathcal{L}(X, Y)$
 $= X \mathcal{L}(H, Y) - Y \mathcal{L}(H, X) - \mathcal{L}(H, X, Y)$

notice: $\mathcal{L}(H, Y) = g_{ij} \dot{y}^i h^j = -dh(Y) = Yh = -X \mathcal{L}(H) + Y \mathcal{L}(H) + (X, Y)(H) = 0$ *

Cor (Liouville): The vol. form $\sqrt{g} dy^1 \wedge \dots \wedge dy^{2n} = \frac{1}{n!} \mathcal{L}^n$ is inv. under any Hamiltonian system. (pf: $L \circ H \mathcal{L}^n = 0$ by Leibniz' rule)

Defⁿ: Canonical Transformation $\bar{\mathbb{F}}$ are transf. preserving \mathcal{L} : $\bar{\mathbb{F}}^* \mathcal{L} = \mathcal{L}$.

Thm B: Every local 1-parameter group of canonical transf. $\bar{\mathbb{F}}_t$ (set $\mathbb{F} = \frac{d}{dt} \bar{\mathbb{F}}_t \Big|_{t=0}$) is locally generated by a Hamiltonian v.f. $\mathbb{F} = \nabla H$ for some H .

pf: $\bar{\mathbb{F}}_t^* \mathcal{L} = \mathcal{L} \Rightarrow 0 = L_X \mathcal{L} = L_{X^*} \mathcal{L} + d L_X \mathcal{L} = d L_X \mathcal{L}$

Poincaré lemma $\Rightarrow L_X \mathcal{L} = dH$ locally, ie. $X = \nabla H$ *

Remark: For simple proofs of Thm A, B using Darboux chart, see the textbook.

Lie Algebra of symplectic transformations

locally, Darboux chart $\Rightarrow X = \nabla H = \left(\frac{\partial H}{\partial p_1}, -\frac{\partial H}{\partial x^1}, \dots, \frac{\partial H}{\partial p_n}, -\frac{\partial H}{\partial x^n} \right)$

Defⁿ: Linear canonical transf. on \mathbb{R}^{2n} is called symplectic transf.

ie. \exists a matrix $K \in M_{2n}(\mathbb{C})$ with $X(z) = Kz$ (linear vector field)

$$\Rightarrow H = \frac{1}{2} \sum_{i,j=1}^n (a_{ij} x^i x^j + 2b_{ij} x^i p_j + c_{ij} p_i p_j) \Rightarrow K = \begin{pmatrix} B^T & C \\ -A & -B \end{pmatrix}$$

$$A = A^T, C = C^T$$

under coord. $(x^1, \dots, x^n, p_1, \dots, p_n)$

Cor. This Lie algebra is exactly $\mathfrak{sp}(n) = \text{Lie } Sp(n)$, (see § 14.3, Defⁿ 14.3.5)

$Sp(n) \subset GL(n, \mathbb{H})$ which preserve $\langle, \rangle_{\mathbb{H}}$ in $\mathbb{H}^n \cong \mathbb{C}^{2n}$ $z = a + bi + cj + dk = (a+bi) + (c+di)j$

$$\langle z_1, z_2 \rangle := \sum_{k=1}^n z_1^k \bar{z}_2^k = \sum (x_1^k + y_1^k j) \overline{(x_2^k + y_2^k j)} = \sum (x_1^k x_2^k + y_1^k y_2^k) + (y_1^k x_2^k - x_1^k y_2^k) j$$

ie. $Sp(n) \cong \{ T \in U(2n) \mid T \text{ preserves the skew sym form } \sum_k (y_1^k x_2^k - x_1^k y_2^k) \}$ *

Lagrange Surface

Defⁿ: Extended phase space. Given Hamiltonian system via $H(x, p) : \dot{y} = \nabla H(y)$

Had seen for $\varphi(x, p, t)$, $\dot{y} = \frac{\partial \varphi}{\partial t} + \langle \nabla \varphi, \nabla H \rangle \Rightarrow \dot{E} = \dot{H} = \frac{\partial H}{\partial t} + \langle \nabla H, \nabla H \rangle$

If $H(x, p, t)$ depends on t , set $x^{n+1} = t$, $p_{n+1} = E$, $\tilde{H}(x, p, t, E) := H(x, p, t) - E$

then $\frac{\partial \tilde{H}}{\partial p_{n+1}} = \frac{\partial H}{\partial E} = -1 = -\dot{t}$ Notice that (t, E) are new variables!

$\frac{\partial \tilde{H}}{\partial x^{n+1}} = \frac{\partial H}{\partial t} = \dot{E}$ with $\tilde{\Omega} := \Omega - dt \wedge dE = \sum_{i=1}^n dx^i \wedge dp_i - dt \wedge dE$

Defⁿ: A surface Γ of $\frac{1}{2}$ -dim. is Lagrangian if $\Omega|_{\Gamma} \equiv 0$. Eg. $(x=0)$ or $(p=0)$

Hence for $\tilde{\Omega}$ a canonical transf. $\tilde{\Omega}(\Gamma)$ is also Lagrangian. $(x, p) \mapsto (p, -x)$

Typical Example: In Darboux chart: $T^*\mathbb{R}^n$, $\Gamma := (x, d\varphi) = (x^i, p_i = \frac{\partial \varphi}{\partial x^i})$

then $\sum dx^i \wedge dp_i = \sum dx^i \wedge d(\frac{\partial \varphi}{\partial x^i}) = \sum \frac{\partial^2 \varphi}{\partial x^i \partial x^j} dx^i \wedge dx^j = 0$.

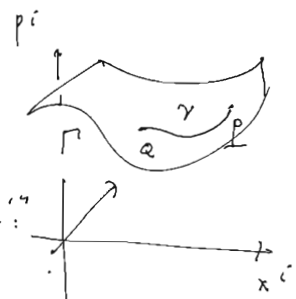
Thm: Every Lagrangian surface Γ is locally the graph of a differential.

Pf: Locally $\Omega = d\eta$ (eg. $\eta = -p_i dx^i$) now $d\eta|_{\Gamma} = 0$ or $d(\eta|_{\Gamma}) = 0$

$\Rightarrow \eta|_{\Gamma} = d\varphi$ for some function φ on Γ .

suppose that p_i on Γ can be parametrized by x^1, \dots, x^n ,

Then $d\varphi = \frac{\partial \varphi}{\partial x^i} dx^i = \eta|_{\Gamma} = -p_i dx^i \Rightarrow p_i = -\frac{\partial \varphi}{\partial x^i}$ *



For classical Hamilton system via H , this gives the alternative defⁿ:

Cor: (1) For phase space, Γ^n is Lagrangian iff $\forall q \in \Gamma^n$ the

truncated action $S_0(p) = \int_{\gamma} p dx$ is locally indep of $\gamma \subset \Gamma^n$ joining q, p

(2) For extended phase space, Γ^{n+1} is Lagrangian iff $\forall q \in \Gamma^{n+1}$, the

truncated action $S_0(p) = \int_{\gamma} (p dx - E dt)$ is locally indep of $\gamma \subset \Gamma^{n+1}$ joining q, p

Defⁿ: In case (2), $S(x, t) := S_0(p)$ is called the action of the trajectory bundle.

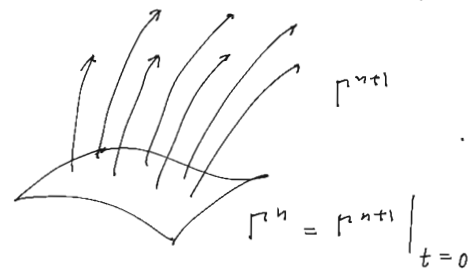
and the eqⁿ $\frac{\partial S}{\partial t} + E(x, p, t) = \frac{\partial S}{\partial t} + H(x, \frac{\partial S}{\partial x}, t) = 0$ is the Hamilton-Jacobi eqⁿ.

Thm: Given $H(x, p)$ indep of t . $S := \{H = \text{const } E_0\}$

(i) $\nabla H = (\frac{\partial H}{\partial p}, -\frac{\partial H}{\partial x}) \in T_p S$, (ii) $\langle \nabla H, \zeta \rangle = 0 \forall \zeta \in T_p S$

(iii) if Γ^n is Lagrangian and with const H , then $\nabla H \in T_p S$

and, any trajectory touching Γ^n lies in Γ^n entirely.



Pf: (i) + (ii): By defⁿ: $\langle \nabla H, \zeta \rangle = dH(\zeta) = 0$ on $T_p S$,

in particular for $\zeta = \nabla H$. since (i) is skew-sym.

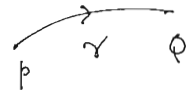
(iii): $T_p \Gamma^n$ has max dim of Lagrangian directions, (ii) $\Rightarrow \nabla H \in T_p \Gamma^n$

if γ is a trajectory $\gamma(0) = p$, then $\dot{\gamma} = \nabla H \in T_p \Gamma^n \Rightarrow \gamma \subset \Gamma^n$ *

Remk: If $H(x, p, t)$ dep on t , Thm can be applied to extended phase space on Γ^{n+1} .

2nd Variations (mainly for geodesics)

Let γ satisfy E-L eqⁿ for $S[\gamma] = \int_{\gamma} L(x, \dot{x}) dt$
for vector fields ξ, η along γ , $\xi = 0$ at P, Q



$$(*) \quad G_{\gamma}(\xi, \eta) := \frac{\partial^2}{\partial \lambda \partial \mu} S[\gamma + \lambda \xi + \mu \eta] \Big|_{\lambda=0, \mu=0}$$

γ minimum $\Rightarrow G_{\gamma}(\xi, \xi) \geq 0$, and $G_{\gamma}(\xi, \xi) > 0 \quad \forall \xi \neq 0 \Rightarrow \gamma$ is minimum.

Lemma: $G_{\gamma}(\xi, \eta) = - \int_a^b (J_{ij} \xi^j) \eta^i dt$ where J is the Jacobi diff. operator

$$J_{ij} \xi^j := - \left(\frac{\partial^2 L}{\partial x^i \partial x^j} \xi^j + \frac{\partial^2 L}{\partial x^i \partial \dot{x}^j} \dot{\xi}^j \right) + \frac{d}{dt} \left(\frac{\partial^2 L}{\partial \dot{x}^i \partial x^j} \xi^j + \frac{\partial^2 L}{\partial \dot{x}^i \partial \dot{x}^j} \dot{\xi}^j \right).$$

pf: let $y(t) = x(t) + \lambda \xi(t)$, then

$$(*) = \frac{\partial}{\partial \lambda} \Big|_{\lambda=0} \int_a^b \left(\frac{\partial L}{\partial y^i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{y}^i} \right) \eta^i dt = \int_a^b (J_{ij} \xi^j) \eta^i dt \quad *$$

Defⁿ: ξ is called a Jacobi field (wrt. S) if " $J\xi \equiv 0$ ". Will study geodesics in more details.

Thm: For $S[\gamma] = \int_a^b \frac{1}{2} g_{ij} \dot{x}^i \dot{x}^j dt$ with γ a geodesic

$$G_{\gamma}(\xi, \eta) = - \int_a^b \left(\nabla_{\dot{\gamma}}^2 \xi^k + R_{jli} \dot{x}^j \dot{x}^i \xi^l \right) \eta^m g_{km} dt = - \int_a^b \langle \nabla_T^2 \xi + R(\xi, T)T, \eta \rangle dt$$

$=: J\xi$

pf: $(*) = \frac{\partial}{\partial \lambda} \Big|_{\lambda=0} \int_a^b \left(\ddot{y}^k + \Gamma_{ij}^k \dot{y}^i \dot{y}^j \right) \eta^m g_{km} dt$ where $y(t) = x(t) + \lambda \xi(t)$

$$= - \int_a^b \left(\ddot{\xi}^k + \underbrace{\frac{\partial \Gamma_{ij}^k}{\partial x^l} \xi^l \dot{x}^i \dot{x}^j + 2 \Gamma_{ij}^k \dot{\xi}^i \dot{x}^j \right) \eta^m g_{km} dt \quad \text{let } T = \dot{\gamma} = \dot{x}^i \partial_i$$

Now $\nabla_T \xi^k = \dot{\xi}^k + \Gamma_{li}^k \xi^l \dot{x}^i$

$$\nabla_T^2 \xi^k = \ddot{\xi}^k + \frac{d}{dt} (\Gamma_{li}^k \xi^l \dot{x}^i) + \Gamma_{ps}^k \dot{x}^s (\dot{\xi}^p + \Gamma_{li}^p \xi^l \dot{x}^i)$$

$$\underbrace{\frac{\partial \Gamma_{li}^k}{\partial x^j} \xi^l \dot{x}^i \dot{x}^j + \Gamma_{li}^k \dot{\xi}^l \dot{x}^i + \Gamma_{li}^k \xi^l \ddot{x}^i}$$

at each, pick Riem normal cov get $\Gamma_{ij}^k(p) = 0$

$$(*) = - \int_a^b \left(\nabla_T^2 \xi^k + R_{ijl} \xi^l \dot{x}^i \dot{x}^j \right) \eta^m g_{km} dt$$

Cor. For $(g_{ij}) > 0$, a geodesic is of shortest length when Q is close to P .

pf: $G_{\gamma}(\xi, \xi) = - \int_0^l \langle \nabla_T \nabla_T \xi, \xi \rangle + \langle R(\xi, T)T, \xi \rangle = \int_0^l \left(|\nabla_T \xi|^2 - R(\xi, T, T, \xi) \right) dt$

Ex 36.2 \Rightarrow This is > 0 if $\xi \neq 0$ and l small *

Defⁿ: P, Q are conjugate pts along γ if $J\xi \neq 0, \xi(p) = \xi(q) = 0, J\xi = 0$ (Jacobi field).

Thm. For $(g_{ij}) > 0$: (1) $G_{\gamma}(\xi, \eta)$ is non-degenerate $\Leftrightarrow \gamma(0)$ and $\gamma(l)$ are not conjugate.

(2) γ is no longer minimal beyond the 1st conj pt Q of P .

pf: (1) is easy. (2) By Ex 36.1, use broken v.f. ξ Jacobi on \overline{PQ} :



Q: Ex: Why min energy \Leftrightarrow min arclength?

Higher Dimensional Variations

$D \subset \mathbb{R}^n$, ∂D piece-wise smooth $f: D \rightarrow \mathbb{R}^N \in C^\infty$

Lagrangian $L = L(x^\beta; p^i; q_\alpha^j)$
 $n + k + nN$

Eg. (area of a surface) $r: D \rightarrow \mathbb{R}^3$

$$I[f] = \int_D L(x^\beta; f^i; f_\alpha^j) d\sigma$$

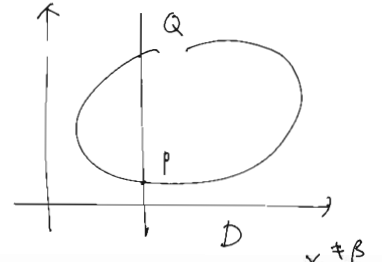
$$A[f] = \int_D \sqrt{EG-F^2} du dv = \int_D \sqrt{|r_1|^2 |r_2|^2 - (r_1 \cdot r_2)^2} du dv$$

Thm: $\eta|_{\partial D} = 0 \nRightarrow I'[f](\eta) = \int_D \frac{\delta I}{\delta f^i} \eta^i d\sigma$ where $\frac{\delta I}{\delta f^i} := \frac{\partial L}{\partial f^i} - \sum_{\alpha=1}^n \frac{\partial}{\partial x^\alpha} \left(\frac{\partial L}{\partial f_\alpha^i} \right)$

pf: $\frac{d}{d\epsilon} I[f + \epsilon \eta] \Big|_{\epsilon=0} = \int_D \frac{d}{d\epsilon} L(x, f + \epsilon \eta, Df + \epsilon D\eta) \Big|_{\epsilon=0} d\sigma$

$$= \int_D \left(\frac{\partial L}{\partial f^i} \eta^i + \frac{\partial L}{\partial f_\alpha^i} D_\alpha \eta^i \right) d\sigma = \int_D \frac{\partial L}{\partial f^i} \eta^i + \sum_{\alpha=1}^n \frac{\partial L}{\partial f_\alpha^i} D_\alpha \eta^i d\sigma$$

$$= \int_D \left\{ \frac{\partial L}{\partial f^i} - \sum_{\alpha=1}^n \frac{\partial}{\partial x^\alpha} \left(\frac{\partial L}{\partial f_\alpha^i} \right) \right\} \eta^i d\sigma \quad *$$



Energy-Momentum Tensor:

If $L(p^i, q_\alpha^i)$ does not involve x^1, \dots, x^n . Then

$$T_j^k := f_j^i \frac{\partial L}{\partial f_i^k} - \delta_j^k L \quad \text{satisfies} \quad \sum_k \frac{\partial}{\partial x^k} T_j^k = 0 \quad (k \leftrightarrow \text{tangent vector component } f_j^k)$$

pf: $\partial_k T_j^k = \partial_k f_j^i \frac{\partial L}{\partial f_i^k} + f_j^i \frac{\partial}{\partial x^k} \left(\frac{\partial L}{\partial f_i^k} \right) - \delta_j^k \frac{\partial L}{\partial f_i^k} \partial_k f_i^i - \delta_j^k \frac{\partial L}{\partial f_i^k} \frac{\partial^2 f_i^i}{\partial x^k \partial x^k} = 0 \quad *$

Rmk: If $n=1$, then $x^1 = t$ and this reduces to energy E . For $n \geq 2$ \exists many components!

Def: If D has metric g_{ij} then $T_{ik} := g_{kl} T_i^l$. Also, $T^{ik} := g^{ij} T_j^k$.

First Simple Example: Minkowski space-time $\mathbb{R}^{1,3}$.

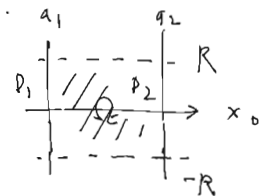
Symmetry: If $T^{ik} \neq T^{ki}$, choose $\psi^{ikl} = -\psi^{ilk}$ st $\sum \frac{\partial}{\partial x^l} \psi^{ikl} = -\frac{1}{2} (T^{ik} - T^{ki})$

(*) Then $\tilde{T}^{ik} := T^{ik} + \sum \frac{\partial}{\partial x^l} \psi^{ikl} = \frac{1}{2} (T^{ik} + T^{ki})$ and $\sum_k \frac{\partial}{\partial x^k} \tilde{T}^{ik} = 0$

Def: The momentum 4 vector $p = (p^0, p^1, p^2, p^3)$ for L is, under fast decay assumption, $p^i := \frac{1}{c} \int_{x^0=a} T^{ik} dS_k = \frac{1}{c} \int_{x^0=a} T^{i0} dS_0$; ($dS_k = \frac{1}{6} \epsilon_{ijmkl} dx^i \wedge dx^j \wedge dx^m \wedge dx^l$)

Prop: If $T^{ik} = O(R^{-(3+\epsilon)})$ then p is conserved (indep of const a)

pf: $0 = \int_{\mathcal{R}} \sum_k \frac{\partial}{\partial x^k} T^{ik} d\sigma = \int_{D_2 - D_1 + \Pi_R} T^{ik} dS_k$. Let $R \rightarrow \infty$ *



Lemma: p is inv. under (*). Hence may assume $T^{ik} = T^{ki}$.

pf: $\int_{x^0=a} \partial_\ell \psi^{ikl} dS_k = \int_{x^0=a} \text{div}(\psi^{i01}, \psi^{i02}, \psi^{i03}) dx^1 \wedge dx^2 \wedge dx^3$

Cor: Angular momentum: $= \lim_{R \rightarrow \infty} \int_{S_R} \langle \psi^{i0}, \vec{n} \rangle dA = 0$ * since $\psi^{i00} = 0$ skew-sym

If $T^{ik} = T^{ki}$, then $M^{ik} := \int x^i dp^k - x^k dp^i = \frac{1}{c} \int_{x^0=a} (x^i T^{kl} - x^k T^{il}) dS_l$

\vec{m} also indep of a . (Same pf as Prop, via $\partial_\ell (x^i T^{kl} - x^k T^{il}) = T^{ki} - T^{ik} = 0$.)

Examples on HD Variational Problems

I. Hodge Theory on compact surfaces S with $\partial S = \emptyset$

de Rham cohomology $H_{dR}^k(S, \mathbb{R}) :=$ closed k forms / exact k forms

in each class $[\omega] = \{ \omega + d\eta, \eta \in \Lambda^{k-1}(S) \}$ with $d\omega = 0$

If ω minimize norm: $\|\omega\|^2$ defined via $(\alpha, \beta) := \int \alpha \wedge * \beta$

$$\langle \omega + \epsilon d\eta, \omega + \epsilon d\eta \rangle = \|\omega\|^2 + 2\langle \omega, d\eta \rangle \epsilon + \|d\eta\|^2 \epsilon^2 \geq \|\omega\|^2 \quad \forall \epsilon \text{ small}$$

$$\Rightarrow 0 = \langle \omega, d\eta \rangle = \langle \delta \omega, \eta \rangle \quad \forall \eta \Rightarrow \delta \omega = 0. \text{ In fact } \delta \text{ hold if } d\eta \neq 0$$

Also the minimizer is unique if it exists.

Then (Hodge) (1) $H_{dR}^k(S, \mathbb{R}) \simeq \mathbb{H}^k$ by harmonic forms $\Delta \omega = 0$ ($\Leftrightarrow d\omega = 0 = \delta \omega$)

$$(2) \dim \mathbb{H}^k < \infty; \Lambda^k(S) = \mathbb{H}^k \oplus \Delta \Lambda^k(S) = \mathbb{H}^k \oplus d\Lambda^{k-1} \oplus \delta \Lambda^{k+1}.$$

Sketch: (1) har form exists and C^∞ by elliptic PDE theory! Also $\dim \mathbb{H}^k < \infty$.

(2) Hence Δ has a spectral resolution $\mathbb{H} \oplus \mathbb{H}_{\lambda_i > 0}$, $G := \Delta^{-1} \oplus \mathbb{H}_{\lambda_i > 0}^{-1}$ Green op.

$$\lambda_i \rightarrow \infty \text{ as } i \rightarrow \infty \Rightarrow G \text{ is a cpt operator } \Rightarrow I = \mathbb{H} \oplus \Delta G$$

Cov. $\Delta \omega = \varphi$ in Λ^k if solvable ($\Leftrightarrow \varphi \in \mathbb{H}^\perp$, i.e. $\langle \varphi, \psi \rangle = 0 \quad \forall \text{ har. } \psi$)

II. The Equations of an Electromagnetic Field, on $\mathbb{R}^{1,3}$

$$\text{Action } S = S_m + S_{mf} + S_f = - \int m c d\sigma - \frac{1}{c} \int A_i j^i d\sigma - \frac{1}{16\pi c} \int F_{ik} F^{ik} d\sigma$$

$$\text{Focus on "fields"} \Rightarrow S[A] = \int L(A_i, A_{ij}) d\sigma; \quad A_{ij} = \partial_j A_i - \partial_i A_j \quad \partial_i A_k - \partial_k A_i$$

$A = A_i dx^i \in \Lambda^1(\mathbb{R}^{1,3})$ is the "vector potential"; $F = dA \in \Lambda^2(\mathbb{R}^{1,3})$

At ∞ , L suitably decay to 0 st. the integral converges, but not A !

$$\Rightarrow S[A] = - \frac{1}{c} \int \left(\frac{1}{c} A(j) + \frac{1}{16\pi} (F|F) \right) d\sigma \quad (F|F) d\sigma = F \wedge * F$$

$$S[A + \epsilon \eta] = S[A] - \epsilon \int \left(\frac{1}{c} \langle \eta, j^b \rangle + \frac{1}{8\pi} \langle d\eta, F \rangle \right) d\sigma - \frac{\epsilon^2}{c} \frac{1}{16\pi} \int |F|^2 d\sigma$$

$$\text{take extremal, in fact minimal } \Leftrightarrow \frac{1}{8\pi} \delta F = - \frac{1}{c} j^b$$

(Recall) under the correspondence $x^0 = ct$, and

$$F = F_{ij} dx^i \wedge dx^j = E_\alpha dx^0 \wedge dx^\alpha + H^1 dx^2 \wedge dx^3 + H^2 dx^3 \wedge dx^1 + H^3 dx^1 \wedge dx^2 \sim \begin{pmatrix} 0 & E_1 & E_2 & E_3 \\ -E_1 & 0 & H^1 & -H^2 \\ -E_2 & H^1 & 0 & H^3 \\ -E_3 & H^2 & H^3 & 0 \end{pmatrix}$$

$$\Leftrightarrow \text{Maxwell eq's } \begin{cases} \delta F = 0 \text{ (trivial)} \Leftrightarrow \text{curl } E = \frac{1}{c} \frac{\partial H}{\partial t}, \text{ div } H = 0 \\ \delta F = -\frac{8\pi}{c} j^b \Leftrightarrow \text{curl } H = -\frac{1}{c} \frac{\partial E}{\partial t} + \frac{4\pi}{c} \vec{j}, \text{ div } E = 4\pi \rho \end{cases}$$

Energy-momentum tensor (here stress tensor) where $j = (c\rho, \vec{j})$

for free space ($j=0$): notice $\delta F \neq 0$ in contrast to Hodge theory (why?)

$$T^{ik} = g^{im} A_{\lambda m} \frac{\partial L}{\partial A_{\lambda k}} - g^{ik} L = -\frac{j^{im}}{4\pi c} \frac{\partial A_\lambda}{\partial x^m} F^{k\lambda} + \frac{g^{ik}}{16\pi c} |F|^2 \xrightarrow{\text{symmetrized}} \frac{1}{4\pi c} \left(-g^{im} F_{ml} F^{kl} + g^{ik} |F|^2 \right)$$

via Maxwell eq's $\partial_l F^{kl} = 0$

Examples of HD variational problems

III. Hilbert - Einstein action in general relativity (Hilbert 1915, 1 day earlier)

$$S = \int R d\sigma \quad R = g^{ij} R_{ij} \quad d\sigma = \sqrt{|g|} dx$$

$$(i) \quad R_{ij}^k = \partial_i \Gamma_{j\lambda}^k - \partial_j \Gamma_{i\lambda}^k + \Gamma_{i\mu}^k \Gamma_{j\lambda}^\mu - \Gamma_{j\mu}^k \Gamma_{i\lambda}^\mu$$

$$\delta R_{ij}^k = \partial_i \delta \Gamma_{j\lambda}^k - \partial_j \delta \Gamma_{i\lambda}^k + \delta \Gamma_{i\mu}^k \Gamma_{j\lambda}^\mu + \Gamma_{i\mu}^k \delta \Gamma_{j\lambda}^\mu - \delta \Gamma_{j\mu}^k \Gamma_{i\lambda}^\mu - \Gamma_{j\mu}^k \delta \Gamma_{i\lambda}^\mu$$

Key point I: $\delta \Gamma_{ij}^k$ is a (1,2) tensor.

$$\Rightarrow \delta R_{ij}^k = \nabla_i \delta \Gamma_{j\lambda}^k - \nabla_j \delta \Gamma_{i\lambda}^k \quad \left(\begin{array}{l} \text{by direct observation, or} \\ \text{at a pt can assume } \Gamma_{ij}^k(p) = 0 \end{array} \right)$$

$$\delta R = \delta(g^{ij} R_{ij}) = \delta g^{ij} R_{ij} + g^{ij} (\nabla_i \delta \Gamma_{j\lambda}^i - \nabla_j \delta \Gamma_{i\lambda}^i)$$

$$(ii) \quad \delta g = \delta \det(g_{ij}) = g g^{ij} \delta g_{ij} \quad \nabla_i g^{ij} \delta \Gamma_{j\lambda}^i - \nabla_j g^{ij} \delta \Gamma_{i\lambda}^i \quad \left(\begin{array}{l} \text{Key point II:} \\ \text{cf. wikipedia} \end{array} \right)$$

this is the divergence term $\int (\dots) d\sigma = 0$ when $\delta g^{ij} \rightarrow 0$ at ∞ rapidly.

This holds in both Riem and pseudo Riem cases.

$$(i) + (ii) \Rightarrow \delta S = \int \delta(R \sqrt{|g|}) dx = \int \delta R d\sigma + R \delta \sqrt{|g|} dx = \int \left(R_{ij} - \frac{R}{2} g_{ij} \right) \delta g^{ij} d\sigma$$

The Euler-Lagrange eqⁿ $\frac{\delta S}{\delta g^{ij}} = R_{ij} - \frac{1}{2} R g_{ij} = 0$ gives Einstein eqⁿ for vacuum.

The most general situation is

$$S = \int \left(\frac{1}{2\kappa} (R - 2\lambda) - \mathcal{L}_M \right) d\sigma \quad \begin{array}{l} \lambda = \text{cosmological constant (never observed yet)} \\ \mathcal{L}_M = \text{Lagrangian describing matter} \end{array}$$

$$\kappa = \frac{8\pi G}{c^4} \quad G = \text{Newton's gravitational constant}$$

$$T_{ij} := \frac{-2}{\sqrt{|g|}} \frac{\delta(\sqrt{|g|} \mathcal{L}_M)}{\delta g^{ij}} = -2 \frac{\delta \mathcal{L}_M}{\delta g^{ij}} + g_{ij} \mathcal{L}_M \quad \text{is the Energy-Stress tensor}$$

$$\Rightarrow R_{ij} - \frac{R}{2} g_{ij} + \lambda g_{ij} = \frac{8\pi G}{c^4} T_{ij} \quad \text{Notice: The whole deduction does NOT use dim = 4! can be any } n \in \mathbb{N}.$$

$$\text{Taking trace get } R - 2R + n\lambda = \frac{8\pi G}{c^4} g^{ij} T_{ij} \quad \text{i.e. } R = n\lambda - \kappa^2 T_{ij}^i$$

of course for vacuum (with $\lambda = 0$) get $R \equiv 0$, hence $R_{ij} = 0$.

Rmk: The Ricci flat space are models for the space-time

In Super symmetric string theory, space-time $\cong \mathbb{R}^{1,3} \times M^6$

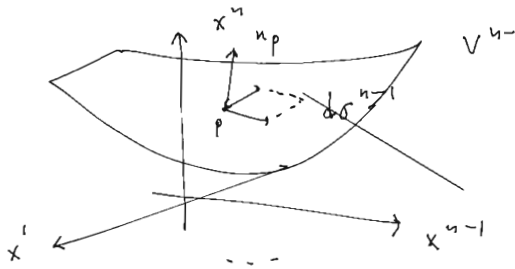
M a Ricci flat Kähler (= complex + symplectic) manifold of $\dim_{\mathbb{R}} M = 6$.

They are known as Calabi-Yau manifolds after YAU (1976) who

proved the Calabi conjecture: $M^6 \Leftrightarrow c_1(M) = 0$ the 1st Chern class.

These are called "inner spaces". Q: How to classify all of them?

IV. Soap films / minimal submanifolds



V^{n-1} graph of $x^n = f(x^1, \dots, x^{n-1})$
 $r_i = (0, \dots, 1, \dots, 0, f_i)$
 clearly $n_p = (-f_1, \dots, -f_{n-1}, 1)^T$
 $\nabla d\sigma^{n-1} = \frac{dx^1 \wedge \dots \wedge dx^{n-1}}{\cos(\langle e_n, n_p \rangle)} = \sqrt{1 + f_1^2 + \dots + f_{n-1}^2} dx^{n-1}$

$$S[f] = \int_D \sqrt{1 + \sum_{i=1}^{n-1} f_i^2} dx^{n-1} \quad \text{E-L eq}^n: \sum_{i=1}^{n-1} \frac{\partial}{\partial x^i} \left(\frac{f_i}{\sqrt{1 + \sum f_i^2}} \right) = 0$$

More generally, can work for $r: D \subset \mathbb{R}^m \rightarrow (\mathbb{R}^n, h_{kl})$

$$S[r] = \int_D \sqrt{\langle r_i, r_j \rangle} d^m u = \int_D \sqrt{g} du$$

$$\delta S = \int_D \frac{g^{ij} \delta g_{ij}}{2\sqrt{g}} du = \int_D d^m \sigma \, g^{ij} h_{kl} r_i^k (\delta r^l)_j$$

$$= \int_D d^m \sigma \left(g^{ij} h_{kl} r_i^k \delta r^l \right)_j - \left(g^{ij} h_{kl} r_i^k \right)_j \delta r^l$$

may use covariant der.
may assume normal variations $\delta r \perp TV$

$$= - \int_D d^m \sigma \, g^{ij} \langle \nabla_j r_i, \delta r \rangle = 0 \quad \forall \delta r \Leftrightarrow \vec{H} := (g^{ij} \nabla_j r_i)^N \equiv 0$$

this is the mean curv. vector.

Def: 2nd fund. form $\mathbb{I}(v, w) := (\nabla_v w)^N \in N_p$

- (i) $\mathbb{I}(w, v) = \mathbb{I}(v, w)$ since $(\nabla_w v - \nabla_v w)^N = [w, v]^N = 0$
- (ii) function linear: $\mathbb{I}(fv, w) = f \mathbb{I}(v, w)$, hence also in w by (i)
- So in general $\nabla_{r_i} r_j = \nabla_{r_j}^T r_i + \nabla_{r_i}^N r_j \xrightarrow{\mathbb{I}(r_i, r_j)}$, $\vec{H} := \text{Tr } \mathbb{I}$ trace.

$V^2 \hookrightarrow \mathbb{R}^3$ is very special: can choose $(u^1, u^2) = (u, v)$ be isothermal coord.
 i.e. v is conformal: $\langle r_1, r_1 \rangle = \langle r_2, r_2 \rangle$; $\langle r_1, r_2 \rangle = 0$

- Prop: (a) $\vec{H} = (\Delta r)^N$ for general cases.
- (b) For isothermal coord $dx^2 = \lambda (du^2 + dv^2)$ in \mathbb{R}^3 , $\vec{H} = \Delta r = \frac{1}{\lambda} (r_{uu} + r_{vv})$.

pf: (a) $\vec{H} = \mathbb{I}(g^{ij} r_j, r_i) = \frac{1}{\sqrt{g}} (\nabla_j g^{ij} \sqrt{g} \partial_i r)^N$ since $(r_i)^N = 0$ (∇ function-linear)
 $= \frac{1}{\sqrt{g}} (\partial_j g^{ij} \sqrt{g} \partial_i r)^N$ same reason.

(b) Need to show $\langle \Delta r, r_i \rangle = 0$: $\langle r_1, r_1 \rangle = \langle r_2, r_2 \rangle \xrightarrow{\partial_1} \langle r_{11}, r_1 \rangle = \langle r_{12}, r_2 \rangle$
 $\langle r_1, r_2 \rangle = 0 \xrightarrow{\partial_2} \langle r_{12}, r_2 \rangle + \langle r_1, r_{22} \rangle = 0$
 sum $\Rightarrow \langle \Delta r, r_1 \rangle = 0$

Rmk: minimal graph is absolutely "local minimum".
 But in general the minimization problem is VERY HARD! (\exists ring pts)
 Plateau problem: given $\Gamma \subset \mathbb{R}^n$ Jordan curve, find minimal disk S with $\partial S = \Gamma$.
 Solved by Douglas-Rado in 1936. HD case \rightarrow Geom. Measure Theory.

Examples of Lagrangians from Quantum mechanics (relativistic)

on \mathbb{R}^{1+3} , $S(\varphi, \bar{\varphi}) = \int \left(\hbar^2 g^{ij} \frac{\partial \bar{\varphi}}{\partial x^i} \frac{\partial \varphi}{\partial x^j} - m^2 c^2 \bar{\varphi} \varphi \right) d\sigma = \int \Lambda(\varphi, \bar{\varphi}, \varphi_i, \bar{\varphi}_i) d\sigma$

view as independent complex scalar fields (wave functions)

$$\frac{\delta S}{\delta \varphi} = 0 = \frac{\delta S}{\delta \bar{\varphi}} = \frac{\partial \Lambda}{\partial \bar{\varphi}} - \sum_{i=0}^3 \frac{\partial}{\partial x^i} \left(\frac{\partial \Lambda}{\partial \bar{\varphi}_i} \right) = -m^2 c^2 \varphi - \hbar^2 g^{ij} \frac{\partial^2 \varphi}{\partial x^i \partial x^j}$$

$$= -(\hbar^2 \square + m^2 c^2) \varphi \quad \text{Klein-Gordon 1927: } \square := \frac{\partial^2}{\partial x_0^2} - \sum_{a=1}^3 \frac{\partial^2}{\partial x_a^2}$$

eg. The energy $T^{00} = g^{00} \left(\varphi_0 \frac{\partial \Lambda}{\partial \varphi_0} + \bar{\varphi}_0 \frac{\partial \Lambda}{\partial \bar{\varphi}_0} \right) - \Lambda \stackrel{\substack{\uparrow \\ \text{via G-L}}}{=} \hbar^2 \sum_{c=0}^3 \bar{\varphi}_c \varphi_c + m^2 c^2 \bar{\varphi} \varphi$
 (Λ is indep of x^i)

For α const, Λ is inv: $\varphi \mapsto e^{i\alpha} \varphi, \bar{\varphi} \mapsto e^{-i\alpha} \bar{\varphi}$ Q: Try get this from Noether's thm

get "Noether current" (inv. quantity) $J^a = i g^{ab} (\bar{\varphi} \varphi_b - \varphi \bar{\varphi}_b)$, ie. $\sum \frac{\partial J^a}{\partial x^a} = 0$

(check: $J^a = i g^{ab} (\bar{\varphi}_a \varphi_b + \bar{\varphi} \varphi_{ab} - \varphi_a \bar{\varphi}_b - \varphi \bar{\varphi}_{ab}) = i \frac{m^2 c^2}{\hbar^2} (-\bar{\varphi} \varphi + \varphi \bar{\varphi}) = 0$)

$Q := \int_{t=\text{const}} J^0 dx^1 dx^2 dx^3$ is called the "charge" of φ .

K-G: $(\square + (\frac{mc}{\hbar})^2) \varphi = 0$ has obvious solutions $e^{i\langle k, x \rangle}$ st. $\langle k, k \rangle = (\frac{mc}{\hbar})^2$.
↳ 4 vectors.

K-G: include electromagnetic field by the rule (for momentum operators)

$$p_a = i\hbar \frac{\partial}{\partial x^a} \mapsto p_a + \frac{e}{c} A_a = i\hbar \frac{\partial}{\partial x^a} + \frac{e}{c} A_a = i\hbar \left(\frac{\partial}{\partial x^a} - \frac{e}{c\hbar} i A_a \right) =: i\hbar \nabla_a^A$$

$$\Lambda \mapsto \Lambda(\varphi, \bar{\varphi}, A) = \hbar^2 g^{ab} \nabla_a^A \bar{\varphi} \nabla_b^A \varphi - m^2 c^2 \bar{\varphi} \varphi - \frac{1}{16\pi c} F_{ab} F^{ab}$$

$$= \hbar^2 |\nabla^A \varphi|^2 - m^2 c^2 |\varphi|^2 - \frac{1}{16\pi c} |F|^2 \quad F = dA$$

For $\alpha = \alpha(x)$ not const. The new action $S(\varphi, \bar{\varphi}, A)$ is inv under "Gauge transf":

$$(\varphi, \bar{\varphi}, A) \mapsto (e^{i\alpha} \varphi, e^{-i\alpha} \bar{\varphi}, A + \frac{c\hbar}{e} d\alpha) \quad (F \mapsto d(A + d\frac{c\hbar}{e} \alpha) = dA = F)$$

History: Schrodinger eqⁿ $i\hbar \frac{\partial}{\partial t} \varphi = \hat{H} \varphi$ arising from "quantization" of Hamiltonian formalism is NOT compatible with special relativity since \hat{H} is not a 1st order op. as in t. The K-G eqⁿ is relativistic, but it does NOT explain all particles (only those without "spin"). It was Dirac who solved it !!

Dirac (1928): Can we factorize (set $\hbar = c = 1$):

$$-(\square + m^2) = (i\gamma^a \frac{\partial}{\partial x^a} + m)(i\gamma^b \frac{\partial}{\partial x^b} - m) \quad ? \quad \text{ie. } \square = g^{ab} \partial_a \partial_b = \not{\partial}^2; \not{\partial} = \gamma^a \partial_a \quad ?$$

obviously, this is equiv. to $\gamma^a \gamma^b + \gamma^b \gamma^a = 2g^{ab}$ with $\gamma^a = \text{constant}$

This is impossible for numbers: $a \neq b \Rightarrow \gamma^a \gamma^b = 0 \Rightarrow$ say $\gamma^a = 0$, $\not{\partial}$ has no ∂_a !
 Solution: Need to allow γ^a being non-commutative (matrix) and φ being vectors.

Spinor Representations / Clifford Algebras

Lemma: Every algebra automorphism on $M(n, \mathbb{C})$ is inner $x \mapsto g x g^{-1}$.

pf: Let $P_i = E_{ii}$ clearly $P_i^2 = P_i$ $P_i P_j = 0$ for $i \neq j$ $P_1 + \dots + P_n = I_n = 1$
 if $h \in \text{Aut } M(n, \mathbb{C})$, then $P_i' := h(P_i)$ $i=1, \dots, n$ have the same property,

hence $\mathbb{C}^n \cong P_1'(\mathbb{C}^n) \oplus \dots \oplus P_n'(\mathbb{C}^n) =: \mathbb{C}_1' \oplus \dots \oplus \mathbb{C}_n'$

Similarly for E_{ij} define $E_{ij}' := h(E_{ij})$ which induces $\mathbb{C}_j' \cong \mathbb{C}_i'$

Let e_i' gen \mathbb{C}_i' then $e_i' := E_{i1}'(e_1')$ gen $\mathbb{C}_i' \neq e_1', \dots, e_n'$ is a basis

Define $g: \mathbb{C}^n \rightarrow \mathbb{C}^n$ by $g(e_i) = e_i'$. claim: $h(x) = g x g^{-1}$.

check $h(E_{ij}) = g E_{ij} g^{-1}$ i.e. $E_{ij}'(e_k) = g E_{ij} g^{-1}(e_k)$ clear.

but E_{ij} gen $M(n, \mathbb{C})$, hence done *

Def'n (Pauli matrix): $\sigma_0 = I_2$, $\sigma_1 = \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, $\sigma_2 = \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$, $\sigma_3 = \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

is a basis for $M(2, \mathbb{C})$. For $\sigma_1, \sigma_2, \sigma_3$, we compute

(i) $[\sigma_i, \sigma_j] = \sigma_i \sigma_j - \sigma_j \sigma_i = 2i \sigma_k$ for (i, j, k) even $\Rightarrow \langle \frac{\sigma_1}{2i}, \frac{\sigma_2}{2i}, \frac{\sigma_3}{2i} \rangle \cong so(3) \cong (\mathbb{R}^3, \times)$

(ii) $\{\sigma_i, \sigma_j\} = \sigma_i \sigma_j + \sigma_j \sigma_i = 2 \delta_{ij}$, Clifford algebra: $v^2 - \langle v, v \rangle = 0$ in $\otimes V$.

(Dirac matrix): $\gamma^0 = \begin{pmatrix} \sigma_0 & \\ & -\sigma_0 \end{pmatrix}$ ($\sigma_0 \cdot id$), $\gamma^1 = \begin{pmatrix} & \sigma_1 \\ -\sigma_1 & \end{pmatrix}$, $\gamma^2 = \begin{pmatrix} & \sigma_2 \\ -\sigma_2 & \end{pmatrix}$, $\gamma^3 = \begin{pmatrix} & \sigma_3 \\ -\sigma_3 & \end{pmatrix}$.

Satisfy (iii) $\{\gamma^a, \gamma^b\} = \gamma^a \gamma^b + \gamma^b \gamma^a = 2g^{ab}$ i.e. $v^2 - \langle v, v \rangle = 0$ in $\mathbb{R}^{1,3}$.

Digression: Had seen $so(3) \cong SU(2)/\pm 1 \cong S^3/\pm 1$ i.e. $\pi_1(so(3)) \cong \mathbb{Z}/2$

$so(n-1) \hookrightarrow so(n) \rightarrow S^{n-1} \neq \pi_1(so(n)) \cong \mathbb{Z}/2 \forall n \geq 3$

$Spin(n) :=$ the univ (double) cover of $so(n)$. Matrix repr of $Spin(n)$?

Cor: Spin repr of $Spin(1,3)$ on \mathbb{C}^4 is given by $O(1,3) \rightarrow SL(4, \mathbb{C})/\pm 1$ via

$\Lambda = (\lambda_i^a)$ acts on $M(4, \mathbb{C})$: $\gamma^a \mapsto \lambda_i^a \gamma^b$ as algebra automorphism

$\Rightarrow \Lambda \cdot x = g x g^{-1}$ for some $g = g(\Lambda) \in SL(4, \mathbb{C})/\pm 1$.

pf: γ^a satisfy (iii) as well. Since $1, \gamma^a, \gamma^a \gamma^b$ ($a < b$), $\gamma^a \gamma^b \gamma^c$ ($a < b < c$)

and $\gamma^0 \gamma^1 \gamma^2 \gamma^3$ span $M(4, \mathbb{C})$ (Ex. linear indep of these 16 matrices)

$\Rightarrow \Lambda \in \text{Aut}(M(4, \mathbb{C}))$, $\exists g(\Lambda)$ by Lemma, up to ± 1 *

Rmk: Can construct $so(3)$ case using σ_i in $M(2, \mathbb{C})$, check (i), (ii) for $\sigma_i' = \lambda_i^j \sigma_j$.

$so(4)$ case using $\gamma^0, i\gamma^1, i\gamma^2, i\gamma^3$ in $M(4, \mathbb{C})$.

Half spinor: $\mathbb{C}^4 \ni \Psi = \Psi_+ + \Psi_-$ according to the block decomp st $\gamma^1, \gamma^2, \gamma^3$ switch them.

Def'n: $\Psi^* := (\bar{\Psi}_1, \bar{\Psi}_2, \bar{\Psi}_3, \bar{\Psi}_4) = {}^t \Psi^{bar}$ and $\bar{\Psi} := \Psi^* \gamma^0$ is the Dirac conjugate.

Ex. The spinor repr of $O(1,3)$ is not unitary, but $\langle \Psi, \Phi \rangle := \Psi^* \gamma^0 \Phi = \bar{\Psi} \Phi$ is inv.

Finally we get Dirac's equation for 4-spinor: $\not{D} \Psi := (i \gamma^b \frac{\partial}{\partial x^b} - m) \Psi = 0$ *

Covariant derivative for the general case

$$\Psi(x) = (\Psi^1(x), \dots, \Psi^N(x)) : \mathbb{R}^4 \rightarrow \mathbb{R}^N \text{ (or } \mathbb{C}^N)$$

$A(x)$ \mathfrak{g} -valued 1-form $\mathfrak{g} = \text{Lie } G$, G some matrix gp in $GL(N, \mathbb{R})$

" $A_\alpha(x) dx^\alpha \in \Lambda^1(\mathfrak{g})$ Define $\nabla_\alpha \Psi = \frac{\partial \Psi}{\partial x^\alpha} + A_\alpha(x) \Psi$ " \mathbb{C}

in order that the result is inv. under G -action i.e. $\delta(\nabla_\alpha \Psi) = \nabla_\alpha(\delta \Psi)$

we require $\Psi \mapsto g(x)\Psi$ and $A_\alpha(x) \mapsto -\frac{\partial g}{\partial x^\alpha} g^{-1} + g A_\alpha g^{-1} = \tilde{A}_\alpha$
" $\tilde{\Psi}$ Gauge field " Gauge transf. $\{g(x)\} \in: \mathfrak{g}$ Base group

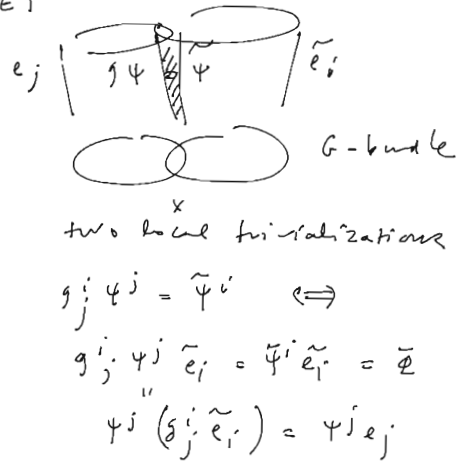
As in the case of TS

Now this is a vector bundle $\begin{matrix} E \\ \downarrow \\ S \end{matrix}$ and $\nabla : \Lambda^0(E) \rightarrow \Lambda^1(E)$

curvature (operator) $R(x, Y) := (\nabla_X \nabla_Y - \nabla_{[X, Y]})$

for $X, Y \in T_p S$. function-linear in X, Y , skew

Also $R(\partial_i, \partial_j) f \Psi = \nabla_i \nabla_j f \Psi - \nabla_j \nabla_i f \Psi$
 $= \nabla_i ((\partial_j f) \Psi + f \partial_j \Psi) - \nabla_j ((\partial_i f) \Psi + f \partial_i \Psi)$
 $= (\partial_i \partial_j f) \Psi + \partial_j f \nabla_i \Psi + (\partial_i f) \partial_j \Psi + f \nabla_i \nabla_j \Psi - (\partial_j \partial_i f) \Psi - \partial_i f \nabla_j \Psi - (\partial_j f) \partial_i \Psi - f \nabla_j \nabla_i \Psi$
 $= f (\nabla_i \nabla_j - \nabla_j \nabla_i) \Psi = f R(\partial_i, \partial_j) \Psi \Rightarrow \tilde{F}_{ij} = g F_{ij} g^{-1}$



i.e. $F = \sum_{i < j} F_{ij} dx^i \wedge dx^j \in \Lambda^2(\mathfrak{g})$ in terms of a trivialization of $E|_U$

Formula: $F_{ij} \Psi = \nabla_i (\partial_j \Psi + A_j \Psi) - \nabla_j (\partial_i \Psi + A_i \Psi) = \partial_i A_j - \partial_j A_i + [A_i, A_j] \Psi$; $F = dA + A \wedge A$

∇ acts on E^* and any \otimes 's E , e.g. $E \otimes E^* \cong \text{End } E$ accordingly by Leibniz rule

e.g. $B(x) \in \mathfrak{g} \subset E \otimes E^* \Rightarrow \nabla_\alpha b_j^i e_i \otimes e^j = \frac{\partial b_j^i}{\partial x^\alpha} e_i \otimes e^j + (A_\alpha^k e_k \otimes e^i - e_i \otimes A_\alpha^l e^l) b_j^i$
 $= \partial_\alpha b_j^i + (A_\alpha^k e_k^i b_j^i - b_j^i A_\alpha^l e^l) e_i \otimes e^j = \partial_\alpha B + [A_\alpha, B]$

Prop (Ex.) Show that $\exists!$ extension $\Lambda^0(E) \xrightarrow{\nabla} \Lambda^1(E) \xrightarrow{d^\nabla} \Lambda^2(E) \xrightarrow{d^\nabla} \dots$

so that $d^\nabla \circ d^\nabla = R$. Moreover $d^\nabla : \Lambda^2(\mathfrak{g}) \rightarrow \Lambda^3(\mathfrak{g})$ has $d^\nabla R = 0$ (Bianchi identity)

Examples (a) $G = U(1) \cong \text{so}(2)$ commutative $\Rightarrow F_{ij} = \partial_i A_j - \partial_j A_i$ i.e. $F = dA$

(b) Linear connection on TS, $(A_i)_j^k = \Gamma_{ji}^k$, $(F_{ij})_k^l = R_{kij}^l$

(c) Cartan connection (or affine) on TS $(\tilde{\nabla}_i \xi)^j := (\nabla_i \xi)^j + \delta_i^j$
 in one chart. ∇ linear. $G =$ affine gp = linear transf + translations

(d)* (semi-) spinors with induced Levi-Civita conn on (M^4, g_{ij}) of type $(1,3)$. Let $U = \bar{U}^T$

by $U = u^\beta \sigma_\beta(x) = \begin{pmatrix} u^0 + u^3 & u^1 + i u^2 \\ u^1 - i u^2 & u^0 - u^3 \end{pmatrix}$ with $\sigma_\beta(x)$ ON. $\forall x$. Let $U = (u^0)^2 - \sum_{i=1}^3 (u^i)^2 \Rightarrow \text{SL}(2, \mathbb{C}) \xrightarrow{2:1} \text{SO}(1,3)$

Any $A_\alpha(x) \in \mathfrak{sl}(2, \mathbb{C}) \Rightarrow \hat{\nabla}_\alpha$ on $\mathbb{C}^2 \Rightarrow \hat{\nabla}_\alpha U = \partial_\alpha U + A_\alpha U + U \bar{A}_\alpha^T$. we identify TM by $\text{SU}(2)$.
 via $U \mapsto g U \bar{g}^T$

Ex. The requirement $\hat{\nabla}_\alpha U = \hat{\nabla}_\alpha (\sigma_\beta u^\beta) = \sigma_\beta \cdot (\nabla_\alpha^{LC} u)^\beta \Rightarrow A_\alpha = -\frac{1}{2} \Gamma_{\rho\alpha}^\gamma \sigma_\gamma \sigma_\beta g_{\mu\nu}^{\rho\delta}$ * Urzawski

Final Lecture: Gauge inv functionals and characteristic classes

Gauge field $A \in \mathcal{A}^1(\mathfrak{g})$ $\mathfrak{g} = \text{Lie } G$, \langle, \rangle Killing form, assume non-degenerate

$L(A)$ Lagrangian inv under Gauge transf. i.e. intrinsically: $E \rightarrow G \text{ bundle}$

eg. $L(A) = |F|^2 = \langle F^{\mu\nu}, F_{\mu\nu} \rangle = g^{\mu\alpha} g^{\nu\beta} \langle F_{\alpha\beta}, F_{\mu\nu} \rangle$

Then (Yang-Mills) The extremal for $\int_S |F|^2 d\sigma =: S[A]$

satisfies $d_A^* F = \nabla_\mu F^{\mu\nu} = \partial_\mu F^{\mu\nu} - [A_\mu, F^{\mu\nu}] = 0$. (sign problem?)

pf: $\frac{d}{d\epsilon} S[A + \epsilon \eta] \Big|_{\epsilon=0} = 2 \int_S \langle F, d\eta + \eta \wedge A + A \wedge \eta \rangle d\sigma$
 $=: 2 \int_S \langle d_A^* F, \eta \rangle d\sigma$
 $d\eta + [A, \eta] = d_A \eta$

\downarrow
 S
 $\nabla: \Lambda^k(E) \rightarrow \Lambda^k(E)$
 a G -connection
 $L = L(\nabla)$
 $F = dA + A \wedge A$
 \uparrow
 matrix mult.

Explicitly, $\int_S \langle F^{\mu\nu}, \partial_\mu \eta_\nu - \partial_\nu \eta_\mu + [A_\mu, \eta_\nu] + [\eta_\mu, A_\nu] \rangle d\sigma$
 sth else' $= \int_S \langle \partial_\mu F^{\mu\nu}, \eta_\nu \rangle - \langle \partial_\nu F^{\mu\nu}, \eta_\mu \rangle - \langle [A_\mu, F^{\mu\nu}], \eta_\nu \rangle + \langle [A_\nu, F^{\mu\nu}], \eta_\mu \rangle$
 $= 2 \int_S \langle \partial_\mu F^{\mu\nu} - [A_\mu, F^{\mu\nu}], \eta_\nu \rangle d\sigma$
 $\mu \leftrightarrow \nu$ switch

Remark: This is the non-abelian generalization of Maxwell eqn, eg. $G = SU(2)$.

Def: Gauge inv. closed form $\omega(A)$ with $\delta\omega(A)$ exact, hence $\delta \int_S \omega \equiv 0$
 for S a space of dim = deg ω , is called a diff. geom. char. class.

① $c_i(A) := \text{tr } F^i = \text{tr}(F \wedge \dots \wedge F) \in \Lambda^{2i}$ $dF = dA \wedge A - A \wedge dA = [dA, A] = [F, A]$
 $\delta c_i(A) = \text{tr}(dF \wedge \dots \wedge F) + \text{tr}(F \wedge dF \wedge \dots) + \dots$ $\delta F = d\delta A + \delta A \wedge A + A \wedge \delta A$
 $= i \text{tr}([dA, A] \wedge F^{i-1}) = i \text{tr}([F, A] \wedge F^{i-1}) = d(\delta A) + [\delta A, A]$
 $= i \text{tr}(F A F^{i-1} - A F^i) = i \text{tr}(A F^i - A F^i) = 0$ \uparrow \mathbb{Z}_2 -bracket
 $\delta c_i(A) = i \text{tr}((d(\delta A) + [\delta A, A]) \wedge F^{i-1}) = i \text{tr}(d(\delta A) \wedge F^{i-1}) + i \text{tr}([\delta A, A] \wedge F^{i-1})$
 for $i=1$ get $\delta c_1(A) = d \text{tr}(\delta A)$ exact, done.

Ex. Show that $\delta c_i(A)$ is exact for all i . \nexists Chern classes $c_i(A) \in \Lambda^{2i}$
 eg. may do $c(A) := \det(1 + \frac{\sqrt{-1}}{2\pi} F)$ directly. \leftrightarrow (up to some const $(\frac{\sqrt{-1}}{2\pi})^i$)

② For $G = SO(m)$, $F \in \mathfrak{g} = \mathfrak{so}(m) \ni F^T = -F \ni (F^i)^T = (-1)^i F^i \ni c_{2k+1} \equiv 0$
 get (only) Pontryagin classes $p_i := c_{2i} \in \Lambda^{4i}$

③ For $G = SO(2n)$, there is one more class $X_n := \epsilon^{i_1 \dots i_n} F_{i_1 i_2} \wedge \dots \wedge F_{i_{n-1} i_n} \in \Lambda^{2n}$
 the Euler class. eg. for $SO(2)$, $X_1 = \epsilon^{ij} F_{ij} = 2K d\sigma$

Ex. Show that X_n is a characteristic class, also all problem with p_i 's. END.