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## Functions of multivariables and continuity (1.1 - 1.3)

$$f(x, y) = x^2 - y^2$$



- Limit of sequence of points

$$\text{distance } |b-a|$$

$$P = (x_1, x_2, \dots, x_m) \in \mathbb{R}^m, Q = (x'_1, x'_2, \dots, x'_m)$$

$$|P-Q| = \left( \sum_{i=1}^m |x_i - x'_i|^2 \right)^{1/2} \text{ Euclidean distance}$$

Def: " $\lim_{n \rightarrow \infty} P_n = Q$ "  $\Leftrightarrow \forall \varepsilon > 0, \exists N \text{ st. } n \geq N \Rightarrow |P_n - Q| < \varepsilon$

$$P_n = (x_n, y_n), Q = (a, b)$$

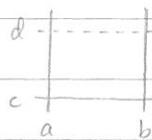
equivalently,  $\lim_{n \rightarrow \infty} x_n = a, \lim_{n \rightarrow \infty} y_n = b$

$$\Rightarrow ((x_n - a)^2 + (y_n - b)^2)^{1/2} < \varepsilon \Rightarrow |x_n - a| < \varepsilon, |y_n - b| < \varepsilon$$

$$\Leftarrow: \forall \varepsilon > 0, \exists N \text{ st. } n \geq N, |x_n - a| < \varepsilon, |y_n - b| < \varepsilon \Rightarrow |P_n - Q| < \sqrt{2}\varepsilon$$

S: Region (區域)  $\subset \mathbb{R}^2$

$$\mathbb{R}^2 \leftrightarrow \mathbb{R}$$



$$[a, b]$$

$$(a, b)$$

$$[a, b]$$

$$(a, b)$$

$$[a, b] \times [c, d] \subset \mathbb{R}^2$$

$$= \{(x, y) \mid a \leq x \leq b, c \leq y \leq d\}$$

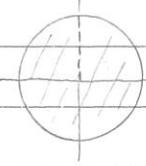
•  $\varepsilon$ -neighborhood:  $(a-\varepsilon, a+\varepsilon) \times (b-\varepsilon, b+\varepsilon)$

open box

$$B_p(\varepsilon) = \{Q \in \mathbb{R}^2 \mid |Q - P| < \varepsilon\}$$

$\downarrow$   $\varepsilon$ -ball

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$$S = \{(x, y) \mid x^2 + y^2 \leq 1 \text{ and if } x=0 \text{ then } y < 0\}$$

- interior points  $S^o = \{P \in \mathbb{R}^2 \mid \exists \varepsilon\text{-neighborhood of } P \text{ contained in } S\}$
- exterior points  $S^e = \{P \in \mathbb{R}^2 \mid \exists \varepsilon\text{-neighborhood of } P \text{ which is disjoint from } S\}$   
 $\{P \in \mathbb{R}^2 \mid \exists B_p(\varepsilon) \text{ st. } B_p(\varepsilon) \cap S = \emptyset\}$
- boundary points  $\partial S = \{P \in \mathbb{R}^2 \mid \forall B_p(\varepsilon), B_p(\varepsilon) \cap S \neq \emptyset, B_p(\varepsilon) \cap S^o \neq \emptyset\}$   
( $S^c = \text{complement of } S := \mathbb{R}^2 \setminus S = \{P \in \mathbb{R}^2 \mid P \notin S\}$ )

$$\mathbb{R}^2 = S^o \sqcup S^e \sqcup \partial S$$

disjoint union

Key terminology.

{ open set :  $S = S^o$

{ closed set :  $S \supset \partial S$

$S$  is open  $\Leftrightarrow S^o$  is closed ( $\partial S = \partial(S^c)$ )

domain and range of a function

$f: \mathbb{R}^2 \supset S \rightarrow \mathbb{R}$   $f(S)$  "image"

eg.  $f(x, y) = \log(1-x^2-y^2)$  domain  $S = B_0(1)$

eg.  $f(x, y) = \tan^{-1}(y/x)$  we need to select a "principal branch" to make the function be single valued

Def: ①  $\lim_{P_n \rightarrow P} f(P_n) = L \Leftrightarrow \forall \varepsilon > 0, \exists N, \text{ st. } n \geq N \Rightarrow |f(P_n) - L| < \varepsilon$

②  $f(x, y)$  is conti. at  $P = (a, b) \Leftrightarrow \lim_{Q \rightarrow P} f(Q) = f(P)$

③  $\lim_{Q \rightarrow P} f(Q) = L \Leftrightarrow \forall \varepsilon > 0, \exists \delta > 0 \text{ st. } |Q - P| < \delta \Rightarrow |f(Q) - L| < \varepsilon$

eg1.  $f(x, y) = \frac{xy}{x^2+y^2}$  is conti. outside  $(0, 0)$

Q:  $\lim_{Q \rightarrow 0} f(Q)$  exist?

along x-axis:  $f(x, 0) = 0$ ; along y-axis:  $f(0, y) = 0$

along  $y=mx$ :  $f(x, y) = \frac{2mx^2}{x^2+(mx)^2} = \frac{2m}{1+m^2}$  varies in  $m$

eg2.  $f(x, y) = \frac{xy^2}{x^2+y^2}$

$$f(x, mx) = \frac{m^2 x^3}{x^2(1+m^2)} = \frac{m^2}{1+m^2} x$$

$$\frac{xy}{x^2+y^2} \leq \frac{1}{2}, |f(x, y)| \leq \frac{|y|}{2}$$

eg2'  $f(x, y) = \frac{xy^2}{x^2+y^4}$

$$f(x, mx) = \frac{m^2 x^3}{x^2(1+m^2 x^2)} = \frac{m^2 x}{1+m^2 x^2}$$

along  $y^2=mx$

eg3. Continuous extension of a function to  $\partial S$  of its domain  $S$

$f(x, y) = e^{-x^2/y}$  with  $S = \{(x, y) \in \mathbb{R}^2 \mid y > 0\}$  upper half plane

$\partial S = x\text{-axis}$

$$\begin{cases} a \neq 0, \lim_{P \rightarrow (a, 0)} f(P) = 0 \\ a = 0, \text{ let } y = mx^2, f(x, y) = e^{-x^2/mx^2} = e^{-1/m} \end{cases}$$

$$f(x, y) = \frac{xy^2}{x^2+y^2} \text{ if } (x, y) \neq (0, 0)$$

$$= 0 \quad \text{if } (x, y) = (0, 0)$$

$$|f(x, y) - f(0, 0)| \leq \left| \frac{xy}{x^2+y^2} \right| |y|$$

$f(x, y)$  is conti.  $\Leftrightarrow \lim_{n \rightarrow \infty} f(x_n, y_n) = f(\lim_{n \rightarrow \infty} (x_n, y_n)) = f(\lim_{n \rightarrow \infty} x_n, \lim_{n \rightarrow \infty} y_n)$



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Continuity

$$f(x, y) = \frac{xy^2}{x^2+y^2} \text{ if } (x, y) \neq (0, 0)$$

$$= 0 \quad \text{if } (x, y) = (0, 0)$$

$$|f(x, y) - f(0, 0)| \leq \left| \frac{xy}{x^2+y^2} \right| |y|$$

The order of a function "O"; "o"  $f(h, k), g(h, k)$

$$f = O(g) \Leftrightarrow \left| \frac{f(h, k)}{g(h, k)} \right| \leq M, \text{ when } (h, k) \rightarrow (0, 0)$$

$$f = o(g) \Leftrightarrow \lim_{(h, k) \rightarrow (0, 0)} \frac{f(h, k)}{g(h, k)} = 0$$

### § 1.4 Partial derivatives

$$z = f(x, y) = x^2 - y^2 \quad \text{slicing: } \begin{array}{l} x=0, z=-y^2 \\ x=c, z=c^2-y^2 \end{array} \quad \begin{array}{l} y=0, z=x^2 \\ y=c, z=x^2-c^2 \end{array}$$

level curves: let  $z = \text{const. } c$

$$\frac{\partial f}{\partial x}(x_0, y_0) = \lim_{h \rightarrow 0} \frac{f(x_0+h, y_0) - f(x_0, y_0)}{h}; \quad \frac{\partial f}{\partial y}(x_0, y_0) = \lim_{h \rightarrow 0} \frac{f(x_0, y_0+h) - f(x_0, y_0)}{h}$$

$$\frac{\partial}{\partial x} f(x_0, y_0) = \partial_x f(x_0, y_0) = \partial_1 f(x_0, y_0)$$

$$\frac{\partial}{\partial y} f(x_0, y_0)$$

### Higher Partial derivatives

$$\frac{\partial}{\partial x} \left( \frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial x^2} = f_{xx} = D_x D_x f; \quad \frac{\partial}{\partial y} \left( \frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x} = f_{yx} = D_y D_x f$$

$$\frac{\partial}{\partial x} \left( \frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial x \partial y} = f_{xy} = D_x D_y f; \quad \frac{\partial}{\partial y} \left( \frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial y^2} = f_{yy} = D_y D_y f$$

$$\text{eg1. } f(x, y) = x^2 - y^2: \quad f_x = 2x, \quad f_{yx} = 0; \quad f_y = 2y, \quad f_{xy} = 0$$

$$\text{eg2. } f(x, y) = e^{xy}: \quad f_x = e^{xy} \cdot \frac{1}{y}, \quad f_{yx} = e^{xy} \cdot \frac{-x}{y^2} + e^{xy} \cdot \frac{1}{y}$$

$$f_y = e^{xy} \cdot \frac{-x}{y^2}, \quad f_{xy} = e^{xy} \cdot \frac{1}{y} \cdot \frac{-x}{y^2} + e^{xy} \cdot \frac{-1}{y^2}$$

$$\text{eg3. } f(x, y) = \frac{xy}{x^2+y^2} \quad (x, y) \neq (0, 0) \quad f_x = \frac{y(x^2+y^2) - xy \cdot 2x}{(x^2+y^2)^2} = \frac{y^3 - x^2y}{(x^2+y^2)^2}$$

$$= 0 \quad (x, y) = (0, 0) \quad f_x(x, mx) = \frac{1}{x} \cdot \frac{m^3 - m}{(1+m^2)^2}$$

Theorem: If  $f_x, f_y$  exists and  $|f_x| \leq M_1, |f_y| \leq M_2$  on  $R$ , domain of  $f$ , then

$f$  is continuous

$$\text{pf. } \Delta f = f(a+h, b+k) - f(a, b) = f(a+h, b+k) - f(a+h, b) + f(a+h, b) - f(a, b)$$

$$= f_y(a+h, b+\theta k) \cdot k + f_x(a+\theta' h, b) \cdot h$$

$$|\Delta| \leq M_2 \cdot k + M_1 \cdot h \xrightarrow[h, k \rightarrow 0]{} 0$$

harmonic function

$$\text{eq4. } f(x, y, z) = \frac{1}{r} = \frac{1}{\sqrt{x^2+y^2+z^2}} \quad \Delta = \text{Laplace operator} = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

$$f_x = -\frac{1}{2} (x^2+y^2+z^2)^{-3/2} \cdot 2x, \quad f_{xx} = \frac{3}{4} (x^2+y^2+z^2)^{-5/2} \cdot (2x)^2 - (x^2+y^2+z^2)^{-3/2}$$

$$\Delta f = f_{xx} + f_{yy} + f_{zz} = \frac{3(x^2+y^2+z^2) - 3(x^2+y^2+z^2)}{(x^2+y^2+z^2)^{5/2}} = 0 \rightarrow \text{Laplace equation}$$

$$\text{eg. } f(x,t) = \frac{1}{\pi} e^{-\frac{(x-a)^2 + (y-b)^2}{4t}} \text{ satisfies } \frac{\partial^2 f}{\partial t^2} = f_{xx} \leftarrow \Delta f$$

Newton's heat equation

Theorem: If  $f_{xy}$  and  $f_{yx}$  are continuous on an open set  $R$ , then  $f_{xy} = f_{yx}$

pf: let  $A(h,k) := f(a+h, b+k) - f(a, b+k) - f(a+h, b) + f(a, b)$

Wrong method still works

$$A(h,k) = f_x(a+\theta_1 h, b+k) - f_x(a+\theta_2 h, b)$$

$$\text{let } \phi(x) = f(x, b+k) - f(x, b)$$

$$A(h,k) = \phi(a+h) - \phi(a) = \phi'(a+\theta_1 h) \cdot h = (f_x(a+\theta_1 h, b+k) - f_x(a+\theta_1 h, b))h = f_{yx}(a+\theta_1 h, b+\theta_2 k) \cdot h$$

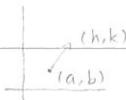
$$\lim_{(h,k) \rightarrow (0,0)} \frac{A(h,k)}{hk} = f_{yx}(a,b)$$

$$\text{change the role of } x \leftrightarrow y, f_{xy}(a,b) = f_{yx}(a,b)$$

3/ what is the notion of "differentiability" of a multivariable function?

Def. A function  $z = f(x,y)$  is differentiable at  $(x,y) = (a,b)$  iff

$$f(a+h, b+k) = f(a,b) + Ah + Bk + o(\sqrt{h^2+k^2}) \quad \text{linear approximation}$$



$$o(\sqrt{h^2+k^2}) \text{ with } \lim_{(h,k) \rightarrow (0,0)} o(\sqrt{h^2+k^2}) = 0$$

Corollary:  $A = f_x(a,b), B = f_y(a,b)$

$$\text{set } (h,k) = (h,0) : f(a+h, b) = f(a,b) + Ah + o(|h|) \Rightarrow A = \frac{\partial f}{\partial x}(a,b)$$

Theorem: If  $f_x, f_y$  exist and are conti. in a nbd of  $(a,b)$ , then  $f$  is differentiable at  $(a,b)$

pf.  $f(a+h, b+k) - f(a,b)$

neighborhood  
(ie. open set)

$$= f(a+h, b+k) - f(a+h, b) + f(a+h, b) - f(a,b)$$

$$= f_y(a+h, b+\theta_1 k) \cdot k + f_x(a+\theta_2 h, b) \cdot h$$

$$= f(a+h, b+k) - f(a,b) - (f_x(a,b)h + f_y(a,b)k)$$

$$= (f_x(a+\theta_2 h, b) - f_x(a,b))h + (f_y(a+\theta_1 k) - f_y(a,b))k$$

$$= f(a+h, b) - f(a,b) - f_x(a,b)h = o(|h|)$$

$$= o(\sqrt{h^2+k^2}) \text{ by continuity of } f_x \text{ & } f_y$$

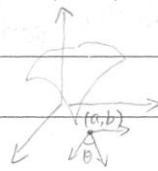
Theorem': if  $z = f(x_1, \dots, x_n)$  has at least  $(n-1)$  of  $\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}$  to be conti., then  $f$  is differentiable

Def:  $f \in C^k$  iff all partial derivatives of order  $\leq k$  are continuous

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Directional derivatives ( $\frac{\partial}{\partial r}$ )  $D_{\vec{v}} f = \nabla f \cdot \vec{v}$

$$D_{(\theta)} f(a, b) := \lim_{r \rightarrow 0} \frac{f(a+r\cos\theta, b+r\sin\theta) - f(a, b)}{r}$$



Assume that  $f$  is differentiable at  $(a, b)$

$$\lim_{r \rightarrow 0} \frac{f_x(a, b) \cdot r\cos\theta + f_y(a, b) \cdot r\sin\theta + o(\sqrt{h^2+k^2})}{r} = f_x \cos\theta + f_y \sin\theta$$

chain rule

$$u = f(x, y, z), \quad x = x(t), \quad y = y(t), \quad z = z(t)$$

$$\Delta f = f_x \cdot \Delta x + f_y \cdot \Delta y + f_z \cdot \Delta z + o(|\Delta \vec{x}|)$$

$$\lim_{t \rightarrow 0} \frac{\Delta f}{\Delta t} = f_x \cdot x' + f_y \cdot y' + f_z \cdot z' \pm \lim_{t \rightarrow 0} \frac{o(|\Delta \vec{x}|)}{|\Delta \vec{x}|} \cdot |\frac{\Delta \vec{x}}{\Delta t}|$$

$\nabla f \cdot (x', y', z')$

Def:  $\nabla f := (f_x, f_y, f_z)$  called the gradient of  $f$   
梯度

$$f(x(t), y(t), z(t)) = c \text{ constant}$$

$\nabla f \cdot (x', y', z') = 0 \Rightarrow \nabla f$  is the normal vector

eg.  $u = f(x, y, z) = 3x^2 + 2y^2 + z^2$  on the level surface  $u=1$

the normal vector is given by  $\nabla f = (6x, 4y, 2z)$

eg.

$$\frac{\partial z}{\partial t} = \nabla f \cdot (x'(t), y'(t))$$

$$z = f(x, y) \doteq f(a, b) + f_x(a, b)(x-a) + f_y(a, b)(y-b)$$

up to  $o(\sqrt{(x-a)^2 + (y-b)^2})$



$f$  is diff at  $(a, b) \Leftrightarrow$  the notion of tangent plane exists

$h, k \propto \Delta x, \Delta y \propto dx, dy$

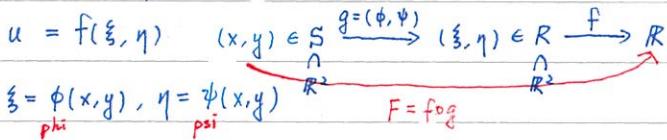
$df = f_x dx + f_y dy$  total differential (全微分)

" $d$ " =  $dx \frac{\partial}{\partial x} + dy \frac{\partial}{\partial y}$  operator (算子)

$$d^2 f = f_{xx} dx^2 + f_{xy} dx dy + f_{xy} dy dx + f_{yy} dy^2 = f_{xx} dx^2 + 2 f_{xy} dx dy + f_{yy} dy^2$$

$f \in C^2$

### 3/3 1.6 Composite of functions



Thm:  $f, g$  conti.  $\Rightarrow F = f \circ g$  is conti.

pf. given  $\varepsilon > 0$ ,  $\exists \delta$ , st.  $|w - g(p)| < \delta \Rightarrow |f(w) - f(g(p))| < \varepsilon$

$\exists \delta$  st.  $|q - p| < \delta \Rightarrow |g(q) - g(p)| < \delta$ ,

Thm:  $f, g$  differentiable  $\Rightarrow F = f \circ g$  is also differentiable & "formula"

$\hookrightarrow \phi, \psi$  are both differentiable

$$du = f_\xi d\xi + f_\eta d\eta \quad d\xi = \phi_x dx + \phi_y dy \quad d\eta = \psi_x dx + \psi_y dy$$

$$\Rightarrow du = (f_\xi \phi_x + f_\eta \psi_x) dx + (f_\xi \phi_y + f_\eta \psi_y) dy$$

$$\frac{\partial u}{\partial x} \quad \frac{\partial u}{\partial y}$$

$$\text{pf. } \Delta u = f_\xi \Delta \xi + f_\eta \Delta \eta + \varepsilon \cdot \sqrt{\Delta \xi^2 + \Delta \eta^2}$$

$$\Delta \xi = \phi_x \Delta x + \phi_y \Delta y + \varepsilon_1 \cdot \sqrt{\Delta x^2 + \Delta y^2}$$

$$\Delta \eta = \psi_x \Delta x + \psi_y \Delta y + \varepsilon_2 \cdot \sqrt{\Delta x^2 + \Delta y^2} \quad (\Delta x, \Delta y) \rightarrow (0, 0) \Rightarrow (\Delta \xi, \Delta \eta) \rightarrow (0, 0) \Rightarrow \varepsilon \rightarrow 0$$

$$\Rightarrow \Delta u = (f_\xi \phi_x + f_\eta \psi_x) \Delta x + (f_\xi \phi_y + f_\eta \psi_y) \Delta y + \underbrace{\varepsilon \sqrt{\Delta \xi^2 + \Delta \eta^2}}_{(f_\xi \cdot \varepsilon_1 + f_\eta \cdot \varepsilon_2) \sqrt{\Delta x^2 + \Delta y^2}}$$

$$\sqrt{\Delta \xi^2 + \Delta \eta^2} \leq |\Delta \xi| + |\Delta \eta| \leq |\phi_x| |\Delta x| + |\phi_y| |\Delta y| + |\varepsilon_1| \cdot \sqrt{\Delta x^2 + \Delta y^2} + |\psi_x| |\Delta x| + |\psi_y| |\Delta y|$$

$$\Rightarrow \frac{\sqrt{\Delta \xi^2 + \Delta \eta^2}}{\sqrt{\Delta x^2 + \Delta y^2}} \leq \text{_____ is bounded} \quad + |\varepsilon_2| \cdot \sqrt{\Delta x^2 + \Delta y^2}$$

$$\text{eg. } u = f(x, y) = f(r \cos \theta, r \sin \theta)$$

$$\frac{\partial u}{\partial r} = f_x x_r + f_y y_r = f_x \cos \theta + f_y \sin \theta$$

$$\frac{\partial u}{\partial \theta} = f_x x_\theta + f_y y_\theta = -f_x r \sin \theta + f_y r \cos \theta$$

$$\text{eg. } u = f(\xi, \eta), \xi = \phi(x, y), \eta = \psi(x, y)$$

$$u_x = u_\xi \xi_x + u_\eta \eta_x \Rightarrow u_{yx} = (u_\xi \xi_x)_y + (u_\eta \eta_x)_y = (u_{\xi\xi} \xi_y \xi_x + u_{\eta\xi} \eta_y \xi_x + u_{\xi\eta} \xi_y \eta_x) + (u_{\xi\xi} \xi_y \eta_x + u_{\eta\xi} \eta_y \eta_x + u_{\xi\eta} \eta_y \eta_x)$$

$$\Rightarrow u_{xx} = (u_\xi \xi_x)_x + (u_\eta \eta_x)_x = (u_{\xi\xi} \xi_x^2 + u_{\eta\xi} \eta_x \xi_x + u_{\xi\xi} \xi_y \eta_x)$$

$$+ (u_{\xi\xi} \xi_y \eta_x + u_{\eta\eta} \eta_x^2 + u_{\eta\eta} \eta_y \eta_x)$$

$$\Rightarrow u_{yy} = (u_\xi \xi_y)_y + (u_\eta \eta_y)_y = (u_{\xi\xi} \xi_y^2 + u_{\eta\xi} \eta_y \xi_y + u_{\xi\xi} \xi_y \eta_y)$$

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$$\text{Assume } C^2, \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = u_{\xi\xi} (\xi_{xx} + \xi_{yy}) + u_{\eta\eta} (\eta_{xx} + \eta_{yy}) + (\xi_x^2 + \xi_y^2) u_{\xi\xi} + (\eta_x^2 + \eta_y^2) u_{\eta\eta}$$

$$\begin{array}{c} (\xi_y, \eta_y) \\ (\xi_x, \eta_x) \end{array} \quad \xi_x \xi_y + \eta_x \eta_y = 0 \quad + 2u_{\xi\eta} (\xi_x \eta_x + \xi_y \eta_y)$$

保角  $\xi_x^2 + \eta_x^2 = \xi_y^2 + \eta_y^2$

①  $u = f\left(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2}\right)$  反演：圓內翻到圓外 (inversion)

$$\begin{aligned} \xi_x &= \frac{(x^2+y^2)-2x^2}{(x^2+y^2)^2} = \frac{y^2-x^2}{(x^2+y^2)^2}; \quad \xi_y = \frac{-2xy}{(x^2+y^2)^2} \\ \eta_x &= \frac{-2xy}{(x^2+y^2)^2}; \quad \eta_y = \frac{x^2-y^2}{(x^2+y^2)^2} \end{aligned}$$

$$\Rightarrow \xi_x \eta_x + \xi_y \eta_y = \frac{-2xy}{(x^2+y^2)^4} ((y^2-x^2)+(x^2-y^2)) = 0$$

$$\Rightarrow \xi_x^2 + \xi_y^2 = \eta_x^2 + \eta_y^2$$

$$\xi_{xx} = \frac{-2(x^2+y^2)^2 - (y^2-x^2) \cdot 2(x^2+y^2) \cdot 2x}{(x^2+y^2)^4} = \frac{-2x^3 - 2xy^2 - 4y^2x + 4x^3}{(x^2+y^2)^3} = \frac{2x^3 - 6xy^2}{(x^2+y^2)^3}$$

$$\xi_{yy} = \frac{-2(x^2+y^2)^2 + 2xy \cdot 2(x^2+y^2) \cdot 2y}{(x^2+y^2)^4} = \frac{-2x^3 - 2xy^2 + 8xy^2}{(x^2+y^2)^3} = \frac{-2x^3 + 6xy^2}{(x^2+y^2)^3}$$

$$u = f(x, y) = f(r \cos \theta, r \sin \theta) \quad u(r, \theta) = f(r)g(\theta)$$

$$\Delta u = u_{xx} + u_{yy} = u_{rr} + \frac{1}{r^2} u_{\theta\theta} + \frac{1}{r} u_r$$

$$\left\{ \begin{array}{l} u_r = u_x x_r + u_y y_r = \cos \theta u_x + \sin \theta u_y \\ u_\theta = u_x x_\theta + u_y y_\theta = -r \sin \theta u_x + r \cos \theta u_y \end{array} \right.$$

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Polar coordinates

$$u = u(x, y) \text{ 令 } x = r \cos \theta, y = r \sin \theta$$

$$r = \sqrt{x^2 + y^2}, \quad \theta = \tan^{-1} \frac{y}{x}$$

$$\Delta u = u_{xx} + u_{yy}$$

$$r_x = \frac{x}{\sqrt{x^2 + y^2}}, \quad r_y = \frac{y}{\sqrt{x^2 + y^2}}$$

$$u_x = u_r r_x + u_\theta \theta_x$$

$$\theta_x = \frac{-y/x^2}{1+(y/x)^2} = \frac{-y}{x^2+y^2}, \quad \theta_y = \frac{1/x}{1+(y/x)^2} = \frac{x}{x^2+y^2}$$

$$= u_r \cdot \frac{x}{r} + u_\theta \cdot \frac{-y}{r^2}$$

Rmk:  $(r_x, \theta_x) \perp (r_y, \theta_y)$ , so it is not a conformal change

保角

$$u_y = u_r \cdot \frac{y}{r} + u_\theta \cdot \frac{x}{r^2}$$

of coordinate

$$u_{xx} = \left( u_{rr} \cdot \frac{x}{r} - u_{\theta\theta} \cdot \frac{y}{r^2} \right)_x \frac{y^2}{r^3}$$

$$= \left( u_{rr} \cdot \frac{x^2}{r^2} + u_{r\theta} \cdot \frac{-xy}{r^3} + u_r \cdot \frac{y-x \cdot \frac{x}{r}}{r^2} \right) - \left( u_{\theta r} \cdot \frac{xy}{r^3} - u_{\theta\theta} \cdot \frac{y^2}{r^4} + u_\theta \cdot \frac{-2xy}{r^3} \right)$$

$$= u_{rr} \cdot \frac{x^2}{r^2} - 2u_{r\theta} \cdot \frac{xy}{r^3} + u_{\theta\theta} \cdot \frac{y^2}{r^4} + u_r \cdot \frac{y^2}{r^3} + u_\theta \cdot \frac{2xy}{r^4}$$

$$u_{yy} = u_{rr} \cdot \frac{y^2}{r^2} + 2u_{r\theta} \cdot \frac{xy}{r^3} + u_{\theta\theta} \cdot \frac{x^2}{r^4} + u_r \cdot \frac{x^2}{r^3} - u_\theta \cdot \frac{2xy}{r^4}$$

$$u_{xx} + u_{yy} = u_{rr} + \frac{1}{r^2} u_{\theta\theta} + \frac{1}{r} u_r$$

## 1.7 Mean Value Theorem &amp; Taylor expansion

$$f(Q) - f(P) = f(P + \vec{h}) - f(P) = g(1) - g(0) = \underset{\substack{\text{h} \\ \uparrow \\ (0,1)}}{g'(0)} \cdot 1 = (\nabla f)(P + \theta \vec{h}) \cdot \vec{h}$$

let  $g(t) = f(P + t\vec{h})$

$$g'(t) = \frac{d}{dt} f(P + t\vec{h}) = \nabla f \cdot \vec{h} \quad (g(t) = f(a+th, b+tk), g'(t) = f_x \cdot h + f_y \cdot k = \nabla f \cdot (h, k))$$

前提：可微分

## Taylor expansion

$$f(x, y) = f(a, b) + a_{00}(x-a) + a_{01}(y-b) + a_{20}(x-a)^2 + a_{11}(x-a)(y-b) + a_{02}(y-b)^2 + \dots$$

"  $a_{ij} (x-a)^i (y-b)^j$  "

$$g(t) = f(P + t\vec{h}), g'(t) = \nabla f \cdot \vec{h} = f_x h + f_y k = \left( h \cdot \frac{\partial}{\partial x} + k \cdot \frac{\partial}{\partial y} \right) f = df$$

$$g''(t) = \left( h \cdot \frac{\partial^2}{\partial x^2} + k \cdot \frac{\partial^2}{\partial y^2} \right) f \quad \hookrightarrow \text{differential operator 微分算子}$$

$$\Rightarrow \text{if } f \in C^k \text{ then } g^{(k)}(t) = d^k f = \left( h \cdot \frac{\partial}{\partial x} + k \cdot \frac{\partial}{\partial y} \right)^k f$$

$$g(1) = g(0) + g'(0) \cdot 1 + \frac{g''(0)}{2!} \cdot 1^2 + \dots + \frac{g^{(n)}(0)}{n!} \cdot 1^n + R_n, R_n = \frac{g^{(n+1)}(0)}{(n+1)!}$$

assume  $g \in C^{n+1}$

$$g^{(k)}(0) = h^k \frac{\partial^k f}{\partial x^k}(a, b) + \dots + c_k^k h^k k^{k-1} \frac{\partial^k f}{\partial x^i \partial y^{k-i}}(a, b) + \dots$$

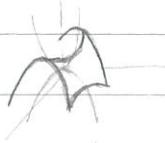
$$\Rightarrow f(x, y) = f(a, b) + f_x(a, b)(x-a) + f_y(a, b)(y-b) + \frac{1}{2!} \left( f_{xx}(a, b)(x-a)^2 + 2f_{xy}(a, b)(x-a)(y-b) + f_{yy}(a, b)(y-b)^2 \right)$$

$$z = f(x, y) = x^2 + y^2$$



$$z = f(x, y) = -x^2 - y^2$$

$$z = f(x, y) = x^2 - y^2$$



$$(x-a \ y-b) \begin{pmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{pmatrix} \begin{pmatrix} x-a \\ y-b \end{pmatrix}$$

$$(x-a \ y-b \ z-c) \begin{pmatrix} f_{xx} & f_{xy} & f_{xz} \\ f_{yx} & f_{yy} & f_{yz} \\ f_{zx} & f_{zy} & f_{zz} \end{pmatrix} \begin{pmatrix} x-a \\ y-b \\ z-c \end{pmatrix}$$

= 次型 quadratic form

$$\sum a_{ij} x_i x_j, a_{ij} = a_{ji} \quad \vec{x}^T A \vec{x} \quad \vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

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$\begin{pmatrix} a & b \\ c & d \end{pmatrix}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  conformal mapping (保角)

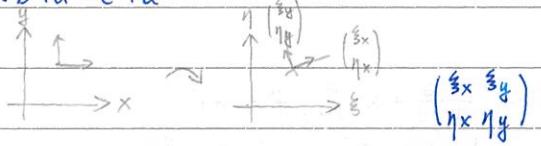
旋轉:  $\begin{pmatrix} a & b \\ -b & a \end{pmatrix}$  · 反射:  $\begin{pmatrix} a & b \\ b & -a \end{pmatrix}$  只有這兩種

p.f.  $(1, 0) \mapsto (a, c)$ ,  $(0, 1) \mapsto (b, d) \Rightarrow ab + cd = 0$

$(1, 1) \mapsto (a+b, c+d)$ ,  $(-1, 1) \mapsto (-a+b, -c+d) \Rightarrow b^2 - a^2 + d^2 - c^2 = 0$

$$(b^2 - a^2)^2 = (c^2 - d^2)^2 \Rightarrow b^4 + a^4 = c^4 + d^4 \Rightarrow (b^2 + a^2)^2 = (c^2 + d^2)^2 \Rightarrow b^2 + a^2 = d^2 + c^2$$

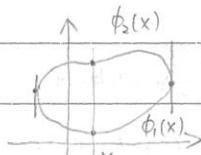
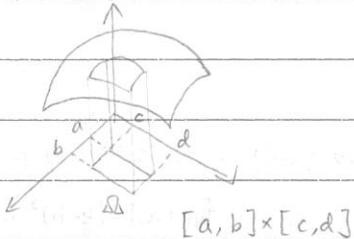
$$\begin{cases} b^2 - a^2 = c^2 - d^2 \\ b^2 + a^2 = c^2 + d^2 \end{cases} \quad b^2 = c^2, a^2 = d^2 \quad b = \pm c, a = \mp d$$



Jacobian 2 possibilities:

$$\textcircled{1} \begin{pmatrix} \xi_x = \eta_y \\ \xi_y = -\eta_x \end{pmatrix} \quad \textcircled{2} \begin{pmatrix} \xi_x = -\eta_y \\ \xi_y = \eta_x \end{pmatrix}$$

## 1.8 Integrals of functions with parameters



$$g(x) = \int_c^d f(x, y) dy$$

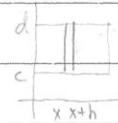
↑ parameter  
 $\phi(x)$

Let  $f(x, y)$  be continuous

$$\text{eg. } \int_c^d y^{1/x} dy = \frac{1}{\frac{1}{x} + 1} y^{\frac{1}{x} + 1} \Big|_c^d$$

①  $g(x)$  is continuous HW:  $[ ] \times [ ] \Rightarrow$  uniform conti. App!

$$\text{pf. } |g(x+h) - g(x)| = \left| \int_c^d (f(x+h, y) - f(x, y)) dy \right| \leq \varepsilon \cdot (d-c)$$



if  $|f(x+h, y) - f(x, y)| < \varepsilon \quad \forall y \in [c, d]$  ← uniform continuity for continuous functions

with multivariables

② Assume that  $f_x(x, y)$  exists and is continuous

$$Q: g'(x) = \int_c^d f_x(x, y) dy \quad \text{Ans: Yes}$$

$$\text{eg. } \int_0^1 (x-1) \frac{x^k}{\log x} dx \quad k > -1, k \in \mathbb{R}$$

$$\frac{d}{dk} g(k) = \int_0^1 \frac{x-1}{\log x} \cdot x^k \cdot \log x \cdot dx$$

$$\text{pf. } g'(x) = \lim_{h \rightarrow 0} \frac{g(x+h) - g(x)}{h} = \lim_{h \rightarrow 0} \int_c^d \frac{f(x+h, y) - f(x, y)}{h} dy = \lim_{h \rightarrow 0} \int_c^d f_x(x+\theta h, y) dy$$

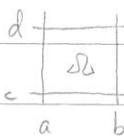
$$\left| \int_c^d (f_x(x+\theta h, y) - f_x(x, y)) dy \right| \leq \varepsilon(d-c) \text{ when } |h| < \delta \quad (\text{uniform continuity})$$

$$g(x) = \int_{\phi_1(x)}^{\phi_2(x)} f(x, y) dy, \quad f_x \text{ conti. } \phi_1, \phi_2 \text{ differentiable}$$

$$\Rightarrow g'(x) = f(x, \phi_2(x)) \phi'_2(x) - f(x, \phi_1(x)) \phi'_1(x) + \int_{\phi_1(x)}^{\phi_2(x)} f_x(x, y) dy$$

$$\text{pf. } F(x, u, v) = \int_u^v f(x, y) dy, \quad g(x) = F(x, \phi_1(x), \phi_2(x))$$

$$g'(x) = F_x(x)' + F_u \phi'_1(x) + F_v \phi'_2(x) = \int_{\phi_1(x)}^{\phi_2(x)} f_x(x, y) dy - f(x, \phi_1(x)) \phi'_1(x) + f(x, \phi_2(x)) \phi'_2(x)$$



$$\int_a^b dx \int_c^d f(x, y) dy \stackrel{?}{=} \int_c^d dy \int_a^b f(x, y) dx \quad (\text{Fubini theorem})$$

Yes, if  $f(x, y)$  is continuous

$$\text{pf. } v(x, y) = \int_c^y f(x, \eta) d\eta, \quad u(x, y) = \int_a^x v(\xi, y) d\xi = \int_a^x d\xi \int_c^y f(\xi, \eta) d\eta$$

$$\rightarrow v_y = f(x, y) \text{ conti.} \quad \rightarrow u_y(x, y) = \int_a^x v_y(\xi, y) d\xi = \int_a^x f(\xi, y) d\xi$$

$$\Rightarrow u(x, y) = u(x, c) + \int_c^y d\eta \int_a^x f(\xi, \eta) d\xi$$

### 3/15 1.9 Differential and Line Integrals

Recall arc length, work  $\int_a^b \vec{F} \cdot d\vec{r}$   $\vec{r}: [a, b] \rightarrow \mathbb{R}^2$

$$\int_a^b \vec{F} \cdot d\vec{r} = \int_a^b (A(x, y) \cdot \frac{dx}{dt} + B(x, y) \cdot \frac{dy}{dt}) dt = \int_P A dx + B dy$$

$$\vec{r}(t) = (x(t), y(t))$$

$\rightarrow$  this is independent of the parameter "t" as long as the

This is a general form of "1-differential form" (-次微分形式) orientation of  $P$  is preserved

eg. total differential  $df = f_x dx + f_y dy$   
(全微分)

• Usually (in this book) we denote by  $P^*$  a curve with a fixed orientation.

•  $P$  with the reverse orientation is denoted by  $-P^*$

$$\Rightarrow \int_{-P^*} = - \int_{P^*}$$

let  $L := Adx + Bdy + Cdz$ ,  $A, B, C$  are functions in  $x, y, z, C$  in  $\mathbb{R}^3$

if  $L = df$  for some  $f$  ie.  $A = f_x, B = f_y, C = f_z$  (or equivalently,  $(A, B, C) = \nabla f$ )

$$\text{then } \int_P L = \int_P df = \int_a^b \frac{df}{dt} dt = f(x(t), y(t), z(t)) \Big|_a^b = f(Q) - f(P)$$

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If such an  $f$  does exist, we must have  $A = f_x$ ,  $B = f_y$ ,  $C = f_z$  ( $\Rightarrow f \in C^2$ ) :  $\begin{cases} Ay = Bx \\ Bz = Cy \\ Cx = Az \end{cases}$  (both  $= f_{xy}$ )

Q: Does condition  $\Leftrightarrow$  imply the existence of  $f$ ?

Examples: ①  $L = ydx + zd\mathbf{y} + xd\mathbf{z}$  :  $Ay = 1 \neq Bx = 0$

②  $L = yzdx + zx\mathbf{dy} + xy\mathbf{dz} = d(xy\mathbf{z}) \Rightarrow f = xyz$

False total differential ③ "  $d\theta$ " =  $d\tan^{-1}\frac{y}{x} = \frac{-ydx + xdy}{x^2 + y^2}$ ,  $A = \frac{-y}{x^2 + y^2}$ ,  $B = \frac{x}{x^2 + y^2}$

$$Ay = \frac{-(x^2 + y^2) + 2y^2}{(x^2 + y^2)^2} = \frac{y^2 - x^2}{(x^2 + y^2)^2}, \quad Bx = \frac{(x^2 + y^2) - 2x^2}{(x^2 + y^2)^2} = \frac{y^2 - x^2}{(x^2 + y^2)^2}$$

$$\text{but } \int_{P^*} \frac{-ydx + xdy}{x^2 + y^2} = \int_0^{2\pi} -\sin\theta (-\sin\theta) d\theta + \cos\theta \cos\theta d\theta = \int_0^{2\pi} d\theta = \theta \Big|_0^{2\pi} = 2\pi \neq 0$$

$P^*$  = unit circle

$$(x(t), y(t)) = (\cos\theta, \sin\theta)$$

Next time: will show the condition  $\Leftrightarrow$  is sufficient if the domain  $U \subset \mathbb{R}^2$  of  $\vec{F} = (A, B)$  is simply connected (單連通) (兩條路徑可以連續變化)

e.g.  $\vec{F}(x, y, z) = \left( \frac{x}{\sqrt{x^2 + y^2 + z^2}}, \frac{y}{\sqrt{x^2 + y^2 + z^2}}, \frac{z}{\sqrt{x^2 + y^2 + z^2}} \right)$

"  $Df$  "  $f(x, y, z) = \frac{1}{\sqrt{x^2 + y^2 + z^2}}$

$\mathbb{R}^3 \setminus (0, 0, 0)$  is simply connected

$\mathbb{R}^3 \setminus \mathbb{R}$  is not simply connected

Fact: The line integral  $\int L$  i.e. independent of path  $\Leftrightarrow L = df$  for some  $f$

pf. " $\Leftarrow$ " : finished

"  $\Rightarrow$ " : we have to "define  $f$ " first

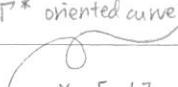
$$f(x, y, z) := \int_{P^*} L = \int_{P^*} Adx + Bdy + Cdz$$

fix  $P \in \mathbb{R}^3 \rightarrow$  any piecewise  $C^1$  curve connecting  $P$  and  $(x, y, z)$

$$\begin{aligned} \frac{\partial f}{\partial x} &= \frac{\partial}{\partial x} \left( \int_{P_1} + \int_{P_2} + \int_{(a, b, c)}^{(x, y, z)} Adx + Bdy + Cdz \right) \\ &= \frac{\partial}{\partial x} \left( \int_{(a, b, c)}^{(x, y, z)} Adx \right) \end{aligned}$$

$$= A$$
  
$$\text{similarly, } B = f_y, C = f_z$$

### 3/17 Line integral

$\Gamma^*$  oriented curve  


$$\mathbf{x}: [a, b] \rightarrow \mathbb{R}^3$$

$$\mathbf{x}(t) = (x(t), y(t), z(t))$$

$$\int_{\Gamma^*} L = \int_a^b (A dx + B dy + C dz) = \int_a^b (A \cdot \frac{dx}{dt} + B \frac{dy}{dt} + C \frac{dz}{dt}) dt = \int_{\Gamma^*} \vec{F} \cdot d\vec{x}$$

$$(\vec{F} = (A, B, C))$$

$$\Leftrightarrow \vec{F} = \nabla f$$

Last time:  $\int_{\Gamma^*} L$  is independent of path  $\Leftrightarrow L = df$  for some  $f$  (potential function)

$\Rightarrow \operatorname{curl} \vec{F} = 0$  compatibility coming from  $f_{x_i x_j} = f_{x_j x_i}$

$$f \quad \nabla f = \operatorname{grad} f = \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) f$$

$$\vec{F} = (A, B, C) \quad \operatorname{div} \vec{F} = \frac{\partial A}{\partial x} + \frac{\partial B}{\partial y} + \frac{\partial C}{\partial z} = \nabla \cdot \vec{F}$$

$$\operatorname{curl} \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A & B & C \end{vmatrix} = (C_y - B_z, A_z - C_x, B_x - A_y)$$

$$(a_1, b_1, c_1) \times (a_2, b_2, c_2) = \begin{vmatrix} i & j & k \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} \quad \text{why? HW}$$

$$L = Adx + Bdy + Cdz \Leftrightarrow \vec{F} = (A, B, C)$$

d: Elie Cartan's & operator

$$1. d^2 f = df \quad 2. dx dy \wedge dy \rightsquigarrow dx \wedge dy = -dy \wedge dx$$

$$dL = dA \wedge dx + dB \wedge dy + dC \wedge dz$$

$$= (Ax dx + Ay dy + Az dz) \wedge dx + (Bx dx + By dy + Bz dz) \wedge dy + (Cx dx + Cy dy + Cz dz) \wedge dz$$

$$= (Bx - Ay) dx \wedge dy + (Cy - Bz) dy \wedge dz + (Az - Cx) dz \wedge dx$$

$$L = \sum_{i=1}^n A_i dx^i \quad (x^1, \dots, x^n).$$

$$dL = \sum_{i=1}^n dA_i \wedge dx^i = \sum_{i=1}^n \left( \sum_{j=1}^n \frac{\partial A_i}{\partial x^j} dx^j \right) \wedge dx^i = \sum_{i < j} \left( \frac{\partial A_i}{\partial x^j} - \frac{\partial A_j}{\partial x^i} \right) dx^i \wedge dx^j$$

$$= 0 \quad \text{closed 1-form}$$

Theorem: Let  $L$  be a  $C^1$  one form defined on a simply connected open set  $U \subseteq \mathbb{R}^3$ ,

$$dL = 0 \Leftrightarrow L = df \text{ for some } f$$

closed one form

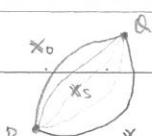
exact

Recall:  $\Leftarrow$  trivial

$\Rightarrow$  is reduced to prove that the line integral is independent of path

Simply connectedness (單連通):

Def.  $U$  is simply connected if any two curves with the same end points can be deformed to each other continuously



$$\mathbf{x}_0: [0, 1] \rightarrow \mathbb{R}^3 \quad \mathbf{x}_0(0) = P, \mathbf{x}_0(1) = Q$$

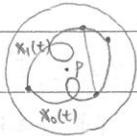
$$\mathbf{x}_1: [0, 1] \rightarrow \mathbb{R}^3 \quad \mathbf{x}_1(0) = P, \mathbf{x}_1(1) = Q$$

$$\text{i.e. } \exists \mathbf{x}: [0, 1] \times [0, 1] \rightarrow U \text{ continuous } \quad \mathbf{x}(t, s) \text{ st. } \mathbf{x}(t, 0) = \mathbf{x}_0(t)$$

Chayu culture

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$$\text{Ball, } B_p(r) \quad \mathbf{x}(t, s) = (1-s)\mathbf{x}_0(t) + s\mathbf{x}_1(t)$$



Fact: Any convex set is simply connected

$$\begin{aligned} \int_{P_1^*} L - \int_{P_0^*} L &= \int_0^1 \left( A \frac{\partial x}{\partial t} + B \frac{\partial y}{\partial t} + C \frac{\partial z}{\partial t} \right) \Big|_{s=1} dt - \int_0^1 \left( A \frac{\partial x}{\partial t} + B \frac{\partial y}{\partial t} + C \frac{\partial z}{\partial t} \right) \Big|_{s=0} dt \\ A \frac{\partial x}{\partial t} \Big|_{s=1} - A \frac{\partial x}{\partial t} \Big|_{s=0} &= \int_0^1 \frac{\partial}{\partial s} \left( A \frac{\partial x}{\partial t} \right) ds = \int_0^1 \left( (Ax_s + Ay_s + Az_s) x_t + Ax_s t \right) ds \\ &= \int_0^1 \left( (Bx_s + By_s + Bz_s) y_t + By_s t \right) ds \\ &= \int_0^1 \left( (Cx_s + Cy_s + Cz_s) z_t + Cz_s t \right) ds \end{aligned}$$

$$\int_0^1 (Ax_t + By_t + Cz_t)_s ds = \int_0^1 (Ax_s + By_s + Cz_s)_t dt$$

$$\because Bx = Ay, Cy = Bz, Az = Cx$$

(Poincaré lemma)

$$\begin{aligned} &= \int_0^1 ds (Ax_s + By_s + Cz_s) \Big|_{t=1} - \int_0^1 ds (Ax_s + By_s + Cz_s) \Big|_{t=0} \\ &= 0 \end{aligned}$$

3/2

$$\begin{aligned} &\text{in } \mathbb{R}^n = (x^1, \dots, x^n) \quad \int_{P_1^*} L \\ &\text{Path } P: x_1(t) \text{ from } P \text{ to } Q \quad P_1^* \text{ and } P_0^* \\ &U \subset \mathbb{R}^n \text{ open set, simply-connected} \\ &L = \sum_{i=1}^n A_i dx^i \\ dL &= \sum_{i=1}^n dA_i \wedge dx^i = \sum_{i=1}^n \left( \sum_{j=1}^n \frac{\partial A_i}{\partial x^j} dx^j \right) \wedge dx^i \\ &= \sum_{j < i} \left( \frac{\partial A_j}{\partial x^i} - \frac{\partial A_i}{\partial x^j} \right) dx^i \wedge dx^j \end{aligned}$$

The necessary condition for the line integral to be independent of path is  $dL = 0 \equiv \frac{\partial A_j}{\partial x^i} - \frac{\partial A_i}{\partial x^j} = 0$   
 (indep. of path  $\Rightarrow \exists f$  st.  $L = df$  i.e.  $A_i = \frac{\partial f}{\partial x^i}$ )

homotopy

$$\begin{aligned} \exists \mathbf{x}: [0, 1] \times [0, 1] &\longrightarrow U \text{ continuous} \quad \mathbf{x}(t, s) = (x^1(t, s), x^2(t, s), \dots, x^n(t, s)) \\ \text{st. } \mathbf{x}(t, 0) &= \mathbf{x}_0(t), \quad \mathbf{x}(t, 1) = \mathbf{x}_1(t) \end{aligned}$$

$$\begin{aligned} (*) &= \int_{P_1^*} L - \int_{P_0^*} L = \int_0^1 dt \sum_{i=1}^n \left( A_i(\mathbf{x}) \frac{\partial x^i}{\partial t} \Big|_{s=1} - A_i(\mathbf{x}) \frac{\partial x^i}{\partial t} \Big|_{s=0} \right) \\ &= \int_0^1 dt \int_0^1 ds \sum_{i=1}^n \frac{\partial}{\partial s} \left( A_i \frac{\partial x^i}{\partial t} \right) ds \\ &= \sum_{j=1}^n \left( \sum_{i=1}^n \frac{\partial A_i}{\partial x^j} \frac{\partial x^i}{\partial s} \right) + \sum_{i=1}^n A_i \frac{\partial x^i}{\partial s} \Big|_{s=0} \end{aligned}$$

$$= \int_0^1 dt \int_0^1 ds \sum_{i=1}^n \frac{\partial}{\partial t} (A_i \frac{\partial x_i}{\partial s}) = \int_0^1 ds \int_0^1 dt \sum_{i=1}^n \frac{\partial}{\partial t} (A_i \cdot \frac{\partial x_i}{\partial s}) = \int_0^1 ds \left( \sum_{i=1}^n A_i \frac{\partial x_i}{\partial s} \right) \Big|_{t=0}^{t=1} = 0$$

Problem:  $f(x, y)$  conti. in  $x, y$ , we want to approximate  $f$  by a  $C^2$  function.

$$f_h(x, y) := \frac{1}{4h^2} \int_{x-h}^{x+h} \int_{y-h}^{y+h} f(\xi, \eta) d\xi d\eta$$

$$\text{blur} = \frac{u(x+h, y+h) - u(x+h, y-h) - u(x-h, y+h) + u(x-h, y-h)}{4h^2} \Rightarrow \frac{\partial}{\partial x} f_h, \frac{\partial}{\partial y} f_h, \frac{\partial^2}{\partial xy} f_h = \frac{\partial^2}{\partial xy} f_h$$

check the textbook

$u$  is a "good" function

cont.

$$|f_h(x, y) - f(x, y)| = \frac{1}{4h^2} \int_{x-h}^{x+h} \int_{y-h}^{y+h} |f(\xi, \eta) - f(x, y)| d\eta \cdot dx < \varepsilon$$

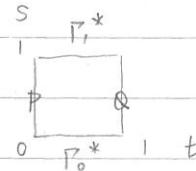
if  $< \varepsilon$

$\bar{x}_i(t, s)$  is now approximated by  $\tilde{x}_i(t, s) \leftarrow$  "good" function  $i=1, 2, \dots, n$

$x(t, s)$  conti.  $\bar{x}(t, s)$  good

$$\begin{aligned} \tilde{x}_i(t, s) &= \bar{x}_i(t, s) - (1-s)(\bar{x}_i(t, s) - x_0(t)) - s(\bar{x}_i(t, s) - x_1(t)) \\ &\quad - (1-t)(\bar{x}_i(t, s) - x_0(s)) - t(\bar{x}_i(t, s) - x_1(s)) \\ &\quad + (1-t)(1-s)(\bar{x}_i(0, 0) - x_0(0)) + (1-t)s(\bar{x}_i(0, 1) - x_1(0)) \\ &\quad + t(1-s)(\bar{x}_i(1, 0) - x_0(1)) + ts(\bar{x}_i(1, 1) - x_1(1)) \end{aligned}$$

四角



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$\mathbb{R}^1$  "[a, b]"

$\mathbb{R}^n$   $[a_1, b_1] \times \dots \times [a_n, b_n]$  "closed and bounded subset"

- bounded means  $S \subset B_R(R)$  for some  $R$

- closed means  $S$  contains all its boundary points

Theorem. (Bolzano-Weierstrass) Let  $S \subset \mathbb{R}^n$  be a closed and bounded set. Then

any sequence  $P_n \in S$ ,  $n=1, 2, \dots$  has a convergent subsequence in  $S$

pf. divided into  $2^n$  subcubes,  $\exists$  a subcube which still contains  $\infty$ -many  $P_i$ 's

Def A set  $S \subset \mathbb{R}^n$  is called (sequentially) compact (緊緻) iff it is closed and bounded

Thm: Let  $f: \mathbb{R}^n \ni S \ni \mathbb{R}$  be conti. with  $S$  being compact. Then  $\exists p \in S$  st.

$$f(p) = \max_S f$$

pf. claim  $\exists M$  st.  $f \leq M$ .

If not,  $\forall n \in \mathbb{N}$ ,  $\exists P_n \in S$  st.  $f(P_n) \geq n$

let  $P_{n_i}$  be a convergent subsequence,  $\lim_{i \rightarrow \infty} P_{n_i} = q \in S$

$$f(P_{n_i}) > n_i \quad \lim_{i \rightarrow \infty} f(P_{n_i}) \rightarrow \infty \quad \Leftrightarrow$$

$$f(\lim_{i \rightarrow \infty} P_{n_i}) = f(q)$$

## Chapter 3. Properties of differential Calculus for multivariables

### • Implicit functions (隱函數)

Ex 1.  $F(x, y) = (x^2 + y^2)^2 - 2a^2(x^2 - y^2) = 0$ . Find the maximal value of  $y$

雙曲線:  $y^2 = \cos 2x$   
Regard  $y$  as a function in  $x$ , " $y = f(x)$ "

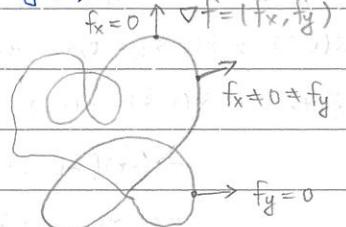
Apply  $\frac{d}{dx}$  to it:  $2(x^2 + y^2)(2x + 2y f') - 2a^2(2x - 2y f') = 0$

$f' = \dots$ ; Here we consider  $f'(x) = 0$

$$(x^2 + y^2) \cdot x - a^2 x = 0 \Rightarrow x(x^2 + y^2 - a^2) = 0$$

$$x = 0 \Rightarrow y^4 + 2a^2 y^2 = 0 \Rightarrow \dots$$

$$\text{or } x^2 + y^2 - a^2 = 0 \Rightarrow a^4 - 2a^2(a^2 - 2y^2) = 0 \Rightarrow \dots$$



Theorem (Implicit Function Theorem): Let  $F(x, y)$  be  $C^1$  and  $F(x_0, y_0) = 0$ ,

$F_y(x_0, y_0) = m \neq 0$ , then  $\exists$  nbd of  $(x_0, y_0)$  st.  $\exists! f, y = f(x)$  st.  $F(x, f(x)) = 0$  and  $f \in C^1$

In fact,  $f'(x) = -\frac{F_x}{F_y}$

$$F(\vec{x}, \vec{y}) = 0 \quad \frac{d}{dx}: F_x + F_y \cdot \frac{dy}{dx} = 0 \Rightarrow \frac{dy}{dx} = -\frac{\partial f / \partial x}{\partial f / \partial y}$$

pf. Step 1.: " $\exists!$ ":  $\exists R = [x_0 - \alpha, x_0 + \alpha] \times [y_0 - \beta, y_0 + \beta]$  st.  $F_y > \frac{m}{2}$  on  $R$  and let  $|F_x| \leq M$  on  $R$

Notice that  $F(x, y) \uparrow$  in  $y$  for any fixed  $x$ .

$$|F(x, y_0) - F(x_0, y_0)| = |F_x(\xi, y_0)| \cdot |x - x_0| \leq M \cdot |x - x_0|$$

$$F(\vec{x}, y_0 + \beta) = (F(\vec{x}, y_0 + \beta) - F(\vec{x}, y_0)) + F(\vec{x}, y_0)$$

$$> \frac{m\beta}{2} - M \cdot |\vec{x} - \vec{x}_0|$$

$$F(\vec{x}, y_0 - \beta) = (F(\vec{x}, y_0 - \beta) - F(\vec{x}, y_0)) + F(\vec{x}, y_0)$$

$$= F_y(x, \eta) \cdot (-\beta)$$

$$< -\frac{m\beta}{2} + M \cdot |\vec{x} - \vec{x}_0|$$

we just require that  $|\vec{x} - \vec{x}_0| < \frac{m\beta}{2M} =: \delta$

$\Rightarrow \exists! y$  st.  $F(\vec{x}, y) = 0$

Call this  $\vec{x} \mapsto y$  by  $y = f(x)$

Step 2. "f ∈ C<sup>1</sup>"

$$\text{let } x \text{ be fixed } f(x+h) - f(x) = k$$

$$D = F(\vec{x} + \vec{h}, f(\vec{x} + \vec{h})) - F(\vec{x}, f(\vec{x}))$$

$$= F_x(\vec{x} + \theta \vec{h}, y + \theta k) h + F_y(\vec{x} + \theta \vec{h}, y + \theta k) \cdot k, \quad \theta \in (0, 1)$$

$\uparrow \quad \downarrow$   
 $|h| \leq M \cdot |h| \quad \frac{m}{2}$

$$\Rightarrow |k| \leq \frac{2M}{m} |h| \Rightarrow f \text{ is (Lip) conti.}$$

$$\frac{f(\vec{x} + \vec{h}) - f(\vec{x})}{h} = \frac{k}{h} = -\frac{F_x(\vec{x} + \theta \vec{h}, y + \theta k)}{F_y(\vec{x} + \theta \vec{h}, y + \theta k)} \rightarrow -\frac{F_x(\vec{x}, y)}{F_y(\vec{x}, y)} \text{ as } h \rightarrow 0 (\Rightarrow k \rightarrow 0)$$

Multi-variable case:  $F(x^1, x^2, \dots, x^n, y)$  st.  $F(\vec{x}_0, y_0) = 0; F_y(\vec{x}_0, y) = m > 0$

$$F(x, y) = 0, \quad f' = -\frac{F_x}{F_y}$$

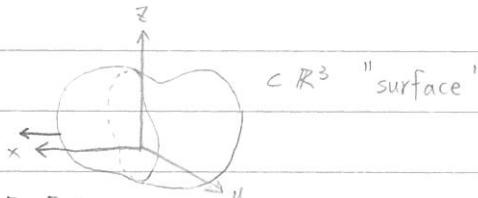
$$\Rightarrow f'' = -\frac{(F_{xx} + F_{yx} f') F_y - F_x (F_{xy} + F_{yy} f')}{F_y^2} = -\frac{F_x F_y + F_{yx} \cdot F_y \cdot (-\frac{F_x}{F_y}) - F_x \cdot F_{xy} + F_x \cdot F_{yy} \cdot (-\frac{F_x}{F_y})}{F_y^2}$$

$$= -\frac{F_y^2 F_{xx} - 2F_x F_y F_{xy} + F_x^2 F_{yy}}{F_y^3}$$

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$$u = F(x, y, z)$$

level set  $u = \text{constant} = 0$



$$N = \nabla F = (F_x, F_y, F_z)$$

$$F(x_0, y_0, z_0) = 0, \quad F_x(x_0, y_0, z_0) \neq 0$$

$\Rightarrow \exists!$  implicit function  $x = f(y, z)$  near  $(x_0, y_0, z_0)$  st.  $F(f(y, z), y, z) = 0$

What happens if  $\nabla F(x_0, y_0, z_0) = 0$

Consider any curve through  $(x_0, y_0, z_0)$  on  $F = 0$

$$F(x(t), y(t), z(t)) = 0$$

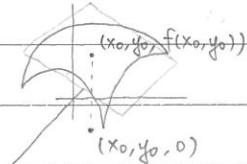
$$0 = \nabla F \cdot (x'(t), y'(t), z'(t)) \Big|_{t=0} \quad (\text{若切向量張開全空間, } \nabla F = 0)$$

$$F(x, y) = y^2 - x^2(x+1)$$

$$\nabla F = (-3x^2 - 2x, 2y)$$

Def. A point  $p \in \{\vec{x} \mid F(\vec{x})=0\}$  is a singular point (奇異點) if the tangent vectors at  $p$  span the whole space ( $\Rightarrow \nabla F(p)=0$ ) ex.  $F(x,y)=y^3-x^4$

Example 1  $z=f(x,y)$



$$\textcircled{1} z-z_0 = f_x(x_0, y_0)(x-x_0) + f_y(x_0, y_0)(y-y_0)$$

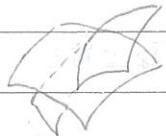
$$\textcircled{2} (x-x_0, y-y_0, z-z_0) \cdot (-f_x, -f_y, 1) = 0$$

$$(x, y, f(x, y)) \xrightarrow{\frac{\partial}{\partial x}} (1, 0, f_x) \quad \xrightarrow{\frac{\partial}{\partial y}} (0, 1, f_y) \quad (-f_x, -f_y, 1) = \vec{N}$$

$$\textcircled{3} F(x, y, z) = z - f(x, y) = 0 \text{ level set}$$

$$\nabla F = (-f_x, -f_y, 1)$$

Example 2.  $F=0, G=0$  in  $\mathbb{R}^3$



$$\cos \omega = \frac{\nabla F \cdot \nabla G}{|\nabla F| |\nabla G|} = \frac{F_x G_x + F_y G_y + F_z G_z}{\sqrt{F_x^2 + F_y^2 + F_z^2} \cdot \sqrt{G_x^2 + G_y^2 + G_z^2}}$$

$$u = a_1 x_1 + a_2 x_2 + \dots + a_n x_n + b y \quad \text{trivial linear model}$$

$$u \leftrightarrow y \quad \text{i.e. } y = -\frac{a_1}{b} x_1 - \frac{a_2}{b} x_2 - \dots - \frac{a_n}{b} x_n + \frac{u}{b}$$

Non-linear version:

$$\textcircled{*} u = F(\vec{x}, y) \quad \text{for a fixed } (\vec{x}_0, y_0), \frac{\partial u}{\partial y} = F_y \neq 0 \Rightarrow y = G(\vec{x}, u) \text{ st. } u = F(\vec{x}, G(\vec{x}, u))$$

$\downarrow$   
 $u = u_0 \text{ fixed}$

Cor. set  $u=0, y=g(\vec{x})$  implicit function

Actually,  $\textcircled{*}$  follows from the  $u=0$  case

pf. let  $H(\vec{x}, u, y) := u - F(\vec{x}, y)$

$$H_y = -F_y \neq 0 \Rightarrow y = G(\vec{x}, u) \text{ st. } H(\vec{x}, u, G(\vec{x}, u)) = 0 = u - F(\vec{x}, G(\vec{x}, u))$$

Theorem. General form of IFT (implicit/inverse function theorem)

$$u = F(\vec{x}, y, z), v = G(\vec{x}, y, z) \text{ with } D := \begin{vmatrix} F_y & F_z \\ G_y & G_z \end{vmatrix} \neq 0 \text{ at } (\vec{x}_0, y_0, z_0)$$

then in a nbd of  $(\vec{x}_0, y_0, z_0)$ ,  $\exists y = A(\vec{x}, u, v), z = B(\vec{x}, u, v)$

$$\text{st. } u = F(\vec{x}, A(\vec{x}, u, v), B(\vec{x}, u, v)), v = G(\vec{x}, A(\vec{x}, u, v), B(\vec{x}, u, v))$$

pf. may assume that  $F_y \neq 0$  (otherwise change  $y \leftrightarrow z$ ) (first row)

$$\frac{\partial u}{\partial y} = F_y \neq 0 \Rightarrow \exists y = \bar{y}(\vec{x}, u, z) \text{ st. } u = F(\vec{x}, \bar{y}(\vec{x}, u, z), z)$$

Now, the variables are  $u, z, \vec{x}$

$$V = G(\vec{x}, \bar{y}(\vec{x}, u, z), z) \quad \text{need to compute } \frac{\partial V}{\partial z} (\neq 0?)$$

$$\frac{\partial V}{\partial z} = G_z \cdot \bar{y}_z + G_z$$

$$\cancel{0} = \frac{\partial u}{\partial z} = F_y \cdot \bar{y}_z + F_z \Rightarrow \frac{\partial V}{\partial z} \neq 0 \Rightarrow \exists z = \bar{z}(\vec{x}, u, v) \text{ st. } V = G(\vec{x}, \bar{y}(\vec{x}, u, \bar{z}(\vec{x}, u, v)), \bar{z}(\vec{x}, u, v))$$

independent the  $u$  equation  
variables

$$u = F(\vec{x}, \bar{y}(\vec{x}, u, \bar{z}(\vec{x}, u, v)), \bar{z}(\vec{x}, u, v))$$

for any  $(\vec{x}, u, v)$  in the nbd

special cases.

1. Set  $u=v=0$ , get  $y(\vec{x}), z(\vec{x})$  st.  $F(\vec{x}, y(\vec{x}), z(\vec{x}))=0, G(\vec{x}, y(\vec{x}), z(\vec{x}))=0$

2. Let  $n=0$ , (ie. no  $\vec{x}$ ). get  $u=F(A(u, v), B(u, v))$ ,  $v=G(A(u, v), B(u, v))$  反函數

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$$\text{eg. } \frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

$$F(x, y, z) \quad N = \nabla F = \left( \frac{2x}{a^2}, \frac{2y}{b^2}, \frac{-2z}{c^2} \right)$$

tangent plane of  $P(x_0, y_0, z_0)$ :  $N_p \cdot (x-x_0, y-y_0, z-z_0) = 0$

$$\Rightarrow \frac{x_0(x-x_0)}{a^2} + \frac{y_0(y-y_0)}{b^2} + \frac{z_0(z-z_0)}{c^2} = 0$$

$$\Rightarrow \frac{x_0x}{a^2} + \frac{y_0y}{b^2} - \frac{z_0z}{c^2} = 1$$

$u = F(x, y, z)$ ,  $v = G(x, y, z)$  are both  $C^1$ , condition  $D = \begin{vmatrix} F_y & F_z \\ G_y & G_z \end{vmatrix} \neq 0$  at  $(x_0, y_0, z_0)$

$\Rightarrow y = f(x, u, v)$ ,  $z = g(x, u, v)$

eg.  $u=v=0$ , get  $y=f(x)$ ,  $z=g(x)$  st.  $F(x, f(x), g(x))=0, G(x, f(x), g(x))=0$

ie.  $F, G$  曲面交線參數化  $y=f(x)$ ,  $z=g(x)$

### §3.7 Maxima & minima problem

$$y = f(x), \quad f'(x) = 0$$

No. \_\_\_\_\_  
Date \_\_\_\_\_

$$\text{eg. } f(x, y) = (ax^2 + by^2) e^{-(x^2+y^2)}, \quad a, b \neq 0 \quad f(x, y) \rightarrow 0 \text{ as } x^2 + y^2 \rightarrow \infty$$

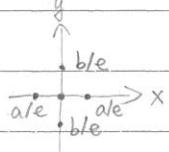
$(x_0, y_0)$  is a extremal point  $\Rightarrow f_x(x_0, y_0) = f_y(x_0, y_0) = 0 \quad (\vec{N} = (-\nabla f, 1), \nabla f = 0)$

$$f_x = 2ax e^{-(x^2+y^2)} + (ax^2 + by^2) e^{-(x^2+y^2)} \cdot (-2x) = 2x e^{-(x^2+y^2)} (a - ax^2 - by^2)$$

$$f_y = 2y e^{-(x^2+y^2)} (b - ax^2 - by^2)$$

$$\nabla f = 0 \Leftrightarrow x=0 \begin{cases} y=0 \\ y=\pm 1 \end{cases}; \quad x \neq 0, a - ax^2 - by^2 = 0 \begin{cases} y=0, x=\pm 1 \\ y \neq 0 \end{cases} \begin{cases} \text{if } a \neq b, \text{ no such case} \\ \text{if } a=b, \text{ get } x^2 + y^2 = 1 \end{cases}$$

• if  $a > b > 0$



$$f(x, y) = f(x_0, y_0) + \frac{1}{2} (f_{xx}(x_0, y_0)(x-x_0)^2 + 2f_{xy}(x_0, y_0)(x-x_0)(y-y_0) + f_{yy}(x_0, y_0)(y-y_0)^2) + \dots$$

$$f(x+h, y+k) = f(x_0, y_0) + \frac{1}{2} (h, k) \begin{pmatrix} f_{xx} & f_{yx} \\ f_{xy} & f_{yy} \end{pmatrix} \begin{pmatrix} h \\ k \end{pmatrix} + \dots \quad \vec{x}^T A \vec{x} \text{ quadratic form}$$

symmetric matrix at  $(x_0, y_0)$        $\vec{y}^T \begin{pmatrix} \lambda_1 & \dots & \lambda_n \end{pmatrix} \vec{y}$

Next, we consider min/max problem with side conditions

$$\text{Eg. } \frac{x^2 + y^2 + z^2}{3} \geq \sqrt[3]{x^2 y^2 z^2}$$

Think as the min/max problem for  $f(x, y, z) = x^2 y^2 z^2$  under  $x^2 + y^2 + z^2 = c$

Lagrange multiplier (乘子)

$$u = f(x, y, z), \quad v = g(x, y, z) = c \quad ; \quad u = f(\vec{x}, y, z), \quad g_1(\vec{x}, y, z) = 0, \quad g_2(\vec{x}, y, z) = 0$$

$$\nabla f = \lambda \nabla g \text{ for some } \lambda \quad ; \quad \nabla f = \lambda_1 \nabla g_1 + \lambda_2 \nabla g_2$$

$$\text{pf. } \textcircled{1} \quad z = h(x, y) \Rightarrow u = f(x, y, h(x, y))$$

$$0 = \frac{\partial u}{\partial x} = f_x + f_z \cdot h_x \quad 0 = \frac{\partial u}{\partial y} = f_y + f_z \cdot h_y$$

$$g_x + g_z \cdot h_x = 0 \quad g_y + g_z \cdot h_y = 0$$

$$\Rightarrow \nabla f = \lambda \nabla g$$

$$\textcircled{2} \quad u = f(\vec{x}, h(\vec{x}), k(\vec{x})), \quad g_1(\vec{x}, h(\vec{x}), k(\vec{x})) = 0, \quad g_2(\vec{x}, h(\vec{x}), k(\vec{x})) = 0$$

$$\frac{\partial u}{\partial x_i} = f_{x_i} + f_y \cdot h_{x_i} + f_z \cdot k_{x_i} = 0 \quad \forall i = 1, \dots, n$$

$$\frac{\partial g_1}{\partial x_i} = g_{x_i} + g_{y_i} \cdot h_{x_i} + g_{z_i} \cdot k_{x_i} = 0, \quad \frac{\partial g_2}{\partial x_i} = g_{x_i} + g_{y_i} \cdot h_{x_i} + g_{z_i} \cdot k_{x_i} = 0$$

$$\begin{pmatrix} 1 & h_{x_1} & k_{x_1} \\ 1 & h_{x_2} & k_{x_2} \\ \vdots & \vdots & \vdots \\ 1 & h_{x_n} & k_{x_n} \end{pmatrix} \times = 0 \Rightarrow x = \lambda_1 x_1 + \lambda_2 x_2$$

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$$\text{Ex 1. } \frac{x_1 + \dots + x_n}{n} \geq \sqrt[n]{x_1 \cdots x_n} \quad (x_i \geq 0)$$

method 1. Let  $x_1 + \dots + x_n = c > 0$ ,  $c$  fixed constant

$$f(x_1, \dots, x_n) = x_1 \cdots x_n$$

equivalent to  $g(x_1, \dots, x_{n-1}) = x_1 \cdots x_{n-1}(c - x_1 - \dots - x_{n-1})$

For simplicity we write out the case  $n=3$

$$g(x_1, x_2) = x_1 x_2 (c - x_1 - x_2) \quad \left( \begin{array}{l} f \equiv 0 \text{ on } \partial \Omega, \text{ the maxima of } f \text{ exists, and is in the interior} \\ (g) \end{array} \right)$$

$$\frac{\partial g}{\partial x_1} = x_2(c - x_1 - x_2) - x_1 x_2 = x_2(c - 2x_1 - x_2) = 0$$

$$\frac{\partial g}{\partial x_2} = x_1(c - x_1 - x_2) = 0$$

$$\Rightarrow x_1, x_2 \neq 0 \Rightarrow 2x_1 + x_2 = c, x_1 + 2x_2 = c$$

$\Rightarrow x_1 = x_2$  in this case " $=$ " holds

method 2. Let  $h(x) = x_1 + \dots + x_n - c$

under  $h=0$ , solve maxima of  $f$

$$\nabla f = \lambda \nabla h \Rightarrow \left( \frac{f}{x_1}, \dots, \frac{f}{x_n} \right) = \lambda(1, \dots, 1)$$

$$\Rightarrow x_1 = \dots = x_n$$

Ex 2. Hölder inequality :  $uv \leq \frac{1}{\alpha} u^\alpha + \frac{1}{\beta} v^\beta$ ,  $u, v \geq 0$ ,  $\frac{1}{\alpha} + \frac{1}{\beta} = 1$

$$\text{fix } uv = c \geq 0 \quad f(u, v)$$

$$\nabla f = \lambda \nabla h \Rightarrow (u^{\alpha-1}, v^{\beta-1}) = \lambda(v, u) \Rightarrow \frac{u^{\alpha-1}}{v} = \frac{v^{\beta-1}}{u} \Rightarrow u^\alpha = v^\beta$$

$$u^\alpha = (\lambda v) \cdot u = \lambda c = v^\beta, \quad uv = (\lambda c)^{\frac{1}{\alpha}} \cdot (\lambda c)^{\frac{1}{\beta}} = \lambda c = c \Rightarrow \lambda = 1$$

$$\Rightarrow \frac{1}{\alpha} u^\alpha + \frac{1}{\beta} v^\beta = c \quad A \quad B$$

general form :  $\sum_{i=1}^n u_i v_i \leq (\sum u_i^\alpha)^{\frac{1}{\alpha}} \cdot (\sum v_i^\beta)^{\frac{1}{\beta}}$   $\alpha = \beta = 2$  (Cauchy)

$$\text{pf. let } u = \frac{u_i}{A}, v = \frac{v_i}{B}$$

$$uv \leq \frac{1}{\alpha} \cdot \frac{u_i^\alpha}{\sum_j u_j^\alpha} + \frac{1}{\beta} \cdot \frac{v_i^\beta}{\sum_j v_j^\beta}$$

$$\sum_{i=1}^n \frac{u_i v_i}{AB} \leq \frac{1}{\alpha} + \frac{1}{\beta} = 1$$

Ex 3. More constraints :

$u = f(\vec{x}, y, z)$ ,  $g(\vec{x}, y, z) = 0$ ,  $h(\vec{x}, y, z) = 0$  assume that  $\begin{vmatrix} gy & gz \\ hg & hh \end{vmatrix} \neq 0$  at the extremal point

$\Rightarrow$  get  $y = A(\vec{x})$ ,  $z = B(\vec{x})$

$$\Rightarrow 0 = \frac{\partial u}{\partial x_i} = f_{x_i} + f_y A_{x_i} + f_z B_{x_i} \quad \forall i = 1, \dots, n$$

$$0 = \frac{\partial u}{\partial y} = g_{x_i} + g_y A_{x_i} + g_z B_{x_i}$$

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$$\begin{array}{c} \text{linearly independent} \\ \left( \begin{array}{ccc|cc} f_{x_i} & f_y & f_z & 1 & \\ g_{x_i} & g_y & g_z & A_{x_i} & \\ h_{x_i} & h_y & h_z & B_{x_i} & \end{array} \right) = 0 \end{array}$$

$\Rightarrow$   $\uparrow$  has  $\det = 0$

$$(f_{x_i}, f_y, f_z) = \lambda_1(g_{x_i}, g_y, g_z) + \lambda_2(h_{x_i}, h_y, h_z)$$

$\lambda_1, \lambda_2$  are uniquely determined by  $(y, z)$  components, independent of  $i = 1, \dots, n$

$$\Rightarrow \nabla f = \lambda_1 \nabla g + \lambda_2 \nabla h$$

3.3 We have proved the inverse function theorem by a composition primitive mappings.  
ie. replace one variable each time

$$\mathbb{R}^2 \xrightarrow[F=(\begin{matrix} f \\ g \end{matrix})]{} \mathbb{R}^2 \quad \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} f(x,y) \\ g(x,y) \end{pmatrix} = \begin{pmatrix} \xi \\ \eta \end{pmatrix}$$

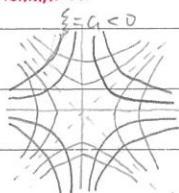
under the assumption that  $F$  is  $C^1$  and  $D = \begin{vmatrix} f_x & f_y \\ g_x & g_y \end{vmatrix} \neq 0$  at  $(x_0, y_0)$

Ex 1. Curvilinear coordinates

$$\xi = f(x, y) = x^2 - y^2, \quad \eta = g(x, y) = 2xy$$

$$D = \begin{vmatrix} 2x & -2y \\ 2y & 2x \end{vmatrix} = 4(x^2 + y^2) \neq 0 \quad \text{unless } (x, y) = 0 \leftarrow (x, y), (-x, -y) \text{ give the same } (\xi, \eta)$$

determinant

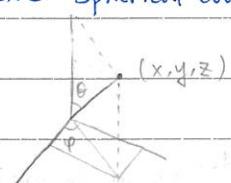


conformal mapping

$$\xi + i\eta = x^2 - y^2 + 2ixy = (x + iy)^2 = z^2$$

$$\mathbb{R}^2 \xrightarrow[(u,v)]{(x,y,z)} \mathbb{R}^3 \quad \mathbf{x}(u, v) = (x(u, v), y(u, v), z(u, v))$$

Ex 2. Spherical coordinates  $\begin{pmatrix} r \\ \theta \\ \varphi \end{pmatrix} \mapsto \begin{pmatrix} x \\ y \\ z \end{pmatrix}$



$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = ?$$

$$\varphi = ?$$

$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

$$z = r \cos \theta$$

$$J = \det [\mathbf{x}_r \mathbf{x}_\theta \mathbf{x}_\varphi] = \begin{vmatrix} \sin \theta \cos \varphi & r \cos \theta \cos \varphi & -r \sin \theta \sin \varphi \\ \sin \theta \sin \varphi & r \cos \theta \sin \varphi & r \sin \theta \cos \varphi \\ \cos \theta & -r \sin \theta & 0 \end{vmatrix} = r^2 \sin \theta$$

matrix notations & chain rule:

$$dx := x_u du + x_v dv \quad dy := y_u du + y_v dv$$

$$\left( \begin{array}{c} dx \\ dy \end{array} \right) = \left( \begin{array}{cc} x_u & x_v \\ y_u & y_v \end{array} \right) \left( \begin{array}{c} du \\ dv \end{array} \right) \Rightarrow d\vec{x} = [x_u \ x_v] d\vec{u} \quad \leftarrow \vec{x}(p+\vec{h}) - \vec{x}(p) = A \cdot \vec{h} + o(|\vec{h}|)$$

$$\vec{x} \quad \vec{u} \quad \vec{\vec{z}} \quad \vec{x}' = D\vec{x} = \frac{d\vec{x}}{d\vec{u}}$$

$$\left( \begin{array}{c} x \\ y \end{array} \right) \xrightarrow{G=\left( \begin{array}{c} u \\ v \end{array} \right)} \left( \begin{array}{c} u \\ v \end{array} \right) \xrightarrow{F=\left( \begin{array}{c} \vec{z} \\ \eta \end{array} \right)} \left( \begin{array}{c} \vec{z} \\ \eta \end{array} \right)$$

$$d\vec{u} = G' d\vec{x} \Rightarrow d\vec{\vec{z}} = F' d\vec{u} = F' \circ G' d\vec{x}$$

$$\text{def: } = (F \circ G)' d\vec{x}$$

$$\text{chain rule: } (F \circ G)'(p) = F'(G(p)) \circ G'(p)$$

$$\text{if } F = G^{-1} \text{ ie. } F \circ G = \text{id} \quad F(G(\vec{x})) = \vec{x}$$

$$F'(G(\vec{x})) \cdot G'(\vec{x}) = I_n$$

$$\text{Ex. } \left( \begin{array}{cc} x_u & x_v \\ y_u & y_v \end{array} \right) \left( \begin{array}{cc} u_x & u_y \\ v_x & v_y \end{array} \right) = \left( \begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right)$$

$$\left( \begin{array}{cc} x_u & x_v \\ y_u & y_v \end{array} \right) = \frac{\begin{pmatrix} v_y - u_y \\ -v_x + u_x \end{pmatrix}}{D}$$

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Dependent functions

$$D = \begin{vmatrix} \phi_x & \phi_y \\ \psi_x & \psi_y \end{vmatrix} = 0 \quad \stackrel{1 \circ 2 \circ 3 \circ}{\textcircled{①}} \quad \text{1.2 不確定反函數是否存在} \quad 3. \text{ dependent function}$$

$D \neq 0$  at  $(x_0, y_0)$   $\xrightarrow{\text{IFT}} \exists$  inverse locally near  $(x_0, y_0)$

$$\text{eg. } y = f(x) = x^3$$

$$\frac{dy}{dx} = 3x^2 = 0 \quad \underset{\text{at } x=0}{\uparrow} \quad \Rightarrow x = y^{1/3} \text{ still exists though it is not differentiable}$$

$$\text{eg. } \begin{cases} u = x^3 \\ v = y \end{cases} \quad D = \begin{vmatrix} 3x^2 & 0 \\ 0 & 1 \end{vmatrix} = 3x^2 \quad D = 0 \text{ along the } y\text{-axis}$$

$$\text{eg. } \begin{cases} u = x+y+z \\ v = x^2+y^2+z^2 \\ w = xy+yz+zx \end{cases} \Rightarrow v+2w=u^2$$

$$D = \begin{vmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ 2x & 2y & 2z \\ y+z & z+x & x+y \end{vmatrix} \underset{\text{2nd row}}{\cancel{\times \frac{1}{2}}} = 0$$

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Condition : If  $u = \phi(x, y)$ ,  $v = \psi(x, y)$  satisfies  $\begin{vmatrix} \phi_x & \phi_y \\ \psi_x & \psi_y \end{vmatrix} \equiv 0$

• If  $\phi_x \equiv 0 \equiv \phi_y$ , then  $\phi = \text{constant}$ .

• Otherwise, we may assume that  $\phi_x \neq 0$  in  $U \ni (x_0, y_0)$

Then we may solve  $x = \chi(u, y)$  st.  $u = \phi(\chi(u, y), y)$ ,  $v = \psi(\chi(u, y), y)$  for any  $(u, y)$

$$\frac{\partial v}{\partial y} = \psi_x \chi_y + \psi_y = \psi_x \left( -\frac{\phi_y}{\phi_x} \right) + \psi_y = \frac{\psi_y}{\phi_x} \equiv 0 \Rightarrow v = \chi(u, y) = \chi(u) \text{ is independent of } y$$

$$0 = \frac{\partial u}{\partial y} = \phi_x \chi_y + \phi_y \quad \text{i.e. } \psi(\chi(u, y), y) = \chi(u) = \chi(\phi(\chi(u, y), y))$$

$(u, y)$  independent variables

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$$F' = \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial y} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial y} \end{pmatrix}$$

If  $\frac{d(\chi, \eta)}{d(x, y)} = D(x_0, y_0) = \det F'(x_0, y_0) \neq 0$ ,  $\exists F^{-1}$  locally

Solve the inverse mapping near  $u_0 = F(x_0)$

Assumption:  $F \in C^1$ ,  $F'(x_0)$  is invertible as a matrix

Given  $u$  near  $u_0$ , we want to solve  $\mathbf{x} = G(\mathbf{x}) := \mathbf{x} + A(u - F(\mathbf{x}))$   
 $\uparrow$   $\uparrow$  any invertible matrix  
expect to hold for some  $\mathbf{x}$

$\mathbf{x} \mapsto G(\mathbf{x})$  is a dynamical system

fixed point:  $\mathbf{x} = G(\mathbf{x}) \Leftrightarrow u = F(\mathbf{x})$

$$G'(\mathbf{x}) = I - AF'(\mathbf{x})$$

pick  $F'(\mathbf{x})^{-1}$ , then  $G'(\mathbf{x}_0) = 0$

$$|G(\mathbf{y}) - G(\mathbf{x})| \leq \sum_{i=1}^n |\nabla g_i(\mathbf{x} + \theta_i(\mathbf{y} - \mathbf{x})) \cdot (\mathbf{y} - \mathbf{x})| \quad |G(\mathbf{y}) - G(\mathbf{x})| = \sqrt{\sum_{i=1}^n (g_i(\mathbf{y}) - g_i(\mathbf{x}))^2}$$

$$\leq \left( \sum_{i=1}^n \max_{\mathbf{xy}} |\nabla g_i| \right) |\mathbf{y} - \mathbf{x}| = \sqrt{\sum_{i=1}^n (\nabla g_i \cdot (\mathbf{y} - \mathbf{x}))^2} \leq \sqrt{\sum_{i=1}^n nM^2 |\mathbf{y} - \mathbf{x}|^2} = nM |\mathbf{y} - \mathbf{x}|$$

Pick  $\delta > 0$  small st.

$$|\mathbf{x} - \mathbf{x}_0| < \delta \text{ st. } \left| \frac{\partial g_i}{\partial x_j}(\mathbf{x}) \right| < \frac{1}{2n^2} \quad \forall i, j \quad \left( \text{since } G'(\mathbf{x}_0) = 0 \right) \quad |G(\mathbf{x}_0) - \mathbf{x}_0| < \frac{\delta}{2}$$

$$\text{let } \mathbf{x}_{n+1} = G(\mathbf{x}_n), \quad n=0, 1, \dots \quad \text{i.e. } |u - F(\mathbf{x})| < \frac{\delta}{2|A|}$$

$$|\mathbf{x}_{n+1} - \mathbf{x}_0| \leq |\mathbf{x}_{n+1} - \mathbf{x}_1| + |\mathbf{x}_1 - \mathbf{x}_0| = |G(\mathbf{x}_n) - G(\mathbf{x}_0)| + |\mathbf{x}_1 - \mathbf{x}_0| \leq \frac{1}{2} |\mathbf{x}_n - \mathbf{x}_0| + \frac{\delta}{2} < \delta$$

$$\left( \text{Claim } \mathbf{x}_n \in B_\delta(\mathbf{x}_0) \quad \forall n, \quad \text{if } n=0, |G(\mathbf{x}_0) - \mathbf{x}_0| = |A(u - F(\mathbf{x}_0))| \leq |A| \cdot |u - F(\mathbf{x}_0)| < \frac{\delta}{2} \right)$$

$\mathbf{x} = \lim_{n \rightarrow \infty} \mathbf{x}_n$  exists by absolute convergence

check  $|A\mathbf{x}| \leq |A||\mathbf{x}|$

$$\mathbf{x}_n = \mathbf{x}_0 + (\mathbf{x}_1 - \mathbf{x}_0) + \dots + (\mathbf{x}_n - \mathbf{x}_{n-1}) \quad |\mathbf{x}_k - \mathbf{x}_{k-1}| \leq \frac{1}{2^{k-1}} |\mathbf{x}_1 - \mathbf{x}_0|$$

Chenyu culture  $\mathbf{x}_{n+1} = G(\mathbf{x}_n) \Rightarrow \mathbf{x} = G(\mathbf{x})$

此證明和維數無關 (優點)、無法說明一次只須換一個變數 (缺點)

## 3.4 3.5 微分幾何 intro.

3.4 Geometric Application: To describe surfaces in  $\mathbb{R}^3$ 

$$(u, v) \in U \mapsto \mathbb{R}^3 \ni (x(u, v), y(u, v), z(u, v))^t = \mathbf{x}(u, v)$$

open  $\subset \mathbb{R}^2$

 $\mathbf{x}_u, \mathbf{x}_v$  form a basis of  $T_{\mathbf{x}(p)} S$ 

$$\frac{d}{dt} \mathbf{x}(u(t), v(t)) = \mathbf{x}_u u'(t) + \mathbf{x}_v v'(t) = \mathbf{x}' \begin{pmatrix} u' \\ v' \end{pmatrix} \quad \mathbf{x}' = (\mathbf{x}_u, \mathbf{x}_v)$$

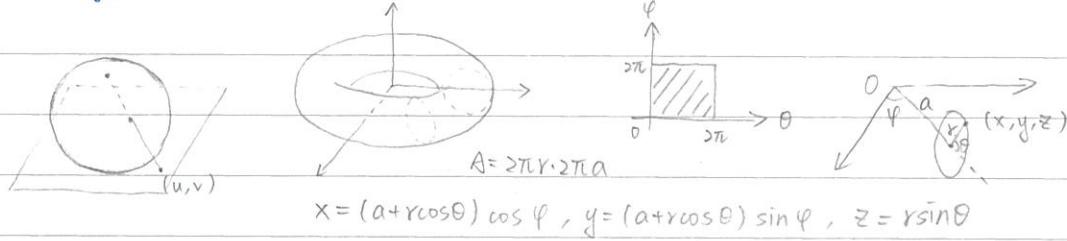
$$\begin{pmatrix} u' \\ v' \end{pmatrix} = u'e_1 + v'e_2$$

$$\begin{aligned} \left( \frac{ds}{dt} \right)^2 &= \frac{d\mathbf{x}}{dt} \cdot \frac{d\mathbf{x}}{dt} = (\mathbf{x}_u \frac{du}{dt} + \mathbf{x}_v \frac{dv}{dt}) \cdot (\mathbf{x}_u \frac{du}{dt} + \mathbf{x}_v \frac{dv}{dt}) \\ &= (\mathbf{x}_u \cdot \mathbf{x}_u) \left( \frac{du}{dt} \right)^2 + 2(\mathbf{x}_u \cdot \mathbf{x}_v) \frac{du}{dt} \cdot \frac{dv}{dt} + (\mathbf{x}_v \cdot \mathbf{x}_v) \left( \frac{dv}{dt} \right)^2 \end{aligned}$$

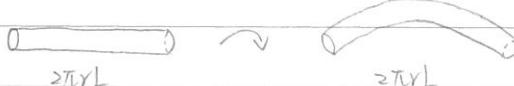
 $ds^2 = E du^2 + 2F du dv + G dv^2$  Gauss First fundamental form

$$= (du \ dv) \begin{pmatrix} E & F \\ F & G \end{pmatrix} \begin{pmatrix} du \\ dv \end{pmatrix}$$

$$= \sum_{i,j=1}^2 g_{ij} du^i du^j \quad \text{算向量長度}$$



$$x = (a + r \cos \theta) \cos \varphi, \quad y = (a + r \cos \theta) \sin \varphi, \quad z = r \sin \theta$$



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Multiple Integrals: definition of area, volume etc.

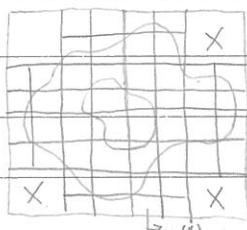
$$A \subset \mathbb{R}^2 \quad |A| \equiv \text{area } A$$

• for (closed) rectangle:  $R = [a, b] \times [c, d]$ ,  $|R| = (b-a) \times (d-c)$ • if  $S_1, S_2, \dots, S_N$  are disjoint sets and  $|S_i|$  is defined, then  $|\cup S_i| = \sum_{i=1}^N |S_i|$ recall on  $\mathbb{R} > \mathbb{Q}$  - does not have length

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"Jordan measurable set"

Outer measure  $A_n^+(S) \downarrow A^+(S)$



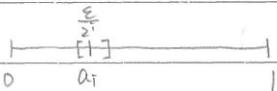
↓  
the sum of area of those sub rectangles containing points of  $S$

Inner measure  $A_n^-(S) \nearrow A^-(S)$

the sum of area of  $R_{ij}^{(n)} \subset S$

$S$  is Jordan measurable if  $A^+(S) = A^-(S)$

(Q is not Jordan measurable, but it has Lebesgue measure = 0)



Fact:  $S$  has a Jordan measure  $\Leftrightarrow |AS| = 0$  ( $|AS|$  可能不存在,  $A^-(AS) = 0$ )

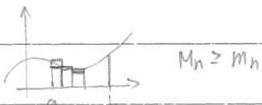
pf.  $\Leftarrow A_n^+(S) - A_n^-(S) \leq A_n^+(AS)$  we may have  $R_{ij}^{(n)} \subset S$  but  $R_{ij}^{(n)} \cap AS \neq \emptyset$

$n \rightarrow \infty$  get  $A^+(S) = A^-(S)$

$\Rightarrow \sum_{i=1}^n (A_i^+ - A_i^-) \geq A_n^+(AS)$

Tarski's Paradox.  $\exists$  partition  $S^2 = \bigcup_{i=1}^N A_i$   $\exists T_i \in SO(3) = \{T \mid T^t T = I_3\}$  orthogonal transformation  
 $\bigcup_{i=1}^N T_i(A_i) = S^2 \sqcup S^2 \Rightarrow$  所有面積定義對  $S^2$  都不存在

Example.  $y = f(x) \in C^0 \quad \int_a^b f(x) dx$



Definition of Riemann integral over a Jordan measurable set

$S \subset \mathbb{R}^n$  st.  $|S|$  exists  $f: S \rightarrow \mathbb{R}$  continuous function

$\int_S f(x_1, \dots, x^n) dx_1 \dots dx^n$

graph of  $f$   
 $y = f(x_1, x_2)$



Theorem (Fubini, the simple form)  $R = [a, b] \times [c, d]$   $\int_R f(x, y) dx dy = \int_c^d dy \int_a^b f(x, y) dx$

Example  $I = \int_0^\infty \frac{e^{-ax} - e^{-bx}}{x} dx \quad a > 0, b > 0$  (上學期習題)

$$= \log \frac{b}{a}$$

$$\begin{aligned} I &= \lim_{T \rightarrow \infty} \int_0^T dx \int_a^b e^{-yx} dy = \lim_{T \rightarrow \infty} \int_a^b dy \int_0^T e^{-xy} dx = \lim_{T \rightarrow \infty} \int_a^b dy \cdot \left[ -\frac{e^{-xy}}{y} \right]_0^T = \lim_{T \rightarrow \infty} \int_a^b \frac{1}{y} - \frac{e^{-Ty}}{y} dy \\ &= \lim_{T \rightarrow \infty} \log y \Big|_a^b - \int_a^b \frac{e^{-Ty}}{y} dy = \log \frac{b}{a} \end{aligned}$$

pf. LHS =  $\lim_{m, n \rightarrow \infty} \sum_{v=1}^n \sum_{u=1}^m f(a+uh, c+vk) \cdot hk$

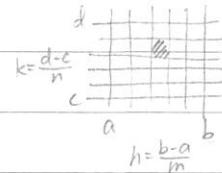
$\forall \epsilon > 0, \exists N$  s.t.  $\forall m, n \geq N \Rightarrow | - \int | < \epsilon$

Denote by  $\Xi_u = \sum_{v=1}^n f(a+uh, c+vk) \cdot h$

$$\left| \int_R f(x, y) dx dy - \sum_{v=1}^n \Xi_u \cdot k \right| < \epsilon, \text{ true } \forall m, n \geq N$$

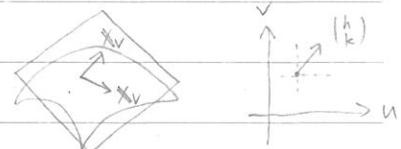
let  $m \rightarrow \infty, \lim_{m \rightarrow \infty} \Xi_u = \int_a^b f(x, c+vk) dx = \phi(c+vk)$

$$\left| \int_R f(x, y) dx dy - \sum_{v=1}^n \phi(c+vk) k \right| \leq \epsilon$$



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Conformal mapping  $\mathbb{X}: U \xrightarrow{\cong} \mathbb{R}^3 \quad (u, v)^t \mapsto (x, y, z)^t$



$$\mathbb{X}' = (\mathbb{X}_u \mathbb{X}_v) \quad \mathbb{X}' \begin{pmatrix} h \\ k \end{pmatrix} = \mathbb{X}_u \cdot h + \mathbb{X}_v \cdot k \in T_{(u,v)} S$$

Theorem.  $\mathbb{X}$  is conformal  $\Leftrightarrow ds^2 = E(du^2 + dv^2)$  i.e.  $E = G$  &  $F = 0$

pf.  $\Rightarrow e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad e_1 \perp e_2 \quad F = \mathbb{X}_u \cdot \mathbb{X}_v = 0$

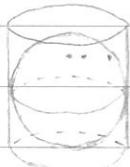
$$e_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, e_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \Rightarrow (\mathbb{X}_u + \mathbb{X}_v) \cdot (-\mathbb{X}_u + \mathbb{X}_v) = 0 \Rightarrow E = G$$

$\Leftarrow$

$$\begin{aligned} (\mathbb{X}_2(t), \mathbb{X}_3(t)) &\Rightarrow \mathbb{X}_u \mathbb{X}_2' + \mathbb{X}_v \cdot \mathbb{X}_2' \\ (\mathbb{X}_1(t), \mathbb{X}_3(t)) &\Rightarrow \mathbb{X}_u \mathbb{X}_1' + \mathbb{X}_v \cdot \mathbb{X}_1' \end{aligned}$$

$$\begin{aligned} \cos \theta &= \frac{(\mathbb{X}_u \mathbb{X}_1' + \mathbb{X}_v \cdot \mathbb{X}_1') \cdot (\mathbb{X}_u \mathbb{X}_2' + \mathbb{X}_v \cdot \mathbb{X}_2')}{|\mathbb{X}_u \mathbb{X}_1' + \mathbb{X}_v \cdot \mathbb{X}_1'| \cdot |\mathbb{X}_u \mathbb{X}_2' + \mathbb{X}_v \cdot \mathbb{X}_2'|} \\ &= \frac{E(u' u_2' + v' v_2')}{\sqrt{E(u'^2 + v'^2)} \cdot \sqrt{E(u_2'^2 + v_2'^2)}} \end{aligned}$$

= cos of the original angle on the  $u-v$  plane



check the ratio's cancel

out to get 1

$O: r \sin \theta \mapsto r$

I :  $ds \mapsto dss \sin \theta$



•  $R = [a, b] \times [c, d]$   $\int_R f(x, y) dx dy = \int_c^d dy \int_a^b f(x, y) dx$

•  $R$  is a convex set  $\int_R f \cdot dA = \int_a^b dx \int_{\psi_0(x)}^{\psi_1(x)} f(x, y) dy$

$\int_{R \cap R_1} f dA = \int_{R_1} f dA + \int_{R_2} f dA$  if  $R_1 \cap R_2 = \emptyset$

→ this holds for  $R^{(n)}$

$\int_{R^{(n)}} f dA = \int_{a^{(n)}}^{b^{(n)}} dx \int_{\psi_0^{(n)}(x)}^{\psi_1^{(n)}(x)} f(x, y) dy$

now let  $n \rightarrow \infty$

$\rightarrow \int_R f dA = \int_a^b dx \int_{\psi_0(x)}^{\psi_1(x)} f(x, y) dy$  ( $\psi_0, \psi_1$  conti.)

$|\int_{R^{(n)}} f dA - \int_R f dA| \leq M A_h^+(R)$ ,  $|f| \leq M$

Mean Value Theorem:  $\frac{1}{|R|} \int_R f dA = f(p)$  for some  $p \in R$ ,  $f \in C^0$

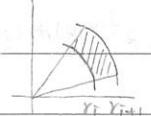
• Example:  $I = \int_{-\infty}^{\infty} e^{-x^2} dx$  Gaussian

$$I^2 = \int_{-\infty}^{\infty} e^{-x^2} dx \int_{-\infty}^{\infty} e^{-y^2} dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-(x^2+y^2)} dx dy$$

$$= \int_0^{2\pi} \int_0^{\infty} e^{-r^2} r dr d\theta = 2\pi \left(-\frac{1}{2} e^{-r^2}\right) \Big|_0^{\infty} = \pi$$

$$D = \begin{vmatrix} \cos\theta & -r\sin\theta \\ \sin\theta & r\cos\theta \end{vmatrix} = r$$

$$\Rightarrow I = \sqrt{\pi}$$



$$\Delta A = \frac{1}{2}((r+\Delta r)^2 - r^2) \Delta\theta$$

$$= r\Delta r\Delta\theta + \frac{1}{2}\Delta r^2\Delta\theta$$

$$\Delta A = \frac{1}{8}(r_{i+1}^2 - r_i^2) \Delta\theta$$

•  $\int_R (\sqrt{1-x^2-y^2} - a) dx dy = \int_0^{2\pi} \int_0^{\sqrt{1-a^2}} (\sqrt{1-r^2} - a) r dr d\theta$

$$= \int_0^{2\pi} \left( -\frac{1}{3} (1-r^2)^{3/2} - \frac{a}{2} r^2 \right) \Big|_0^{\sqrt{1-a^2}} = 2\pi \left( -\frac{a^3}{3} + \frac{1}{3} - \frac{a}{2} + \frac{a^3}{2} \right) = \frac{\pi}{3} (a^3 - 3a + 2)$$

$$= \frac{\pi}{3} (a-1)^2 (a+2)$$

•  $x = r\sin\theta\cos\varphi$ ,  $y = r\sin\theta\sin\varphi$ ,  $z = r\cos\theta$  (dr)(rd\theta)(r\sin\theta d\varphi)

HW.  $\int_R \frac{dx dy}{(1-x^2-y^2)^2}$



•  $v_1, v_2, v_3 \in \mathbb{R}^5$

$$\|v\| = \sqrt{a_1^2 + \dots + a_5^2} = \sqrt{V^t V}$$

$(a_1, \dots, a_5)$

$v_1 \wedge v_2$  the parallelogram spanned by  $v_1, v_2$

$t_1 v_1 + t_2 v_2$   $\{t_1 v_1 + t_2 v_2 \mid 0 \leq t_1, t_2 \leq 1\}$

$$v = (v_1, v_2) = \sqrt{\det(V^t V)}$$

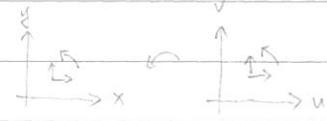
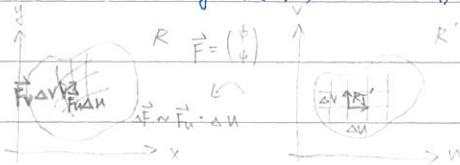
$v = (v_1, \dots, v_m) \in \mathbb{R}^n$

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Change of variable formula for multiple integrals

$$\int_R f(x,y) dx dy = \int_{R'} f(\phi(u,v), \psi(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

Assume  $\begin{cases} x = \phi(u,v) \\ y = \psi(u,v) \end{cases}$  is a  $C^1$  and 1-1 mapping from  $R'$  to  $R$  with  $D \neq 0$



$$\boxed{ } \leftrightarrow \boxed{ } | \vec{F}_u \Delta u, \vec{F}_v \Delta v | = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| \Delta u \Delta v \text{ at some point in } R'$$

primitive mapping e.g.  $\vec{x} = \vec{u}, y = \psi(\vec{u}, v)$   $\left| \frac{\partial(\vec{x}, y)}{\partial(\vec{u}, v)} \right| = \begin{vmatrix} 1 & \psi_u \\ 0 & \psi_v \end{vmatrix} = \psi_v$

proof of CVF for primitive mappings:

Assume  $x=u, y=\psi(u,v)$  gives a 1-1  $C^1$  mapping between  $R, R'$  which has  $\psi_v > 0$  on  $R'$

$$\Delta R_i = \int_{x_0}^{x_0+h} (\psi(x, v_{i+1}) - \psi(x, v_i)) dx = h \cdot (\psi(\tilde{x}_0, v_{i+1}) - \psi(\tilde{x}_0, v_i)), \quad \tilde{x}_0 \in [x_0, x_0+h]$$

area of  $R_i$

$$= h \cdot k \cdot \psi_v(\tilde{x}_0, \tilde{v}_i), \quad \tilde{v}_i \in [v_i, v_{i+1}]$$

Riemann Sum.  $\sum_i f(\tilde{x}_0, \psi(\tilde{x}_0, \tilde{v}_i)) \Delta R_i = \sum_i f(\tilde{x}_0, \psi(\tilde{x}_0, \tilde{v}_i)) \psi_v(P_i) h k$

let  $h, k \rightarrow 0$ .  $\int f(x, y) dx dy = \int f \circ F \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$

Lemma. If CVF holds for  $(x,y) = F_1(u,v)$  and  $(u,v) = F_2(\xi,\eta)$ , then it holds for

$$(x,y) = (F_1 \circ F_2)(\xi,\eta)$$

p.f.  $\int_R f(x,y) dx dy = \int_{R''} f \circ F_1(u,v) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv = \int_{R''} f \circ F_1 \circ F_2(\xi,\eta) \left| \frac{\partial(x,y)}{\partial(u,v)} \right|_{F_2(\xi,\eta)} \left| \frac{\partial(u,v)}{\partial(\xi,\eta)} \right| d\xi d\eta$

p.f for the general case

(Problem:  $r_p$  could vary when  $P$  varies) Then  $\{C_p^o(r_p)\}$  is an open cover of  $R$

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Heine-Borel Theorem: Any open cover of a compact set admit a finite subcover

$$\bigcup_{i \in \Lambda} U_i \supset R \Rightarrow \exists i_1, \dots, i_N \text{ (finite) st. } U_{i_1} \cup \dots \cup U_{i_N} \supset R$$

By Heine-Borel,  $\exists p^{(1)}, \dots, p^{(N)} \in R$  st.  $R \subset C_{p^{(1)}}^o(r_{p^{(1)}}) \cup \dots \cup C_{p^{(N)}}^o(r_{p^{(N)}})$

pick  $r = \min_{i \in \Lambda} (r_{p^{(i)}})$  and get a finite partition  $R = \bigcup R^{(i)}$

Now the "previous step" can be applied to  $R^{(i)} \cap C_{p^{(i)}}^o(r_{p^{(i)}})$

(when F is decomposable into primitive mappings)

Newton

$$\int_R -\frac{Gpm dx}{|r-r'|^3} (\vec{p} - \vec{q}) = \frac{GMm}{l^2}$$

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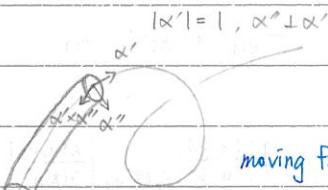
find the volume of the intersection of 2 cylinders in  $\mathbb{R}^3$   $\{x^2 + z^2 \leq 1\}, \{y^2 + z^2 \leq 1\}$

$$8 \int_R \sqrt{1-y^2} dx dy$$

$\stackrel{\wedge}{R^2} \{x^2+y^2 \leq 1, x \geq 0, y \geq 0\}$

$$= 8 \int_0^1 \sqrt{1-y^2} \int_0^{\sqrt{1-y^2}} dx dy$$

$$= 8 \int_0^1 (1-y^2) dy = 8(y - \frac{y^3}{3}) \Big|_0^1 = \frac{16}{3}$$



moving frame  $\{\vec{t}, \vec{n}, \vec{b}\}$ :  $\vec{t} = \alpha'$ ,  $\vec{n} = \frac{\alpha''}{|\alpha''|}$ ,  $\vec{b} = \vec{t} \times \vec{n}$

C: curve:  $\alpha(s)$ ,  $s \in [0, l]$

↑ arc length  $\ell = \text{length}(c)$

$$\mathbf{x}(s, \theta) = \alpha(s) + r(\cos \theta \vec{n} + \sin \theta \vec{b})$$

$$\int_0^{2\pi} \int_0^\ell |\mathbf{x}_s \times \mathbf{x}_\theta| ds d\theta$$

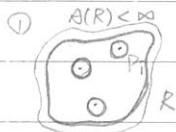
$$\begin{aligned} \mathbf{x}_s &= \vec{t} + r(\cos \theta \vec{n}' + \sin \theta \vec{b}'), \quad \mathbf{x}_\theta = r(-\sin \theta \vec{n} + \cos \theta \vec{b}) \\ &= \vec{t} + r(\cos \theta (-k\vec{t}' - \vec{b}') + \sin \theta \vec{b}') \\ &(\vec{b}' = \vec{t}' \times \vec{n} + \vec{t} \times \vec{n}' = \vec{t} \times \vec{n}') \end{aligned}$$

Chryculture  $\mathbf{x}_s \times \mathbf{x}_\theta = r(-\sin \theta \vec{b} + \cos \theta \vec{n})$

$$\vec{t}' = k\vec{n} \quad \vec{b}' = \alpha \vec{t} + \beta \vec{n}, \quad \alpha = \vec{b}' \cdot \vec{t} = (\vec{b} \cdot \vec{t})' - (\vec{b}' \cdot \vec{t}')$$

$$\begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix}' = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & -2 \\ 0 & 2 & 0 \end{pmatrix} \begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix}$$

## 5/10 4.7 Improper integral



f could be not continuous or even  $\not\in \mathbb{R}$  at some points  $p_i \in R$

②  $A(R) = \infty$

$$R = \mathbb{R}^2 \int_R e^{-x^2-y^2} dx dy$$

Theorem. let  $R$  be bounded with area (ie.  $R$  is Jordan-measurable)

(i)  $R_n \nearrow R$  ie.  $R_n \subset R_{n+1} \& A(R_n) \rightarrow A(R)$  st. f is conti. on  $R_n \forall n$

(ii)  $\int_{R_n} |f| \leq \mu \forall n$  (\*) not necessary

then  $I = \lim_{n \rightarrow \infty} \int_{R_n} f$  exists and is independent of choices of  $\{R_n\}$  in (i)

$$\text{Ex 1. } \int_{R=B_0(1)} \frac{dV}{|\vec{r}|^\alpha}, \vec{r}=(x,y,z) = \lim_{n \rightarrow \infty} \int_{R_n} r^{-\alpha} r^2 \sin \theta dr d\theta d\phi$$

$$= 2\pi (-\cos \theta) \Big|_0^\pi \cdot \underbrace{\int_0^1 r^{2-\alpha} dr}_{\text{require } 2-\alpha > -1 \text{ ie. } \alpha < 3}$$

Q: on  $\mathbb{R}^2$ ,  $1-\alpha > -1$  ie.  $\alpha < 2$ . How about  $\mathbb{R}^n$ ?  $\alpha < n$ ??

$$\text{Ex 2. } \text{if } |f(x,y,z)| \leq \frac{M}{\sqrt{y^2+z^2}^\alpha}, R = [a,b] \times "B_0(1)"$$

need only  $\alpha < 2$        $\int_R f(x,y,z) dx dy dz$  exists       $\hookrightarrow$  on y-z plane

pf of thm:  $I_n^+ := \int_{R_n} f$  is bounded by  $\mu$

$\Rightarrow I_n^+ \rightarrow I^+$  exists (and is a Cauchy sequence)

$\Rightarrow I_n := \int_{R_n} f$  is also a Cauchy sequence:

because  $|I_n - I_m| = |\int_{R_n} f - \int_{R_m} f| = |\int_{R_n \setminus R_m} f| \leq \int_{R_n \setminus R_m} |f| = I_n^+ - I_m^+ < \varepsilon$

$\Rightarrow I = \lim_{n \rightarrow \infty} I_n$  exists

for  $n, m > N(\varepsilon)$

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$S \subset R_n$  for some  $n$ .

Step 2.

Now, for any  $S \subset R$  closed,  $J = \int_S f$  is conti.

Need to check (\*): " $\int_S f \leq \mu$ "

$$|\int_S f - \int_{S \cap R_n} f| \leq A(S \setminus R_n) \cdot \sup_S |f| \xrightarrow{n \rightarrow \infty} 0 \quad (**)$$

similarly for  $|f|$ , get  $\int_S |f| = \lim_{n \rightarrow \infty} \int_{S \cap R_n} |f| \leq \mu$

$$\downarrow |\int_S f - \int_{S \cap R_n} f| = \lim_{m \rightarrow \infty} |\int_{S \cap R_m} f - \int_{S \cap R_n} f| \leq \lim_{m \rightarrow \infty} \int_{R_m \setminus R_n} |f| < \varepsilon \quad \text{Independent of } S$$

for  $m, n > N(\varepsilon)$

boot strapping

Now, for another sequence  $S_m \nearrow R$  satisfying (i),

then (ii) is also satisfied

so,  $J = \lim_{m \rightarrow \infty} \int_{S_m} f$  also exists

$$|J - \int_{S_m \cap R_n} f| \leq |J - \int_{S_m} f| + |\int_{S_m} f - \int_{S_m \cap R_n} f| < 2\varepsilon \text{ as long as } m, n > N(\varepsilon)$$

similarly,  $|I - \int_{S_m \cap R_n} f| < 2\varepsilon$

$$\Rightarrow |I - J| \leq 4\varepsilon \text{ but } \varepsilon \text{ is arbitrary}$$

$$\Rightarrow I = J$$

The case with unbounded  $R$ .

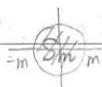
(i)'  $R_n \nearrow R$   
 $\searrow$  compact,  $J = m$  now require the "exhaustion condition": (every compact  $S \subset R$   
must be contained in  $R_n$  for  $n$  large)

(ii)'  $\int_{R_n} f \leq \mu \forall n$

then  $I := \lim_{n \rightarrow \infty} \int_{R_n} f$  exists and is independent of the choice of  $\{R_n\}$

Ex 3. Gauss' integral  $\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$

$$\lim_{n \rightarrow \infty} \int_{R_n} e^{-(x^2+y^2)} dx dy = \lim_{n \rightarrow \infty} \int_{S_m} f$$



## 4.8 More Application

Ex 4.  $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} \leq 1 \quad \frac{4}{3}\pi abc$

$$\begin{aligned} & \begin{cases} x = a\cos\theta \\ y = b\sin\theta \\ z = z \end{cases} \quad V = 2 \int_R c \sqrt{1 - (\frac{x}{a})^2 - (\frac{y}{b})^2} dx dy \\ & \Rightarrow \frac{\partial(x,y)}{\partial(r,\theta)} = abr \quad = 2abc \int_0^{2\pi} \int_0^1 \sqrt{1-r^2} r dr d\theta \\ & \quad = 4\pi abc \left( -\frac{1}{3}(1-r^2)^{3/2} \right) \Big|_0^1 = \frac{4}{3}\pi abc \end{aligned}$$

## Ex 5. Cylindrical coordinates

$$(x, y, z) \leftrightarrow (r, \theta, z)$$

Surface (Solid) of revolution

$$V = \int_R dV = \int_a^b dz \int_0^{2\pi} d\theta \int_0^{\phi(z)} r dr = \pi \int_a^b \phi^2(z) dz$$

$$S = \int_a^b dz \sqrt{1 + \phi'(z)^2} 2\pi \phi(z)$$

$$\text{In fact, } \mathbf{x}(z, \theta) = (\phi(z)\cos\theta, \phi(z)\sin\theta, z)$$

$$\mathbf{x}_z = (\phi'\cos\theta, \phi'\sin\theta, 1), \quad \mathbf{x}_\theta = (-\phi\sin\theta, \phi\cos\theta, 0)$$

$$F = \mathbf{x}_z \cdot \mathbf{x}_\theta = 0$$

$$E = \mathbf{x}_z \cdot \mathbf{x}_z = 1 + (\phi')^2, \quad G = \mathbf{x}_\theta \cdot \mathbf{x}_\theta = \phi^2$$

$$dA = \sqrt{EG - F^2} d\theta dz = \sqrt{1 + \phi'^2} \phi d\theta dz$$



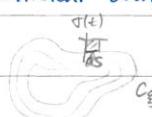
$$\phi(z) = \sqrt{R^2 - z^2}, \quad \phi'(z) = \frac{-z}{\sqrt{R^2 - z^2}}$$

$$\int_0^{\pi} \int_0^{\sqrt{R^2 - z^2}} \sqrt{1 + \phi'^2} \phi d\theta dz = 2\pi \frac{R}{\sqrt{R^2 - z^2}} \cdot \sqrt{R^2 - z^2} = 2\pi R$$

## 5/2 Multiple Integral in curvilinear coordinates (等高線積分法)



$$V(r) = \frac{4}{3}\pi r^3$$



$$\phi(x, y) = \frac{\xi}{\eta}$$

$$\phi(\xi, \eta) = \frac{\xi}{\eta}$$

$$\text{const.}$$

$$\xi = \xi(+), \eta = \eta(+)$$

$$d\xi = \left( \frac{\partial \xi}{\partial x} dx + \frac{\partial \xi}{\partial y} dy \right) dt$$

$$\int f(x, y) ds \frac{d\xi}{|\nabla \phi|}$$

$$\Rightarrow |d\xi| = \frac{d\xi}{|\nabla \phi|} dt$$

The more rigorous deduction of the "Co-Area formula"

pf. consider  $\begin{cases} \xi = \phi(x, y) \\ \eta = y \end{cases} \quad \frac{\partial(\xi, \eta)}{\partial(x, y)} = \phi_x \quad \frac{\partial(\xi, \eta)}{\partial(y, y)} = \frac{1}{\phi_x}$

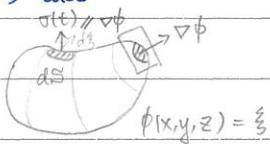
$$\int_R f dx dy = \int f \frac{d\xi d\eta}{|\nabla \phi|} = \int f \frac{d\xi}{\sqrt{\phi_x^2 + \phi_y^2}} \cdot \underbrace{\left( \frac{\sqrt{\phi_x^2 + \phi_y^2}}{|\nabla \phi|} d\eta \right)}_{ds}$$

$$x = f(y) \quad \phi(x, y) = \xi \leftarrow \text{fixed}$$

$$ds = \sqrt{1 + f_y^2} dy \quad \phi_x f_y + \phi_y = 0 \quad f_y = -\frac{\phi_y}{\phi_x}$$

$$ds = \sqrt{1 + (\frac{\phi_y}{\phi_x})^2} dy = \frac{\sqrt{\phi_x^2 + \phi_y^2}}{|\phi_x|} dy$$

3D case:



$$\int f dS \frac{d\xi}{|\nabla \phi|} = \int f dV$$

Example:  $f \equiv 1$  : calculate the volume

$$\phi(x, y, z) = r = \sqrt{x^2 + y^2 + z^2} \quad |\nabla \phi| = |\nabla r| = 1$$

$$dS = \frac{\sqrt{\phi_x^2 + \phi_y^2 + \phi_z^2}}{|\nabla \phi|} dy dz \quad \text{投影在 } yz \text{ 平面}$$

$$x = f(y, z) \quad dS = \sqrt{1 + f_y^2 + f_z^2} \quad ds = |\mathbf{x}_u \wedge \mathbf{x}_v| du dv$$

$$\phi(f(y, z), y, z) = \xi \quad \begin{cases} \phi_x f_y + \phi_y = 0 \\ \phi_x f_z + \phi_z = 0 \end{cases} \quad \sqrt{EG - F^2}$$

$$(cos \alpha, cos \beta, cos \gamma) = \frac{\nabla \phi}{|\nabla \phi|} = \frac{(\phi_x, \phi_y, \phi_z)}{\sqrt{\phi_x^2 + \phi_y^2 + \phi_z^2}}$$

Application.

Area, Volume

$$\text{(1) } |B_0^n(R)| = ? \quad \text{(2) } |S_0^{n-1}(R)| = ?$$

$$\downarrow \quad \downarrow$$

$$\{ \vec{x} \in \mathbb{R}^n \mid |\vec{x}| \leq R \} \quad \{ \vec{x} \in \mathbb{R}^n \mid |\vec{x}| = R \}$$

$$\text{(1) } x_1^2 + \dots + x_n^2 \leq R^2$$

$$V^n(R) = 2 \int_0^R V^{n-1}(\sqrt{R^2 - x_n^2}) dx_n = 2 V^{n-1}(1) \int_0^R (R^2 - x^2)^{n/2} dx$$

$$V^n(1) = * V^{n-1}(1)$$

$$P(n+1) = n! \quad P(n+\frac{1}{2}) \quad P(\frac{1}{2}) =$$

$$\int_0^{\frac{\pi}{2}} \cos^n \theta d\theta = \cos^{n-1} \theta \sin \theta \Big|_0^{\frac{\pi}{2}} + \int_0^{\frac{\pi}{2}} (n-1) \cos^{n-2} \theta (1 - \cos^2 \theta) d\theta$$

$$= (n-1) \int_0^{\frac{\pi}{2}} \cos^{n-2} \theta d\theta - (n-1) \int_0^{\frac{\pi}{2}} \cos^n \theta d\theta$$

$$\int_0^{\frac{\pi}{2}} \cos^n \theta d\theta = \frac{n-1}{n} \int_0^{\frac{\pi}{2}} \cos^{n-2} \theta d\theta$$

No.

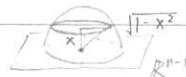
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 $V^n(R) = n\text{-dim volume of } B_o^n(R) = V^n(1) \cdot R^n$  $A^{n-1}(R) = (n-1)\text{-dim area of } S_o^{n-1}(R) = A^{n-1}(1) \cdot R^{n-1} \leftarrow \text{explain it!}$ 

$\frac{d}{dR} V^n(R) = A^{n-1}(R) \Rightarrow nV^n(1) = A^{n-1}(1)$

$V^n(1) = 2 \int_0^1 V^{n-1}(\sqrt{1-x_n^2}) dx_n$



$$= 2 \int_0^1 V^{n-1}(1) (1-x_n)^{\frac{n-1}{2}} dx_n = 2 V^{n-1}(1) \int_0^{\frac{\pi}{2}} \cos^{n-1} \theta \cdot \cos \theta \cdot d\theta = \begin{cases} \frac{n-1}{n} \cdot \frac{n-3}{n-2} \cdots \frac{1}{2} \cdot \frac{\pi}{2} & (n \text{ even}) \\ \frac{n-1}{n} \cdot \frac{n-3}{n-2} \cdots \frac{2}{3} \cdot 1 & (n \text{ odd}) \end{cases} \cdot 2 V^{n-1}(1)$$

$x_n = \sin \theta$

$n=2k, V^{2k}(1) = V^{2k-1}(1) \cdot \frac{2k-1}{2k} \cdots \frac{1}{2} \cdot \pi = V^{2k-2}(1) \cdot \frac{1}{2k} \cdot 2\pi = \cdots = \frac{\pi^k}{k!}$

$n=2k+1, V^{2k+1}(1) = V^{2k}(1) \cdot \frac{2k}{2k+1} \cdots \frac{2}{3} \cdot 2 = V^{2k-1}(1) \cdot \frac{2}{2k+1} \cdot \pi = \cdots = V^1(1) \cdot \frac{2^k \pi^k}{(2k+1)!} \cdots 2$

$\omega_n := A^{n-1}(1)$

$\text{co-area formula: } \int_R f(x_1, \dots, x_n) dx_1 \cdots dx_n = \int_R \frac{f}{|\nabla \phi|} d\xi dA$

$dA = \frac{\sqrt{\phi_{x_1}^2 + \dots + \phi_{x_n}^2}}{|\nabla \phi|} dx_1 \cdots dx_{n-1} \leftarrow \phi(x_1, \dots, x_n) = \xi$

$dA = \sqrt{1 + f_{x_1}^2 + \dots + f_{x_{n-1}}^2} dx_1 \cdots dx_{n-1} \leftarrow x_n = f(x_1, \dots, x_{n-1})$

$r = \xi = \phi = \sqrt{x_1^2 + \dots + x_n^2} \quad |\nabla \phi| = 1$

$\int_{R^n} f dV = \int_{R^n} f dr dA$

pick  $f = e^{-(x_1^2 + \dots + x_n^2)}$  ↳ area element on  $S_o^{n-1}(r)$ 

$\pi^{\frac{n}{2}} = \prod_{i=1}^n \int_{-\infty}^{\infty} e^{-x_i^2} dx_i = A^{n-1}(1) \int_0^{\infty} e^{-r^2} r^{n-1} dr$

$\text{let } s = r^2 \quad ds = 2r dr \quad \frac{1}{2} \int_0^{\infty} e^{-s} s^{\frac{n-1}{2}-\frac{1}{2}} ds = \frac{1}{2} \Gamma\left(\frac{n}{2}\right), \Gamma(s+1) = s\Gamma(s), \Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}$

$\int_0^{\infty} e^{-s} s^{k-1} ds = \Gamma(k) \quad \text{if } k \in \mathbb{N}, \Gamma(k) = (k-1)!$

Integration / differentiation of improper integrals with a parameter

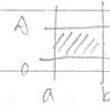
Def:

$F(x) = \int_0^{\infty} f(x, y) dy \quad x \in [a, b] \quad \text{converges uniformly if } \forall \varepsilon > 0 \exists A \text{ st. } \left| \int_B^{\infty} f(x, y) dy \right| < \varepsilon$

$\forall B \geq A \quad (\forall x \in [a, b])$

Simple test: " $|f(x, y)| < \frac{M}{y^{\alpha}}$  for  $y \geq y_0$  some  $\alpha > 1$ "  $\Rightarrow$  unif conv.Thm: Unif convergence  $\Rightarrow F(x)$  is conti. on  $[a, b]$ Given  $\varepsilon$ 

$|F(x+h) - F(x)| < \left| \int_0^A (f(x+h, y) - f(x, y)) dy \right| + 2\varepsilon$

choose  $A$ choose  $h$  small (depend on  $A$ ) st.  $|f(x+h, y) - f(x, y)| < \frac{\varepsilon}{A}$ 

$\Rightarrow |F(x+h) - F(x)| < 3\varepsilon$

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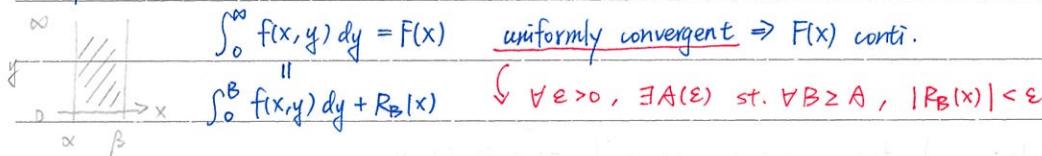
Similarly  $F(x) = \int_x^\beta f(x,y) dy$  but  $y \rightarrow \infty$  has  $\infty$ -discontinuity wif conv.

def: Given  $\epsilon > 0 \exists k$  st.  $|\int_x^{x+h} f(x,y) dy| < \epsilon \forall h \leq k$

Test.  $|f(x,y)| < \frac{M}{(y-\alpha)^2} (0 < 1)$

Integrals.  $\int_\alpha^\beta dx \int_0^\infty f(x,y) dy = \int_0^\infty dy \int_\alpha^\beta f(x,y) dx$   $A \rightarrow \infty$   
 $+ \int_A^\infty dy \int_\alpha^\beta f(x,y) dx$

5/9



$$\int_\alpha^\beta dx \int_0^\infty f(x,y) dy = \int_0^\infty dy \int_\alpha^\beta f(x,y) dx$$

pf.  $\int_\alpha^\beta dx \int_0^\infty f(x,y) dy + \int_\alpha^\beta R_B(x) dx = \int_0^\infty dy \int_\alpha^\beta f(x,y) dx + \int_\alpha^\beta R_B(x) dx$   
 $|\int_\alpha^\beta R_B(x) dx| \leq (\beta - \alpha) \epsilon$

Thus  $\Rightarrow " = "$

For exchange of integral like  $\int_0^\infty dy \int_0^\infty f(x,y) dx$ , so far we only know that it holds if

$\int_{\mathbb{R}^2} |f(x,y)| dxdy$  exists

Differentiation: Suppose that  $f(x,y)$  is piece-wise conti. on  $x \in [\alpha, \beta]$

and  $F(x) = \int_0^\infty f(x,y) dy$ ,  $G(x) = \int_0^\infty f(x,y) dy$  exist uniformly,

then  $F'(x) = G$

pf.  $\int_\alpha^\xi G(x) dx = \int_\alpha^\xi dx \int_0^\infty f(x,y) dy = \int_0^\infty dy \int_\alpha^\xi f(x,y) dx = \int_0^\infty (f(\xi, y) - f(\alpha, y)) dy$   
 $= F(\xi) - F(\alpha)$

$$\Rightarrow F'(x) = G(x)$$

Fubini Thm.  $\Rightarrow$  integral exchange  $\Rightarrow$  differentiation exchange is another possible way to prove (review)

$$\frac{d}{dx} \int_0^\infty f(x,y) dy$$

$x > 0$ 

$$\text{Example 1. } \int_0^\infty e^{-xy} dy = -\frac{e^{-xy}}{x} \Big|_0^\infty = \frac{1}{x}$$

$$\stackrel{\uparrow}{\text{unif. conv.}} -\frac{e^{-xy}}{x} \Big|_0^\infty$$

$$\text{diff. in } x : \int_0^\infty y e^{-xy} dy = \frac{1}{x^2}$$

require the unif. conv. of  $\int_0^\infty y e^{-xy} dy$ 

$$\int_0^\infty y^n e^{-xy} dy = \frac{n!}{x^{n+1}}$$

$$y^n \cdot e^{-\frac{xy}{2}} \cdot e^{-\frac{xy}{2}} \leq M \Rightarrow \text{unif conv.}$$

$$\text{Example 2. } \int_0^\infty \frac{\sin y}{y} dy = \frac{\pi}{2}$$

支錯數列  $\Rightarrow$  收斂

$$\text{Let } F(x) = \int_0^\infty e^{-xy} \frac{\sin y}{y} dy$$

$$\int_0^\infty |...| \leq \int_0^\infty e^{-xy} = \frac{1}{x} \rightarrow 0$$

$$F'(x) = -\int_0^\infty e^{-xy} \sin y dy = \frac{e^{-xy}}{1+x^2}$$

$$F(x) = c - \tanh^{-1} x$$

but  $F(x)$  conti.

$$\text{let } x \rightarrow \infty \quad 0 = c - \frac{\pi}{2}$$

$$F(0) = c = \frac{\pi}{2}$$

$$\text{Example 3. Fresnel's integral } F_1 = \int_{-\infty}^\infty \sin(x^2) dx = 2 \int_0^\infty \sin(x^2) dx$$

$$t = x^2 \quad dt = 2x dx, \quad F_1 = \int_0^\infty \frac{\sin t}{\sqrt{t}} dt$$

$$f(x) \mapsto \hat{f}(y) := \frac{1}{\sqrt{2\pi}} \int_{-\infty}^\infty f(x) e^{-ixy} dx \quad f(x) \mapsto \hat{f}(y) \mapsto f(-x)$$

oscillation mode (phase)

$$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^\infty \hat{f}(y) e^{iyx} dy \quad \text{將微分方程轉化為代數方程}$$

$$v_1, \dots, v_m \in \mathbb{R}^n$$

$$v_1 \wedge \dots \wedge v_m = \left\{ \sum_{i=1}^m t_i v_i \mid 0 \leq t_i \leq 1 \right\} \quad m\text{-dim area} = \sqrt{\det(v^t v)}$$

$$V = (v_1 \dots v_m)_{n \times m}$$

$$v^t v = \begin{pmatrix} v_1^t \\ \vdots \\ v_m^t \end{pmatrix} (v_1 \dots v_m) = (v_i^t \cdot v_j)_{m \times m}$$

$$T \sim v_1 \dots v_m \quad \mathbb{R}^m \hookrightarrow \mathbb{R}^n$$

$$TV = \begin{pmatrix} \square \\ 0 \end{pmatrix}_{m \times m} \quad (TV)^t TV = V^t T^t TV = V^t V$$

$$(\square^t O) \begin{pmatrix} \square \\ 0 \end{pmatrix} = \square^t \square \quad \det V^t V = \det \square^t \square = (\det \square)^2$$

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$$u_1, \dots, u_m \in \mathbb{R}^m \xrightarrow{\quad X \quad} \mathbb{R}^n$$

$$X(u_1, \dots, u_m)$$

$$DX = \left( \frac{\partial X}{\partial u_1}, \dots, \frac{\partial X}{\partial u_m} \right)$$

$$\int f \sqrt{\det(DX)^t DX} du_1 \dots du_m$$

$$\begin{vmatrix} x_1 \cdot x_1 & x_1 \cdot x_2 \\ x_2 \cdot x_1 & x_2 \cdot x_2 \end{vmatrix}^{1/2} = \sqrt{EG - F^2}$$

## 5/24 Vector Calculus

$$\mathbb{R}^3 \xrightarrow{\quad} \text{G}, \text{H}, \text{A}, \text{B}_0(r)$$

Green's Theorem

Gauss' Theorem (divergence theorem) } Integration by parts

Stokes' Theorem

$$\int_a^b f dg = fg|_a^b - \int_a^b g df \Leftarrow \int_a^b df = f|_a^b$$

let  $f = gh$

Green's theorem

$$\int_C P dx + Q dy = \int_{\Omega} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

$$C = \partial \Omega$$

$$\omega = P dx + Q dy, C = \partial \Omega \quad \text{on the plane } \mathbb{R}^2 \quad \text{"form" } dx \wedge dy = -dy \wedge dx (\Rightarrow dx \wedge dx = 0)$$

$$\bullet \int_{\partial \Omega} \omega = \int_{\Omega} d\omega \quad df = \sum \frac{\partial f}{\partial x_i} dx_i \quad (\text{total diff})$$

$$d\omega = dP \wedge dx + dQ \wedge dy$$

$$= (P_x dx + P_y dy) \wedge dx + (Q_x dx + Q_y dy) \wedge dy$$

$$= (Q_x - P_y) dx \wedge dy$$

$$\Omega = [a, b], \omega = f \quad (0\text{-form})$$

$$f|_a^b = \int_a^b f' dx$$

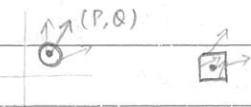
An equivalent form: 2-dim divergence thm.

$$\vec{F} = (P, Q) \quad \operatorname{div} \vec{F} := \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y}$$

(散度)

$$\int_{\Omega} (P_x + Q_y) dx dy = \int_{\partial \Omega} (-Q dx + P dy)$$

chuya culture



$$(P, Q), (Q, P)$$

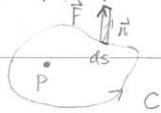
$$(dx, dy) = X'(t) dt$$

outer normal

$$\int_{\partial \Omega} \vec{F} \cdot (dy, -dx) = \int_{\partial \Omega} \vec{F} \cdot \vec{n} ds$$

$$\Rightarrow \lim_{\Delta \rightarrow P} \frac{1}{|\Delta|} \int_{\partial \Delta} \vec{F} \cdot \vec{n} ds = \lim_{\Delta \rightarrow P} \frac{1}{|\Delta|} \int_{\Delta} \operatorname{div} \vec{F} dA = \operatorname{div} \vec{F} \text{ at } P$$

通量 flux



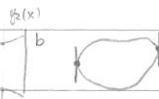
$$\int_{\partial \Delta} \omega = \int_{\Delta} d\omega$$

\*  $\int_{\partial \Delta} P dx + Q dy = \int_{\Delta} (Qx - Py) dx dy$  : for any 2  $C^1$  functions  $P$  &  $Q$  in  $\Delta$   
 $\partial \Delta = \bigcup C_i$ ,  $C_i$  piecewise  $C^1$  curve  
It is enough to prove \* for  $P$  &  $Q$  separately.

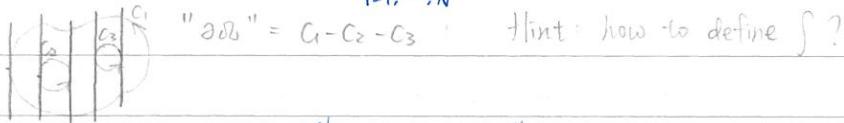
pf of \* (Green's thm) for  $P$ :

Step 1.  $\Delta$  is a region of the form:

$$\begin{aligned} \text{RHS} &= \int_{\Delta} -Py dx dy = - \int_a^b dx \left. P(x, y) \right|_{y_1(x)}^{y_2(x)} \\ &= \int_a^b P(x, y_1(x)) dx - \int_a^b P(x, y_2(x)) dx = \int_{\partial \Delta} P dx = \text{LHS} \end{aligned}$$



Step 2. Divide  $\Delta$  into subregions  $\Delta_i$  st. each  $\Delta_i$  is of the form in Step 1.



$$\text{Then RHS} = \int_{\Delta} -Py dx = \sum_{i=1}^N \int_{\Delta_i} -Py dx = \sum_{i=1}^N \int_{\partial \Delta_i} P dx = \int_{\partial \Delta} P dx$$

Similar pf works for  $Q$ , but with step 1. modified to be

$$\textcircled{1} \quad \int_{\Delta} \operatorname{div} \vec{F} dA = \int_{\partial \Delta} \vec{F} \cdot \vec{n} ds$$

$$\textcircled{2} \quad \int_{\Delta} \operatorname{curl} \vec{F} \cdot e_3 \cdot dA = \int_{\partial \Delta} \vec{F} \cdot d\vec{x}$$

$\cancel{Qx - Py}$

$$\vec{F} = \nabla f \quad \operatorname{div} \nabla f = (f_x)_x + (f_y)_y = f_{xx} + f_{yy} = \Delta f$$

$(\operatorname{grad} f) \quad \nabla \cdot$

$$\textcircled{1}: \int_{\Delta} \Delta f dA = \int_{\partial \Delta} \frac{\nabla f \cdot \vec{n}}{\partial f / \partial n} ds$$

$\text{an special notation}$   
 $\text{for normal derivatives}$

$$\vec{F} = g \nabla f \quad \operatorname{div} F = \nabla \cdot (g \nabla f) = \nabla g \cdot \nabla f + g \Delta f$$

$$\int_{\Delta} (\nabla g \cdot \nabla f + g \Delta f) = \int_{\partial \Delta} g \frac{\partial f}{\partial n} ds \quad \int_{\Delta} (\nabla f \cdot \nabla g + f \Delta g) = \int_{\partial \Delta} f \frac{\partial g}{\partial n} ds$$

$$\int_{\Delta} (f \Delta g - g \Delta f) = \int_{\partial \Delta} (f \frac{\partial g}{\partial n} - g \frac{\partial f}{\partial n}) ds$$

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1-form  
Green's thm.

$$\frac{5}{2}b \quad \oint_C \omega = \int_{\Omega} d\omega = \int_{\Omega} (\partial_x - \partial_y) dx dy$$

$$\int_C P dx + Q dy \longrightarrow \int_C \vec{F} \cdot d\vec{x} \quad \vec{x}(t) = (x(t), y(t)) \quad \vec{F} = (P, Q)$$

封閉曲線  
 $P(x, y), Q(x, y) \in C^1$

$$\int_C \vec{F} \cdot \vec{n} ds \quad \vec{F} = (Q, -P)$$

flux integral

## 1. Change of variable formula

$$I = \int_R f dx dy$$

$$\begin{cases} x = x(u, v) \\ y = y(u, v) \end{cases}$$

Step 1. Let  $f = Qx$  for some  $Q$

Step 2.

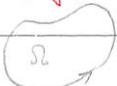
$$\begin{aligned} I &= \int_R f dx dy = \int_R Qx dx dy = \int_C Q dy = \int_C Q(x(u, v), y(u, v)) (y_u du + y_v dv) = \int_C (Q \cdot y_u) du + (Q \cdot y_v) dv \\ &= \int_{R'} ((Qy_v)_u - (Qy_u)_v) du dv = \int_{R'} (Q_x x_u \cdot y_v + Q_y y_u \cdot y_v + Q_{xy} y_{uv} - Q_x x_v \cdot y_u - Q_y y_v \cdot y_u - Q_{xy} y_{uv}) du dv \\ &= \int_{R'} Q_x \cdot \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} du dv = \int_{R'} f \cdot \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} du dv \end{aligned}$$

$y: C^2 \Rightarrow$  先前的證明條件較少

the area enclosed by a curve  $C$ .

$$A = -\int_C y dx = \int_C x dy = \frac{1}{2} \int_C x dy - y dx$$

$P = -y, Q = 0 \quad P = 0, Q = x$



isoperimetric inequality. Fix the length of a curve, find the maximal area enclosed by ( $= l$ ) such curves

$$4\pi A \leq l^2, " = " \text{ iff } C \text{ is a circle}$$

if  $C$  bounds  $\Omega$  with the maximal area

step 1. convex

step 2. for any  $|PQ| = \frac{l}{2}$ ,  $\overline{PQ}$  divide  $\Omega$  into two pieces into equal area

step 3. Only need to consider  $P, Q \in L$  with  $|PQ| = \frac{l}{2}$  fixed

$$\angle PRQ = \frac{\pi}{2}, \forall R \in \overline{PQ}$$



fix the shadow part, with  $P, Q$  allowed to move

$\Rightarrow \overline{PQ}$  is a half circle

## Poincaré

Suppose that  $\int_0^{\pi} f dx = 0$ , then  $\int_0^{\pi} f^2 \leq \int_0^{2\pi} f'^2$  " = " iff  $f = a \cos t + b \sin t$

$$f - \frac{1}{2} \int_0^{\pi} f dx$$

$$pf. \quad f = (a_1 \cos t + b_1 \sin t) + (a_2 \cos 2t + b_2 \sin 2t) + \dots$$

$$f' = (-a_1 \sin t + b_1 \cos t) + 2(-a_2 \sin 2t + b_2 \cos 2t) + \dots$$

$$\frac{1}{\pi} \int_0^{\pi} f^2 = (a_1^2 + b_1^2) + (a_2^2 + b_2^2) + \dots$$

$$\frac{1}{\pi} \int_0^{\pi} f'^2 = (a_1^2 + b_1^2) + 2(a_2^2 + b_2^2) + \dots$$

pf of isoperimetric inequality " $\ell^2 \geq 4\pi A$ ".

for simplicity, assume  $\ell = 2\pi$

$$A = \int_C xy' ds \quad 2\pi = \int_0^{2\pi} (x'^2 + y'^2) ds$$

we use arc length as parameter of  $C$ .

$$2(\pi - A) = \int_0^{2\pi} (x'^2 + y'^2) - 2xy' ds = \int_0^{2\pi} (x'^2 - x^2) ds + \int_0^{2\pi} (x - y')^2 ds \geq 0$$

Poincaré (Fourier)

" = " iff  $x(s) = a \cos s + b \sin s$ ,  $y(s) = a \sin s - b \cos s + c$

$$= \sqrt{a^2 + b^2} \cos(s + \theta_0) \quad = \sqrt{a^2 + b^2} \sin(s + \theta_0) + c$$

$$\int_{\partial\Omega} \vec{F} \cdot \vec{n} ds = \int_{\Omega} \operatorname{div} \vec{F} dA$$

散度

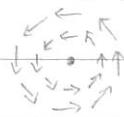
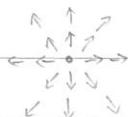
divergence

$$\int_{\partial\Omega} \vec{F} \cdot \vec{t} ds = \int_{\Omega} (\operatorname{curl} \vec{F})_z dA$$

旋度

vorticity, vortex

$$\operatorname{curl} \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$



$$\operatorname{div} \vec{F} = 0 \quad \Delta f = 0 \quad \text{harmonic function}$$

$$\Delta f$$

$$\Delta f = \frac{\partial^2 f}{\partial r^2} + \frac{1}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

$$rf' = f(r) : rf'' + f' = 0 \quad (rf')' = 0$$

$$rf' = \text{const.} \quad f' = \frac{c}{r} \quad f = c \log r + c_1 = \frac{c}{2} \log(x^2 + y^2) + c_1$$

$$\vec{F} = \nabla f = \left( \frac{c}{2} \cdot \frac{2x}{x^2 + y^2}, \frac{c}{2} \cdot \frac{2y}{x^2 + y^2} \right) = d \tan \frac{\theta}{2}$$

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$$\int_C \frac{Pdx + Qdy}{\partial n} = \int_C \vec{F} \cdot d\vec{x} = \int_{\Omega} (\operatorname{curl} \vec{F})_z dA \quad \text{Stoke's thm (for dim=2)}$$

$$\text{Green's theorem} \quad \int_C \vec{F} \cdot \vec{n} ds = \int_{\Omega} \operatorname{div} \vec{F} dA \quad \text{Gauss' thm (divergence thm)}$$

if  $\operatorname{curl} \vec{F} = Q_x - P_y = 0$ , then "locally"  $\vec{F} = \nabla f$

$\Rightarrow \operatorname{div} \vec{F} = \Delta f$  "  $\Delta f = 0$ " Laplace equation (f is a harmonic function)

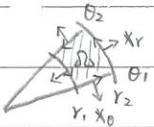
heat equation  $\frac{\partial}{\partial t} f(x, t) = \Delta f$

$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2}{\partial \theta^2}$$

Green's thm  $\Rightarrow$

$$\int_{\Omega} \Delta f dA = \int_C \nabla f \cdot \vec{n} ds = \int_C \frac{\partial f}{\partial n} ds$$

$$\int_{\Omega} \operatorname{div}(g \nabla f) dA = \int_{\Omega} (\nabla g \cdot \nabla f + g \Delta f) dA = \int_C g \frac{\partial f}{\partial n} ds$$



$$\begin{aligned} \int_{\Omega} \Delta f dA &= \int_{\partial \Omega} \frac{\partial f}{\partial n} ds = \int_{\theta_1}^{\theta_2} \frac{\partial f}{\partial r} \Big|_{r_1}^{r_2} - r \Big|_{r_1}^{r_2} d\theta + \int_{r_1}^{r_2} \frac{\partial f}{\partial \theta} \Big|_{\theta_1}^{\theta_2} \cdot \frac{1}{r} dr \\ &= \int_{\theta_1}^{\theta_2} \int_{r_1}^{r_2} \frac{\partial}{\partial r} \left( \frac{\partial f}{\partial r} \cdot r \right) dr d\theta + \int_{r_1}^{r_2} \int_{\theta_1}^{\theta_2} \frac{\partial}{\partial \theta} \left( \frac{\partial f}{\partial \theta} \cdot \frac{1}{r} \right) d\theta dr \\ &= \int_{\theta_1}^{\theta_2} \int_{r_1}^{r_2} \left( \frac{\partial^2 f}{\partial r^2} + \frac{1}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} \right) dA \end{aligned}$$

$$X_r = (\cos \theta, \sin \theta)$$

Apply MVT and let  $\Omega \rightarrow$  a point

$$X_\theta = (-r \sin \theta, r \cos \theta)$$

$$\Rightarrow \Delta f = \frac{\partial^2 f}{\partial r^2} + \frac{1}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

$$f(X(r, \theta)) \quad \frac{\partial f}{\partial \theta} = \nabla f \cdot X_\theta$$

Q: what kind of f do we have?

case 1. if  $f = f(r)$

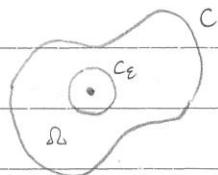
$$f'' + \frac{1}{r} f' = 0, \quad (rf')' = 0, \quad rf' = c, \quad f' = \frac{c}{r}, \quad f = c \log r + C,$$

$$\vec{F} = \nabla f = c \left( \frac{x}{x^2+y^2}, \frac{y}{x^2+y^2} \right), \quad r = (x^2+y^2)^{1/2}$$

$$\int_{C_\epsilon} \vec{F} \cdot \vec{n} ds = \int_0^{2\pi} \frac{\partial f}{\partial r} ds = \int_0^{2\pi} c \frac{1}{r} ds = 2\pi c \neq 0 \text{ since } (0,0) \text{ is singular} \Rightarrow \text{cannot apply Green's thm}$$

$\hookrightarrow$  this is independent of  $\epsilon$ !

apply Green's thm



$$\int_C \vec{F} \cdot \vec{n} ds - \int_{C_\epsilon} \vec{F} \cdot \vec{n} ds = C - C_\epsilon$$

$$\int_{C-C_\epsilon} \vec{F} \cdot \vec{n} ds = \int_{\Omega} \operatorname{div} \vec{F} dA = 0$$

apply Green's thm

case 2. if  $f = f(\theta) \Rightarrow f(\theta) = a\theta + b = a\arctan \frac{y}{x} + b$  is not a well-defined function of  $(x, y)$

$$\nabla f = a\left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2}\right)$$

$$\int_C \vec{F} \cdot \vec{n} ds = 0$$

$$\int_C \nabla \vec{F} \cdot d\vec{x} = f \Big|_{\theta=0}^{\theta=2\pi} = (a\theta + b) \Big|_{\theta=0}^{\theta=2\pi} = a \cdot 2\pi$$

$$3D \quad \textcircled{1} \int_{\partial\Omega} P dx + Q dy = \int_{\Omega} (Qx - Py) dx dy ; \quad \textcircled{2} \int_{\partial\Omega} -Q dx + P dy = \int_{\Omega} \frac{(Px + Qy)}{\operatorname{div} \vec{F}} dx dy$$

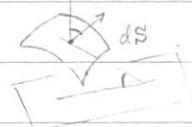
$$\textcircled{2} \quad \vec{F} = (a, b, c) \quad \operatorname{div} \vec{F} = a_x + b_y + c_z$$

$$\int_{\Omega} \operatorname{div} \vec{F} dV = \int_{\substack{\partial\Omega \\ \text{boundary surface}}} \vec{F} \cdot \vec{n} dS \quad \text{area of } \partial\Omega = S$$

$$\vec{n} = (\cos\alpha, \cos\beta, \cos\gamma)$$

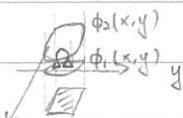
$$\vec{F} \cdot \vec{n} dS = (a \cos\alpha, b \cos\beta, c \cos\gamma) dS$$

$$= adydz + bdzdx + cdxdy$$



pf of divergence theorem. (We prove the theorem for "c")

Step 1.  $\Omega$  is bounded by 2 graphs of functions  $\phi_1(x, y), \phi_2(x, y)$  over some region in  $(x, y)$



plane

Step 2. For general  $\Omega$ , find a partition  $\Omega = \bigcup \Omega_i$

Möbius band 不可定向曲面 non-orientable

Theorem. (Jordan curve theorem): Any "closed" surface in  $\mathbb{R}^3$  is orientable and  $S = \partial\Omega$  for a bounded region  $\Omega$

Prove closed curve on  $\mathbb{R}^2$  divides  $\mathbb{R}^2$  into two parts

6/2

Divergence thm in  $\mathbb{R}^3$  若先給  $S$ , 可能不確定  $\vec{F}$  是否存在 避免解釋何謂 closed surface  
(~~有限個~~) which can be partitioned into a finite union of simple regions  $\Omega_i$  (ie.  $x, y, z$  directions)

Let  $\Omega$  be a bounded open set in  $\mathbb{R}^3$  with  $\partial\Omega$  be a surface  $S$ , and let  $\vec{F}$  be a

$C^1$  vector field, then  $\int_{\Omega} \operatorname{div} \vec{F} dV = \int_S \vec{F} \cdot \vec{n} ds$  which is  $C^1$

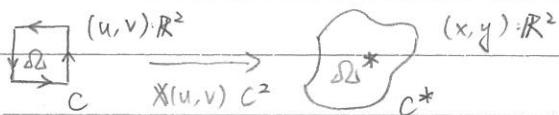
"S" ↳ outer normal

In order to talk about the "boundary of a surface", we need to consider the "induced topology" from  $\mathbb{R}^3$  to  $S$   $S \hookrightarrow \mathbb{R}^3$   $\{\begin{matrix} \text{open} \\ \text{closed} \end{matrix}\}$  topology

Definition. A set  $U \subset S$  is open iff  $U = V \cap S$  for some open set  $V \subset \mathbb{R}^3$

- a point  $p \in S$  is an interior if  $\exists$  open set  $U \ni p$  st.  $U$  looks like a disk
- a point  $p \in S$  is a boundary point of  $S$  if  $\nexists U \ni p$  st.  $U$  looks like a disk

2-dim Green's thm

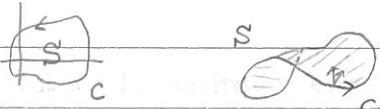


$$\begin{aligned} \int_{\partial\Omega^*} P dx + Q dy &= \int_C P(xu+yu) du + Q(xv+yv) dv = \int_C (Pxu+Qyu) du + (Pxv+Qyv) dv \\ &= \int_{\Omega^*} ((Px_v+Qy_v)u - (Px_u+Qy_u)v) du dv = \int_{\Omega^*} (Px_vx_v + Px_vu + Qy_vv + Qy_vu - Px_uu - Qy_uu - Qy_vu) du dv \\ &= \int_{\Omega^*} ((Px_xu x_v + Py_yu x_v + Qx_xu y_v + Qy_yu y_v) - (Px_xv x_u + Py_yv x_u + Qx_xv y_u + Qy_yv y_u)) du dv \\ &= \int_{\Omega^*} (-Py_y + Qx_x) \left| \frac{x_u}{y_u} \frac{x_v}{y_v} \right| du dv = \int_{\Omega^*} (-Py_y + Qx_x) dx dy \end{aligned}$$

finite polyhedron

$$\int_C \vec{F} \cdot d\vec{x} = \int_S (\operatorname{curl} \vec{F})_z dA$$

C = \partial S



$S \subset \mathbb{R}^3$  be an oriented surface (ie. with a given continuously defined normal vectors)

" $C = \partial S$ " has the induced (positive) orientation

$$\text{Stoke's thm in } \mathbb{R}^3 \quad \int_C \vec{F} \cdot d\vec{x} = \int_S (\operatorname{curl} \vec{F}) \cdot \vec{n} dA$$

$$\begin{aligned} \text{Its primitive form is } \int_C P dx + Q dy + R dz &= \int_S (R_y - Q_z) \cos\alpha + (P_z - R_x) \cos\beta + (Q_x - P_y) \cos\gamma dA \\ &= \int_S (R_y - Q_z) dy dz + (P_z - R_x) dz dx + (Q_x - P_y) dx dy \end{aligned}$$

parameterize  $S$  by  $\vec{x}(u, v)$   $\frac{\vec{x}}{\Omega} \xrightarrow{\substack{x \\ y \\ z}} \mathbb{R}^3 \quad \vec{x}(u, v) = (x(u, v), y(u, v), z(u, v))$ ,  $\partial\Omega = C^*$ ,  $\partial S = C$

$$\begin{aligned} \text{pf. } \int_C P dx + Q dy + R dz &= \int_{C^*} (Px_u + Qyu + Rzu) du + (Px_v + Qyv + Rzv) dv \\ &= \int_{\Omega^*} ((Px_v + Qy_v + Rz_v)u - (Px_u + Qy_u + Rz_u)v) du dv = \int_{\Omega^*} (Px_vx_v + Px_vu + Qy_vv + Qy_vu - Px_uu - Qy_uu - Qy_vu) du dv \\ &\quad \text{green's thm on } \mathbb{R}^2 \\ &= \int_{\Omega^*} ((Py_yu x_v + Pz_zu x_v - Py_yv x_u - Pz_zv x_u) + (Qz_zu y_v + Qx_xu y_v - Qz_zv y_u - Qx_xv y_u) \\ &\quad \quad \quad + (Rx_xu z_v + Ry_yu z_v - Rx_xv z_u - Ry_yv z_u)) du dv \end{aligned}$$

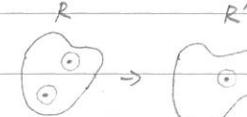
$$= \int_{\Delta} \left( (R_y - Q_z) \begin{vmatrix} y_u & y_v \\ z_u & z_v \end{vmatrix} + (P_z - R_x) \begin{vmatrix} z_u & z_v \\ x_u & x_v \end{vmatrix} + (Q_x - P_y) \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} \right) dudv$$

$$= \int_{\Delta} (R_y - Q_z) dy dz + (P_z - R_x) dz dx + (Q_x - P_y) dx dy$$

$$dS = |x_u \times x_v| dudv \Rightarrow \begin{vmatrix} y_u & y_v \\ z_u & z_v \end{vmatrix} dudv = \cos \alpha dS$$

 $b_1$ 

$$R \xrightarrow{g} R'$$

 $(x,y) \quad (u,v)$ if  $g$  is 1-1,

$$\text{Define } \varepsilon_R(u,v) = \begin{cases} 0, & (u,v) \notin \text{Im } g \\ \text{sgn}\left(\frac{\partial(u,v)}{\partial(x,y)}\right), & (u,v) = g(x,y) \end{cases} \quad u,v \in \mathbb{R}^2$$

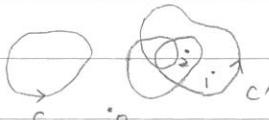
$$\text{Then CVF: } \int_{R^2} f \varepsilon_R dudv = \int_R f \frac{\partial(u,v)}{\partial(x,y)} dx dy$$

General case:  $R \xrightarrow{g} R'$  not 1-1, but  $R = \bigcup_{i=1}^m R_i$  st.  $g$  is 1-1 on  $R_i$  (let  $c_i = \partial R_i$ )  
Assume

$$\int_R f \frac{\partial(u,v)}{\partial(x,y)} dx dy = \sum_{i=1}^m \int_{R_i} f \frac{\partial(u,v)}{\partial(x,y)} dx dy = \sum_{i=1}^m \int_{R^2} f \varepsilon_{R_i} dudv = \int_{R^2} f \cdot \sum_{i=1}^m \varepsilon_{R_i} dudv$$

$\chi_R(u,v) = \text{"degree of the mapping } g \text{ at } (u,v)"$

Identity:  $(*) \chi_R(u,v) = \mu_C(u,v)$  winding number of  $C'$  = image of  $C$  at the point  $(u,v)$



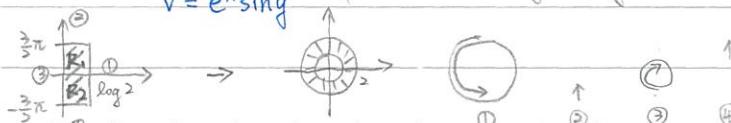
p.f.  $(i)$   $(*)$  is true if  $R \rightarrow R'$  is 1-1  $\xrightarrow{(R)} \xrightarrow{(R')}$   $J(g) > 0, \mu_C = 1$   
 $J(g) < 0, \mu_C = -1$

$(ii)$   $(*)$  is additional  $R = \bigcup A_i$

$$R = \bigcup A_i$$

$$\chi_R(u,v) = \sum_i \chi_{A_i}(u,v) = \sum_i \mu_{C_i}(u,v) = \mu_C(u,v)$$

Example.  $u = e^x \cos y$   
 $v = e^x \sin y$   $(u+iv = e^x(\cos y + i \sin y) = e^{x+iy})$



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Date : \_\_\_\_\_

### harmonic functions

$$\Delta = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2}{\partial \theta^2}$$

$$\Delta f = 0 \quad \text{for } f = f(r) \text{ or } f = f(\theta) \quad \text{singularity}$$

$(u(x,y), v(x,y))$  conformal  $\Rightarrow$  satisfy Cauchy-Riemann equation  $\begin{cases} u_x = v_y \\ v_x = -u_y \end{cases}$

$$\Rightarrow \Delta u = u_{xx} + u_{yy} = v_y x + (-v_{xy}) = 0, \quad \Delta v = 0$$

$$w = z^3 = (x+iy)^3; \quad w = e^z$$

In general, we need "f(x)" to be analytic" i.e.  $f(x) = \text{Taylor series} \Rightarrow f(z)$  well defined

$$w = x^3 + 3x^2y - 3xy^2 - y^3 = (x^3 - 3xy^2) + i(3x^2y - y^3)$$

$\Rightarrow u, v$  satisfy Cauchy-Riemann equation  $\Rightarrow u, v$  harmonic

$$\log z = \log(r e^{i\theta}) = \log r + (i\theta + 2\pi k i) \quad \log x \text{ has Taylor series at } x \neq 0$$

$$\log x = \log(a + (x-a)) = \log a + \log(1 + \frac{x-a}{a})$$

$$f(z) = f(x+iy)$$

$$(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2})f = f'' + f'' \cdot i^2 = 0$$

$\Delta$  in spherical coordinates:

$$x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta \quad \times$$

$$\int_{\Omega} \Delta f dV = \int_{\Omega} \frac{\partial f}{\partial n} dS$$



$$\begin{aligned} \int_{\Omega} \Delta f dV &= \int_{r=r_1}^{r=r_2} r^2 \sin \theta \frac{\partial f}{\partial r} d\theta d\phi - \int_{r=r_1}^{r=r_2} \dots \\ &= \int_{\Omega} \frac{\partial}{\partial r} (r^2 \sin \theta \frac{\partial f}{\partial r}) dr d\theta d\phi \end{aligned}$$

$$\theta: \quad \int_{\Omega} \frac{\partial}{\partial \theta} (\frac{1}{r} \frac{\partial f}{\partial \theta} r \sin \theta) dr d\theta d\phi$$

$$\phi: \quad \int_{\Omega} \frac{\partial}{\partial \phi} (\frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} \cdot r) dr d\theta d\phi$$

$$\Rightarrow \Delta f = \frac{1}{r^2 \sin \theta} \left( \frac{\partial}{\partial r} (r^2 \sin \theta \frac{\partial f}{\partial r}) + \frac{\partial}{\partial \theta} (\frac{\partial f}{\partial \theta} r \sin \theta) + \frac{\partial}{\partial \phi} (\frac{\partial f}{\partial \phi} \cdot \frac{1}{\sin \theta}) \right)$$

n-dim,  $\Delta$  in spherical coordinates

Chuuy culture  $x_n = r \cos \theta_1, x_{n-1} = r \sin \theta_1 \cos \theta_2, x_{n-2} = r \sin \theta_1 \sin \theta_2 \cos \theta_3, \dots$

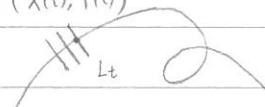
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$$X(t) = \frac{1}{|L_t|} \int_{L_t} x \, ds$$

4.10 b area swept out by a moving line in  $\mathbb{R}^2$ 

(X(t), Y(t))

Co-area formula (等高線積分法)

Equation of a line  $\xi(t)x + \eta(t)y = p(t)$  at time t.

$$(\xi, \eta) \parallel \vec{n} \quad \vec{v} = (x'|t), y'(t))$$

$$\xi'x + \eta'y + \xi x' + \eta y' = p'$$

velocity vector of the centroid

$$\vec{n} \cdot \vec{v} = \xi \frac{dx}{dt} + \eta \frac{dy}{dt} = \frac{dp}{dt} - \frac{d\xi}{dt}x - \frac{d\eta}{dt}y \quad \vec{n} \cdot \vec{w} = \xi \frac{dx}{dt} + \eta \frac{dy}{dt} = \frac{dp}{dt} - \frac{d\xi}{dt}x - \frac{d\eta}{dt}y$$

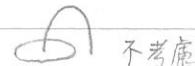
$$A = \int dt \int_{L_t} \frac{ds}{|\nabla \phi|} \quad \frac{1}{|\nabla \phi|} = \pm \vec{v} \cdot \vec{n} \quad \left( \begin{array}{l} \phi(x(t), y(t)) = t, \quad \nabla \phi \cdot (x(t), y(t)) = 1 \\ \pm |\nabla \phi| \vec{n} \quad \vec{v} \end{array} \right)$$

$$= \pm \int dt \left( \frac{dp}{dt} \cdot |L_t| - \frac{d\xi}{dt} x(t) \cdot |L_t| - \frac{d\eta}{dt} y(t) \cdot |L_t| \right)$$

$$= \pm \int_a^b |L_t| \vec{w} \cdot \vec{n} \, dt$$

special case: if  $L_t \perp \vec{n}$   $\forall t$ ,  $A = \int |L_t| \frac{ds}{dt} dt = \int |L_t| d\sigma$   $\sigma$ , arc length of  $(X(t), Y(t))$ application:  $V(r) = (\pi r^2) l$  true for  $r$  small

$$S(r) = V'(r) = 2\pi r l$$



不考慮

Stoke's thm in higher dimension

Green - divergence - Gauss ( $n=N$ )step 1.  $B = [0, 1]^n \subset \mathbb{R}^n = \{(x_i)\}_{i=1}^n \mid 0 \leq x_i \leq 1\}$ 

$$\int_B d\omega = \int_{\partial B} \omega \text{ for any } (n-1) \text{ form } \omega$$

$$\text{step 2. } f: B \xrightarrow{\text{C}} \Omega \quad \int_{\Omega} d\omega = \int_{\partial \Omega} \omega$$

$\downarrow \quad \downarrow$   
 $\mathbb{R}^n \quad \mathbb{R}^N$

$$\text{step 1 for } n=1, \text{ FTC} \quad \int_{[0,1]} df = \int_{\partial [0,1]} f \quad \xrightarrow{\substack{\circ \\ B}} \quad \partial [0,1] = "1" - "0"$$

$$n=2, \text{ Green} \quad \int_B (Qx - Py) dx \wedge dy = \int_{\partial B} P dx + Q dy \quad \xrightarrow{\substack{c_1 \\ c_2 \\ c_3 \\ c_4}} \quad \partial B = c_1 + c_2 + c_3 + c_4$$

$$\text{for step 2. } B \xrightarrow{\text{g: } c_1, c_2, c_3, c_4} \mathbb{R}^N \quad g(B) = \Omega$$

$$\omega: 1\text{-form on } \mathbb{R}^N, \omega = \sum f_i dx_i; \quad \int_{\Omega} d\omega = \int_{\partial \Omega} \omega$$

$$\int_{\partial \Omega} \omega = \int_{\partial \Omega} \sum_i f_i dx_i = \int_{\partial B} \sum_{i,j} f_i \frac{\partial x_i}{\partial u_j} du_j = \int_B \sum_{i,j,k} \frac{\partial}{\partial u_k} (f_i \frac{\partial x_i}{\partial u_j}) du_k \wedge du_j$$

$$= \int_{\Omega} \sum_i df_i \wedge dx_i = \int_{\Omega} d\omega$$

$$\frac{\partial f_i}{\partial u_k} \cdot \frac{\partial x_i}{\partial u_j} + f_i \frac{\partial x_i}{\partial u_k}$$

## CH3. iteration inverse function

primitive map  $\rightarrow$  CVF

No.

Date

CH4,5 Fubini thm (domain) Co-area formula  
improper 微積分次序for step 2 ( $n=3$ )

$$\int_{\partial B} ady \wedge dz + bdz \wedge dx + cdx \wedge dy = \int_B (ax+by+cz) dx dy dz$$

$$B \rightarrow \mathbb{R}^N$$

$$u_1, u_2, u_3 \quad x_1, \dots, x_N$$

 $\omega$ : 2-form on  $\mathbb{R}^N$ ,  $\omega = \sum f_{i_1, i_2} dx_{i_1} \wedge dx_{i_2}$ 

$$\begin{aligned} \int_{\partial \Omega} \omega &= \int_{\partial \Omega} \sum_i f_{i_1, i_2} dx_{i_1} dx_{i_2} = \int_{\partial B} \sum_{i, j} f_{i_1, i_2} \frac{\partial x_{i_1}}{\partial u_j} \frac{\partial x_{i_2}}{\partial u_j} du_1 \wedge du_2 \\ &= \int_B \sum_{i, j, k} \frac{\partial}{\partial u_k} \left( f_{i_1, i_2} \frac{\partial x_{i_1}}{\partial u_j} \frac{\partial x_{i_2}}{\partial u_j} \right) du_k \wedge du_1 \wedge du_2 \\ &\quad \cancel{\frac{\partial f_{i_1, i_2}}{\partial u_k} \cdot \frac{\partial x_{i_1}}{\partial u_j} \cdot \frac{\partial x_{i_2}}{\partial u_j}} + \cancel{f_{i_1, i_2} \frac{\partial^2 x_{i_1}}{\partial u_k \partial u_j} \frac{\partial x_{i_2}}{\partial u_j}} + \cancel{f_{i_1, i_2} \frac{\partial x_{i_1}}{\partial u_k} \cdot \cancel{\frac{\partial x_{i_2}}{\partial u_j}}} \\ &= \int_{\Omega} \sum_I df_I \wedge dx_{i_1} \wedge dx_{i_2} \\ &= \int_{\Omega} d\omega \end{aligned}$$

$$d: \Omega^p \rightarrow \Omega^{p+1}$$

$$\omega \rightarrow d\omega$$

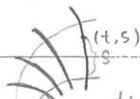
$$\omega = \sum f_I dx_{i_1} \wedge \dots \wedge dx_{i_p}$$

$$d\omega = \sum_I df_I \wedge dx_{i_1} \wedge \dots \wedge dx_{i_p}$$

$$d^2\omega = d(d\omega) = \sum_{I, i, j} d\left(\frac{\partial f}{\partial x_i}\right) \wedge dx_i \wedge \dots$$

$$\frac{\partial^2 f}{\partial x_i \partial x_j} dx_j \wedge dx_i \wedge \dots$$

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$$\phi(x, y) = t$$

$$\{(x, y) \mid \phi(x, y) = t\} =: L_t \quad s: \text{arc length on } L_t$$

$$\xi(t) x + \eta(t) y = p(t)$$

$\uparrow \quad \uparrow$   
 $x(t, s) \quad y(t, s)$

$$\xi' x + \eta' y + \xi \frac{\partial x}{\partial t} + \eta \frac{\partial y}{\partial t} = p' \quad \text{integrate on } s \text{ variable}$$

$$\int_{L_t} x ds = |L_t| \cdot \bar{x}(t)$$

## Orientation (方向)

Def.

$\subset \mathbb{R}^2$ ,  $\Omega_1 \cap \Omega_2 \neq \emptyset$  has the same orientation if  $\frac{\partial(x, y)}{\partial(u, v)} > 0$   
 $\Leftrightarrow \frac{\partial(u, v)}{\partial(x, y)} > 0$

linear algebra version

$$\mathbb{R}^n. \text{ 2 basis } \{v_1, \dots, v_n\}, \{w_1, \dots, w_n\} \quad w_i = \sum_{j=1}^n a_{ij} v_j \quad A = (a_{ij})$$

has the same orientation  $\Leftrightarrow \det A > 0$ 

$$\{\vec{v}_1, \dots, \vec{v}_n\}, \{\vec{w}_1, \dots, \vec{w}_n\}$$

coordinates

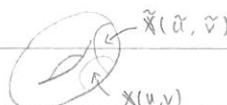
$$x_1, \dots, x_n \quad y_1, \dots, y_n$$

$$\vec{v} = \sum_i x_i \vec{v}_i = \sum_i y_i \vec{w}_i$$

$$= \sum_{i,j} y_i a_{ij} \vec{v}_j$$

$$x_i = \sum_j y_j a_{ji}$$

$$\frac{\partial(x_1, \dots, x_n)}{\partial(y_1, \dots, y_n)} = (a_{ji}) = A^t$$

What do we mean if a surface  $S \subset \mathbb{R}^3$  is "orientable" (可定向)

$$T_p S \quad \{\tilde{x}_u, \tilde{x}_v\} \quad \{\tilde{x}_{\tilde{u}}, \tilde{x}_{\tilde{v}}\}$$

$$\tilde{x}_u = \tilde{x}_{\tilde{u}} \frac{\partial \tilde{u}}{\partial u} + \tilde{x}_{\tilde{v}} \frac{\partial \tilde{v}}{\partial u}; \quad \tilde{x}_v = \tilde{x}_{\tilde{u}} \frac{\partial \tilde{u}}{\partial v} + \tilde{x}_{\tilde{v}} \frac{\partial \tilde{v}}{\partial v}$$

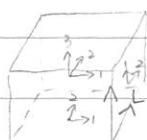
法向量只能在少一維的情況定義  $|\tilde{x}_u, \tilde{x}_v, \tilde{x}_u \times \tilde{x}_v| > 0$ 

Möbius band

$$|\tilde{x}_{\tilde{u}}, \tilde{x}_{\tilde{v}}, \tilde{x}_u \times \tilde{x}_v| > 0$$

①   
 $\{\text{orientation on } \partial S + \text{inner normal vector}\} = \text{orientation on } S$   
 $\partial S$  induced orientation

step 1. eventually, we only need to consider the case of a cube.

 $\Omega = [0, 1]^n \subset \mathbb{R}^n$  with orientation given by  $e_1, \dots, e_n$  $\partial\Omega = \text{the } 2^n \text{ "boundary pieces"}$ as a set  $\partial\Omega = \{(x_i)_{i=1}^n \in \Omega \mid x_i = 0 \text{ or } 1 \text{ for some } i\}$ 

$$\partial\Omega = A_1 \cup \dots \cup A_{2^n}$$

$$\partial(\partial\Omega) = \partial A_1 \cup \dots \cup \partial A_{2^n} = \emptyset$$

closed surface: a surface without boundary ( $\partial\Omega$ )

$$\partial^2 = 0 \Leftrightarrow d^2 = 0$$

$$\vec{F} \cdot d\vec{x} \rightarrow P dx + Q dy + R dz$$

$$\vec{E} \cdot d\vec{x} \rightarrow P dx \wedge dy + Q dx \wedge dz + R dy \wedge dz$$

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## I. Point Set Topology

g(r)

## II. Limit

$$\sup_{\theta} |f(x+r\cos\theta, y+r\sin\theta) - L| < \epsilon \quad \forall r < \delta$$

$\langle \text{Def} \rangle \lim_{(x,y) \rightarrow (a,b)} f(x,y) = L \Leftrightarrow \forall \epsilon > 0, \exists \delta > 0 \text{ st. } |f(x,y) - L| < \epsilon \quad \forall |(x,y) - (a,b)| < \delta$

$\Leftrightarrow \forall \{f(x_n, y_n)\}_{n=1}^{\infty} \text{ with } (x_n, y_n) \rightarrow (a, b), \text{ we have } \lim_{n \rightarrow \infty} f(x_n, y_n) = L$

eg.  $\lim_{(x,y) \rightarrow (0,0)} \sqrt{1+e^{xy}} = \sqrt{2}$

eg.  $\lim_{(x,y) \rightarrow (0,0)} |x|^y$

$$\begin{cases} (1) (0, y) \rightarrow \lim_{(x,y) \rightarrow (0,0)} 0^y = 0 & \rightarrow \text{不存在} \\ (2) (x, x) \rightarrow \lim_{(x,y) \rightarrow (0,0)} |x|^x = 1 \end{cases}$$

eg.  $\lim_{(x,y) \rightarrow (0,0)} |x|^{\frac{1}{|y|}} = 0$

$$0 \leq |x|^{\frac{1}{|y|}} \leq |x|^2 \rightarrow 0 \text{ as } (x, y) \rightarrow (0, 0)$$

$$\lim_{(x,y) \rightarrow (0,0)} \frac{\sin(x^4+y^4)}{x^2+y^2} = 0$$

$$\text{pf. } 0 \leq \left| \frac{\sin(x^4+y^4)}{x^2+y^2} \right| \leq \frac{x^4+y^4}{x^2+y^2} \leq \frac{(x^2+y^2)^2}{x^2+y^2} = x^2+y^2 \rightarrow 0 \text{ as } (x, y) \rightarrow (0, 0)$$

$$\lim_{(x,y) \rightarrow (0,0)} \frac{e^{-\frac{1}{x^2+y^2}}}{x^4+y^4} = 0$$

$$\text{pf. } \sup_{\theta} \frac{e^{-\frac{1}{r^2}}}{r^4(\cos^4\theta + \sin^4\theta)} = 2 \frac{e^{-\frac{1}{r^2}}}{r^4} \rightarrow 0 \text{ as } r \rightarrow 0$$

$$1 - \frac{1}{2} \sin^2 2\theta$$

$$\lim_{r \rightarrow 0^+} |f(a+r\cos\theta, b+r\sin\theta) - L| = 0, \forall \theta \Rightarrow f(x, y) \rightarrow L \text{ as } (x, y) \rightarrow (a, b)$$

$C^1 \Rightarrow \text{diff.} \Rightarrow \text{conti.} \Rightarrow \text{limit exists}$

$f_x$  or  $f_y$  存在、方向 deri. 存在

$$\text{eg. } \lim_{(x,y) \rightarrow (0,0)} \frac{x^6+y^6}{x^6+y^6+(y-x^2)^2}$$

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$\langle \text{Definition} \rangle f$  is differentiable at  $(a, b)$  if there exists  $(A, B) \in \mathbb{R}^2$  st.

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(a+h, b+k) - f(a, b) - Ah - Bk}{\sqrt{h^2+k^2}} = 0$$

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## How to check differentiability?

(1) Test the limit  $\forall (A, B) \in \mathbb{R}^2 \rightarrow$  impossible

<Lemma>

If such  $(A, B)$  exists, then  $A = f_x(a, b)$ ,  $B = f_y(a, b)$

Moreover,  $D_{(0)} f(a, b) = f_x(a, b) \cos \theta + f_y(a, b) \sin \theta$

$\therefore$  we need only to check the limit for  $A = f_x(a, b)$  and  $B = f_y(a, b)$

(2) Calculate  $f_x(x, y)$  and  $f_y(x, y)$  near  $(a, b)$

<Lemma>

$f$  is  $C^1$  at  $(a, b) \Rightarrow f$  is differentiable at  $(a, b)$

$$\varphi(x, t) = \begin{cases} x, & 0 \leq x \leq \sqrt{t}, t \geq 0 \\ -x + 2\sqrt{t}, & \sqrt{t} \leq x \leq 2\sqrt{t}, t \geq 0 \\ -x, & 0 \leq x \leq \sqrt{-t}, t \leq 0 \\ x - 2\sqrt{-t}, & \sqrt{-t} \leq x \leq 2\sqrt{-t}, t \leq 0 \\ 0, & \text{otherwise} \end{cases}$$

$$\int_1^1 \frac{\partial}{\partial t} \varphi(x, 0) dx = 0 \neq 1 = \left. \frac{d}{dt} \int_{-1}^1 \frac{\partial \varphi}{\partial t}(x, 0) dx \right|_{t=0}$$

<Thm>  $L = Adx + Bdy + Cdz$  is conservative on  $D \subset \mathbb{R}^3$

$\Leftrightarrow \exists \phi$  st.  $\nabla \phi = (A, B, C)$  on  $D$

$\Leftrightarrow \int_P L$  is independent of path  $\forall P \subset D$

$\Leftarrow dL = 0$  on  $D$  and  $D$  is simply connected

$$\int_P (9x^2y + 8xy^2 + 5y^3) dx + (3x^3 + 8x^2y + 15xy^2) dy$$

$$P: \{ (x, y) \mid y = (\pi x)^3 \sin \frac{1}{x}, 0 \leq x \leq \frac{1}{2\pi} \}$$

$$\phi(x, y) = \int (9x^2y + 8xy^2 + 5y^3) dx = 3x^3y + 4x^2y^2 + 5y^3x + C(y)$$

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$f \in C^1 \Rightarrow f$  differentiable  $\Rightarrow f_{x_i}$  exists

$$f(ath, b+k) = f(a, b) + f_x \cdot h + f_y \cdot k + o(\sqrt{h^2+k^2}) \Rightarrow D_{(0)} = f_x \cos \theta + f_y \sin \theta$$

$$D_{(0)} \equiv \lim_{r \rightarrow 0} \frac{f(x+r\cos \theta, y+r\sin \theta) - f(x, y)}{r}$$

$$\text{MVT. } f(x+h, y+k) - f(x, y) = h f_x(x+\theta h, y+\theta k) + k f_y(x+\theta h, y+\theta k)$$

convex set,  $f_x, f_y \in C^1 \Rightarrow \text{MVT}$

convex set,  $f_x, f_y \in C^1, |f_x|, |f_y| \leq M \Rightarrow f \text{ Lipschitz conti.} \Rightarrow \text{uniformly conti.}$

$f(x, y)$  uniformly conti. on  $U \subset \mathbb{R}^2 \Rightarrow \forall \varepsilon \exists \delta \text{ st. } |f(x_1, y_1) - f(x_2, y_2)| < \varepsilon \quad \forall \|(x_1, y_1) - (x_2, y_2)\| < \delta$

$$(x_1, y_1), (x_2, y_2) \in U$$

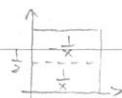
$f(x, y)$  conti. on closed bounded set  $S \Rightarrow f$  uniformly conti.

$\Rightarrow f(x, y), f_x$  conti. on  $[a, b] \times [c, d] \Rightarrow \frac{d}{dx} \int_c^d f(x, y) dy = \int_c^d f_x(x, y) dy$  conti.

$\Rightarrow g_{xy}, g_y$  conti.,  $g_x$  exists  $\Rightarrow g_{xy} = g_{yx}$  ( $g_{xy}, g_y$  conti.  $\Rightarrow g_{xy} = g_{yx}$ )

$\Rightarrow f$  conti. on  $[a, b] \times [c, d] \Rightarrow \int_a^b \int_c^d f dy dx = \int_c^d \int_a^b f dx dy$

反例:  $(0, 1) \times (0, 1)$



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Recall IFT: If  $F(x, y, u, v) \in C^1, G(x, y, u, v) \in C^1$  and  $\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix} \neq 0$  at  $(u_0, v_0)$

then  $F=0, G=0$  can be solve as  $u=u(x, y), v=v(x, y)$  near  $(u_0, v_0)$

(1) 中間值定理

(2) Dynamic system:

Goal: Find  $\delta > 0$  st.  $\forall (x, y) \in B_\delta(F(u_0, v_0), G(u_0, v_0)) \exists! (u, v)$  st.  $x=F(u, v), y=G(u, v)$

Key: Consider  $\varphi \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} u \\ v \end{pmatrix} + A \left( \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} F(u, v) \\ G(u, v) \end{pmatrix} \right)$

事後選擇的 fixed  $\begin{pmatrix} x \\ y \end{pmatrix} \in B_\delta(F(u_0, v_0), G(u_0, v_0))$

Geometry:

Surface theory  $\mathbb{X}: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3$

<1> 切平面: Given a curve  $\{(x(t), y(t))\} \subset U \quad x(0) = x_0, y(0) = y_0$

$$\vec{r}(t) = (x(t), y(t), z(x(t), y(t)))$$

$$\frac{d\vec{r}(t)}{dt} = (x'(t), y'(t), \frac{\partial z}{\partial x} x'(t) + \frac{\partial z}{\partial y} y'(t))$$

$$\frac{d\vec{r}(t)}{dt} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \end{pmatrix} \begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix}$$

$X'$ : 線性算子, 將路徑切向量  $\rightarrow$  曲面切向量

$X'$  切向量

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$$\frac{x^2}{1^2} + \frac{y^2}{2^2} + \frac{z^2}{3^2} = 1 \quad x+y+z=1 \quad \text{上半部體積}$$

$$\text{sol. let } x=x^*, y=2y^*, z=3z^* \quad \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} \begin{pmatrix} x^* \\ y^* \\ z^* \end{pmatrix}$$

$$\iiint_R dx dy dz = \iiint_{R^*} b dx dy dz \quad R^*: x^{*2} + y^{*2} + z^{*2} = 1 \quad x^* + 2y^* + 3z^* = 1$$

$$\rightarrow z^{**} = \frac{1}{\sqrt{14}}$$

$$\text{ex. } \iiint_{x^2+y^2+z^2 \leq 1} \cos(x+y+z) dx dy dz$$

$$\iiint_{x^2+y^2+z^2 \leq 1} \sin(x+y+z) dx dy dz = 0$$

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Recall: line integral In  $\mathbb{R}^2$ ,  $C: \vec{r}(t) = (x(t), y(t))$ ,  $t \in I = [a, b]$ ,  $\varphi: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$(1) \int_C \varphi ds = \int_a^b \varphi(x(t), y(t)) \sqrt{x'^2 + y'^2} dt \quad \text{算質量} (\varphi: \text{密度}) \cdot \text{弧長} (\varphi: 1)$$

$$(2) \int_a^b \frac{d}{dt} (\varphi \circ \vec{r}) dt = \varphi \circ \vec{r}(b) - \varphi \circ \vec{r}(a)$$

$$\int_a^b (\varphi_x \cdot x' + \varphi_y \cdot y') dt = \int \varphi_x dx + \varphi_y dy$$

$$(2') \int_C w = \int_C P dx + Q dy \quad 1\text{-form 只能在曲線上積分}$$

$$\Rightarrow \text{Green's theorem} \quad \int_C P dx + Q dy = \iint_D (Q_x - P_y) dx dy$$

$$\int_C P dx + Q dy + R dz = \text{Stoke's theorem}$$

$$\hookrightarrow \iint_{S_1} \text{curl } \vec{F} \cdot \vec{n} ds = \iint_{S_2} \text{curl } \vec{F} \cdot \vec{n} ds$$



Surface integral In  $\mathbb{R}^3$   $S: \vec{r}(u, v) = (x(u, v), y(u, v), z(u, v))$

$$\varphi: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$(1) \iint_S \varphi dS = \iint \varphi(x(u, v), y(u, v), z(u, v)) \frac{\sqrt{EG - F^2}}{\sqrt{\|\vec{r}_u\|^2 \|\vec{r}_v\|^2 - (\vec{r}_u \cdot \vec{r}_v)^2}} du dv$$

$$(2') \omega = P dx \wedge dy + Q dy \wedge dz + R dz \wedge dx \quad 2\text{-form 只能在曲面上積分}$$

$$\int_S w = \int_S P dx \wedge dy + Q dy \wedge dz + R dz \wedge dx \triangleq \int P(x_u du + x_v dv) \wedge (y_u du + y_v dv) + \dots$$

$$= \int P(x_u y_v du \wedge dv + x_v y_u dv \wedge du) + \dots = \int P \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} du \wedge dv + \dots$$

$$= \int (P, Q, R) \cdot (1, 1, 1, 1, 1) du dv$$

$$= \iint_S (P, Q, R) \cdot \vec{n} dS$$

$\xrightarrow{\text{Gauss' thm}}$   
culture