



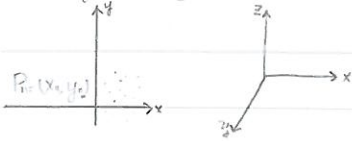
Subject: Chapter I

No.:

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§ 1.1 ~ 1.3 Functions of multivariable and continuity

$f(x, y) = x^2 - y^2$



• Limit of sequence of points

Defⁿ = " $\lim_{n \rightarrow \infty} P_n = Q$ " $\Leftrightarrow \forall \epsilon > 0, \exists N$ st $n \geq N \Rightarrow |P_n - Q| < \epsilon$

$P_n = (x_n, y_n), Q = (a, b)$

equivalently, $\lim_{n \rightarrow \infty} x_n = a, \lim_{n \rightarrow \infty} y_n = b$

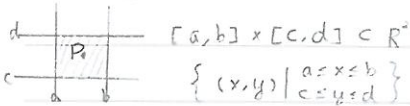
" \Rightarrow " $[(x_n - a)^2 + (y_n - b)^2]^{\frac{1}{2}} < \epsilon$

$|x_n - a| < \epsilon, |y_n - b| < \epsilon$

" \Leftarrow " $\forall \epsilon > 0, \exists N$ st $n \geq N \quad |x_n - a| < \epsilon \quad |y_n - b| < \epsilon$

$\Rightarrow |P_n - Q| < \sqrt{2} \epsilon \quad \neq Q \in D.$

$S =$ Region (Box) $\subset \mathbb{R}^2$

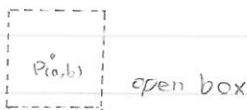


• ϵ -neighborhood

• $B_p(\epsilon) = \epsilon$ -ball

$(a - \epsilon, a + \epsilon) \times (b - \epsilon, b + \epsilon)$

$\{ Q \in \mathbb{R}^2 \mid |Q - P| < \epsilon \}$



$S = \{ (x, y) \mid x^2 + y^2 \leq 1 \text{ and if } x=0 \text{ then } y < 0 \}$

• interior point

$S^\circ = \{ p \in \mathbb{R}^2 \mid \exists \epsilon$ -neighborhood of p contained in $S \}$



• exterior point

$= \{ p \in \mathbb{R}^2 \mid \exists B_p(\epsilon)$ st $B_p(\epsilon) \cap S = \emptyset \}$

$S^c =$ complement of S
 $= \mathbb{R}^2 \setminus S = \{ p \in \mathbb{R}^2 \mid p \notin S \}$

• boundary points

$\partial S = \{ p \in \mathbb{R}^2 \mid \forall B_p(\epsilon), B_p(\epsilon) \cap S \neq \emptyset \quad B_p(\epsilon) \cap S^c \neq \emptyset \}$

disjoint

$\mathbb{R}^2 = S^\circ \cup \partial S \cup S^c$



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Key terminology [open set : $S = S^\circ$
close set : $S \subset \partial S$

• S is open $\Leftrightarrow S^c$ is close [$\partial S = \partial(S^c)$]

domain and range of a function

$f: S \subset \mathbb{R}^n \rightarrow \mathbb{R}$ $f(S)$ "image"

[eg] $f(x,y) = \log(1-x^2-y^2)$ domain $S = B_0(1)$

$f(x,y) = \tan^{-1}(\frac{y}{x})$ we need to select a "principal branch" to make the function to be single valued.

Defⁿ = ① $\lim_{P_n \rightarrow P} f(P_n) = L$

" \Leftrightarrow " $\forall \epsilon > 0 \exists N$, st $n > N$
 $\Rightarrow |f(P_n) - L| < \epsilon$

①' $\lim_{Q \rightarrow P} f(Q) = L$

$\forall \epsilon > 0, \exists \delta > 0$

st. $|Q - P| < \delta \Rightarrow |f(Q) - L| < \epsilon$

② $f(x,y)$ is continuous at $P = (a,b)$

$\Leftrightarrow \lim_{Q \rightarrow P} f(Q) = f(P)$

(Ex 1.) $f(x,y) = \frac{x^2 y}{x^2 + y^2}$ is conti outside $(0,0)$

Q: Does $\lim_{Q \rightarrow (0,0)} f(Q)$ exist?

along x -axis $\rightarrow f(x,0) = 0$

y -axis $\rightarrow f(0,y) = 0$

$y = mx \rightarrow f(x, mx) = \frac{x^3 m}{1+m^2}$ varies in m . [A] = x

(Ex 2.) $f(x,y) = \frac{x^2 y^2}{x^2 + y^2}$

along x -axis $\rightarrow f(x,0) = 0$

y -axis $\rightarrow f(0,y) = 0$

$y = mx \rightarrow f(x, mx) = \frac{m^2 x^3}{1+m^2}$

$f(x,y) = \frac{x^2 y^2}{x^2 + y^2}$

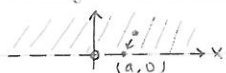
$f(x, mx) = \frac{m^2 x^3}{x^2(1+m^2)}$

along $y^2 = mx \Rightarrow f = \frac{m^3}{1+m^2}$

$|f(x,y)| \leq \frac{y^2}{2}$

(Ex 3) Continuous extension of a function to ∂S of its domain S

$f(x,y) = e^{-x/y}$ with $S = \{(x,y) \in \mathbb{R}^2 \mid y > 0\}$ (upper half plane)



$\partial S = x$ -axis

$\lim_{P \rightarrow (a,0)} e^{-x/y}$

[$a \neq 0$, $\lim_{y \rightarrow 0} \dots$]

[$a = 0$, let $y = mx \rightarrow f(x,y) = e^{-x/mx} = e^{-1/m} \rightarrow$ constant]



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Recall

$$f(x,y) = \frac{xy^2}{x^2+y^2} \quad \text{if } (x,y) \neq (0,0)$$

$$= 0 \quad \text{if } (x,y) = (0,0)$$

$$|f(x,y) - f(0,0)| \leq \left| \frac{xy^2}{x^2+y^2} \right| |y| \leq \frac{1}{2} |y|^3$$

$\hookrightarrow f(x,y)$ is continuous $\iff \lim_{(x_n, y_n) \rightarrow (0,0)} f(x_n, y_n) = f(\lim_{(x_n, y_n) \rightarrow (0,0)} (x_n, y_n)) = f(\lim_{n \rightarrow \infty} x_n, \lim_{n \rightarrow \infty} y_n)$

The order of a function "0"/"o"

$$f = O(g) \iff \left| \frac{f(h,k)}{g(h,k)} \right| \leq M$$

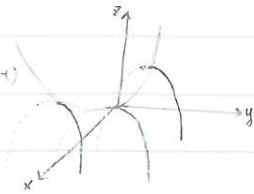
$$f = o(g) \iff \lim_{(h,k) \rightarrow (0,0)} \frac{f(h,k)}{g(h,k)} = 0$$

§1.4 Partial derivatives

$$z = f(x,y) = x^2 - y^2$$

"slicing"

($x \rightarrow \text{constant}$)



$$x=0, z = -y^2$$

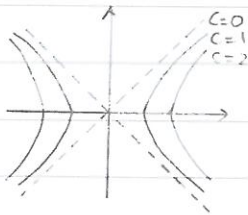
$$x=C, z = -y^2 + C^2$$



"level curves"

($z \rightarrow \text{constant}$)

$$x^2 - y^2 = C$$



$$\frac{\partial f}{\partial x}(x_0, y_0) = \lim_{h \rightarrow 0} \frac{f(x_0+h, y_0) - f(x_0, y_0)}{h}$$

$$\downarrow$$

$$D_x f(x_0, y_0), D_x^2 f(x_0, y_0), \partial_x f(x_0, y_0), f_x(x_0, y_0)$$

$$\frac{\partial f}{\partial y}(x_0, y_0) = \lim_{h \rightarrow 0} \frac{f(x_0, y_0+h) - f(x_0, y_0)}{h}$$

Higher partial derivatives

$$\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial x^2} = f_{xx} = D_x D_x f$$

$$\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x} = f_{yx} = D_y D_x f$$

$$\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial x \partial y} = f_{xy} = D_x D_y f$$

$$\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial y^2} = f_{yy} = D_y D_y f$$



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(Ex 1) $f(x, y) = x^2 - y^2$

$f_x = 2x$, $f_y = -2y$

$f_{yx} = 0$, $f_{xy} = 0$

(Ex 2) $f(x, y) = e^{\frac{x}{y}}$

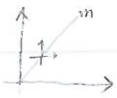
$f_x = e^{\frac{x}{y}} \cdot \frac{1}{y}$, $f_y = e^{\frac{x}{y}} \cdot \frac{-x}{y^2}$

$f_{yx} = e^{\frac{x}{y}} \cdot \frac{-x}{y^2} \cdot \frac{1}{y} + e^{\frac{x}{y}} \cdot \frac{-1}{y^2}$

$f_{xy} = e^{\frac{x}{y}} \cdot \frac{1}{y} \cdot \frac{-x}{y^2} + e^{\frac{x}{y}} \cdot \frac{-1}{y^2}$

(Ex 3) f_x, f_y exist

$$f(x, y) = \begin{cases} \frac{xy}{x^2+y^2} & (x, y) \neq (0, 0) \\ 0 & (x, y) = (0, 0) \end{cases}$$



Thm: If f_x, f_y exists and $|f_x| \leq M_1$, $|f_y| \leq M_2$ on R then f is continuous.

$f_y = \frac{y(x^2+y^2) - xy \cdot 2y}{(x^2+y^2)^2} = \frac{y^3 - x^2y}{(x^2+y^2)^2}$ is this bounded?

$y = mx$ $f(x, mx) = \frac{1}{x} \cdot \frac{y^3 - x^2y}{(1+m^2)^2}$

$| \Delta f |$

$$\begin{aligned} & f(a+h, b+k) - f(a, b) \\ &= (f(a+h, b+k) - f(a+h, b)) + (f(a+h, b) - f(a, b)) \\ &= \underbrace{f_y(a+h, b+k)k}_{\leq M_2} + \underbrace{f_x(a+h, b)h}_{\leq M_1} \end{aligned}$$

$| \Delta f | \leq M_2 |k| + M_1 |h|$

(Ex 4) $f(x, y, z) = \frac{1}{r} = (x^2 + y^2 + z^2)^{-1/2}$

$\Delta =$ Laplace operator $= \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$

$f_x = -\frac{1}{2} (x^2 + y^2 + z^2)^{-3/2} \cdot 2x$

$f_{xx} = \frac{3}{4} (x^2 + y^2 + z^2)^{-5/2} \cdot (2x)^2 - (x^2 + y^2 + z^2)^{-3/2}$

$\Delta f = \frac{3(x^2+y^2+z^2) - 3(x^2+y^2+z^2)}{(x^2+y^2+z^2)^{5/2}} = 0$

(Ex 5) $f(x, t) = \frac{1}{\sqrt{4t}} e^{-(x-a)^2/4t}$ satisfies $\frac{\partial f}{\partial t} = f_{xx}$

↑
temperature

↑
Newton's heat



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Thm: If f_{xy} and f_{yx} are continuous on an open set R_1
then $f_{xy} = f_{yx}$

pf

$$\text{Let } A(h, k) := f(a+h, b+k) - f(a, b+k) - f(a+h, b) + f(a, b)$$

• wrong method $A(h, k) = f_x(a+\theta_1 h, b+k) - f_x(a+\theta_2 h, b)$ still works.

$$\text{Let } \phi(x) = f(x, y+k) - f(x, y)$$

$$A(h, k) = \phi(a+h) - \phi(a) = \phi'(a+\theta_1 h)h$$

$$= [f_x(a+\theta_1 h, b+k) - f_x(a+\theta_2 h, b)]h$$

$$= f_{yx}(a+\theta_1 h, b+\theta_2 k)hk$$

$$\lim_{(h,k) \rightarrow (0,0)} \frac{A(h,k)}{hk} = f_{yx}(a,b)$$

• change the role of $x \leftrightarrow y$

$$f_{xy}(a,b) = f_{yx}(a,b) \quad *$$



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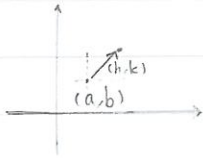
What is the meaning of "differentiability" of a multivariable function?

Defⁿ: A function $z = f(x, y)$ is differentiable at $(x, y) = (a, b)$

$$\text{iff } f(a+h, b+k) = f(a, b) + Ah + Bk + o(\sqrt{h^2+k^2})$$

$\downarrow \Delta x$ $\downarrow \Delta y$

$\hookrightarrow \varepsilon(h, k) \sqrt{h^2+k^2}$
 with $\lim_{(h,k) \rightarrow (0,0)} \varepsilon = 0$



corollary: $A = \frac{\partial f}{\partial x}(a, b)$

so at $(h, k) = (h, 0)$

$$f(a+h, b) - f(a, b) = Ah + o(|h|)$$

$$B = \frac{\partial f}{\partial y}(a, b)$$

Thm: If f_x, f_y exist and continuous in a nbd of (a, b) then f is diffble at (a, b)

* nbd = neighborhood (i.e. open set)
diffble = differentiable

pf $f(a+h, b+k) - f(a, b) = (f(a+h, b+k) - f(a+h, b)) + (f(a+h, b) - f(a, b))$

$$= f_y(a+h, b)k + f_x(a+h, b)h$$

$$f(a+h, b+k) - f(a, b) - (f_x(a, b)h + f_y(a, b)k)$$

$$= (f_x(a+h, b) - f_x(a, b))h + (f_y(a+h, b) - f_y(a, b))k$$

$$= o(\sqrt{h^2+k^2}) \quad \checkmark f(a+h, b) - f(a, b) - f_x(a, b)h = o(|h|)$$

\hookrightarrow by continuity of f_x & f_y

Theorem: If $z = f(x_1, x_2, \dots, x_n)$ has at least $(n-1)$ of $\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}$ to be conti., then f is diffble.

Defⁿ: $f \in C^k$ iff all partial derivatives of order $\leq k$ are continuous.

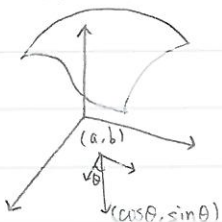
Directional derivatives

$$D_{\theta} f(a, b) = \lim_{r \rightarrow 0} \frac{f(a+r\cos\theta, b+r\sin\theta) - f(a, b)}{r}$$

Assume that f is diffble at (a, b)

$$= f_x(a, b)\cos\theta + f_y(a, b)\sin\theta + o(\sqrt{h^2+k^2})$$

$$= f_x \cos\theta + f_y \sin\theta$$





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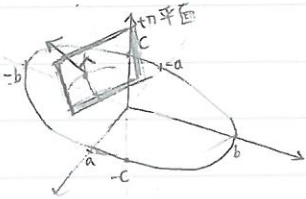
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Chain rule

$$u = f(x, y, z) \begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases}$$

ellipsoid $\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 + \left(\frac{z}{c}\right)^2 = 1$



$$f(x, y, z) = C \text{ (constant)}$$

$$\frac{\Delta f}{\Delta t} = f_x \frac{\Delta x}{\Delta t} + f_y \frac{\Delta y}{\Delta t} + f_z \frac{\Delta z}{\Delta t} + o\left(\frac{|\Delta \vec{x}|}{\Delta t}\right)$$

$$\rightarrow \sqrt{\Delta x^2 + \Delta y^2 + \Delta z^2}$$

$$\lim_{\Delta t \rightarrow 0} \frac{\Delta f}{\Delta t} = f_x x' + f_y y' + f_z z'$$

$$\nabla f(x, y, z)$$

$$\approx \frac{o(|\Delta \vec{x}|)}{|\Delta \vec{x}|} \cdot \left| \frac{\Delta \vec{x}}{\Delta t} \right|$$

Defⁿ: $\nabla f = (f_x, f_y, f_z)$ called the gradient of f

eg^l $u = f(x, y, z) = 3x^2 + 2y^2 + z^2$ on the level surface $u=1$,

the normal vector i.e. given by $\nabla f = (6x, 4y, 2z)$



$$z = f(x, y) = f(a, b) + f_x(a, b)(x-a) + f_y(a, b)(y-b)$$

up to $o(\sqrt{(x-a)^2 + (y-b)^2})$

f is diff. at $(a, b) \iff$ the notion of tangent plane exists.

Total differential 全微分

$$df = f_x dx + f_y dy$$

$$"d" = \partial x \frac{\partial}{\partial x} + dy \frac{\partial}{\partial y}$$

operator
算子

$(f \in C^2)$

$$\begin{aligned} d^2 f &= d(f_x dx + f_y dy) = f_{xx} dx^2 + f_{xy} dy dx + f_{yx} dx dy + f_{yy} dy^2 \\ &= f_{xx} dx^2 + 2f_{xy} dx dy + f_{yy} dy^2 \end{aligned}$$



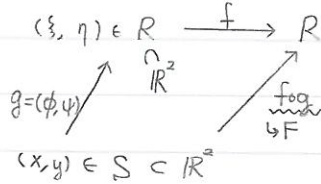
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§ 16 composite of functions

$$u = f(\xi, \eta)$$



$$\xi = \phi(x, y) ; \eta = \psi(x, y)$$

Thm f, g are differentiable $\Rightarrow F := f \circ g$ is also differentiable & formula
 (ϕ, ψ are both diff'ble)

$$u = f(\xi, \eta) = f(\phi(x, y), \psi(x, y))$$

$$\Delta u = A \Delta x + B \Delta y + \epsilon$$

$\hookrightarrow o(\sqrt{(\Delta x)^2 + (\Delta y)^2})$

$$\begin{aligned}
 du &= f_\xi \Delta \xi + f_\eta \Delta \eta & \begin{cases} d\xi = \phi_x dx + \phi_y dy \\ d\eta = \psi_x dx + \psi_y dy \end{cases} \\
 &= (f_\xi \phi_x + f_\eta \psi_x) dx + (f_\xi \phi_y + f_\eta \psi_y) dy \\
 &\quad \left[\frac{\partial u}{\partial x} \right] dx & \quad \left[\frac{\partial u}{\partial y} \right] dy
 \end{aligned}$$

$$\begin{aligned}
 \Delta u &= f_\xi \Delta \xi + f_\eta \Delta \eta + \epsilon \sqrt{(\Delta \xi)^2 + (\Delta \eta)^2} & \begin{cases} \Delta \xi = \phi_x \Delta x + \phi_y \Delta y + \epsilon_1 \sqrt{(\Delta x)^2 + (\Delta y)^2} \\ \Delta \eta = \psi_x \Delta x + \psi_y \Delta y + \epsilon_2 \sqrt{(\Delta x)^2 + (\Delta y)^2} \end{cases} \\
 &= (f_\xi \phi_x + f_\eta \psi_x) \Delta x + (f_\xi \phi_y + f_\eta \psi_y) \Delta y + \underbrace{[\epsilon_1 \sqrt{(\Delta \xi)^2 + (\Delta \eta)^2} + (f_\xi \epsilon_1 + f_\eta \epsilon_2) \sqrt{(\Delta x)^2 + (\Delta y)^2}]}_{\epsilon}
 \end{aligned}$$

$$(\Delta x, \Delta y) \rightarrow (0, 0) \Rightarrow (\Delta \xi, \Delta \eta) \rightarrow (0, 0)$$

$$\begin{aligned}
 \sqrt{(\Delta \xi)^2 + (\Delta \eta)^2} &\leq |\Delta \xi| + |\Delta \eta| \leq |\phi_x| |\Delta x| + |\phi_y| |\Delta y| + |\epsilon_1| \sqrt{(\Delta x)^2 + (\Delta y)^2} \\
 &\Rightarrow \frac{\sqrt{(\Delta \xi)^2 + (\Delta \eta)^2}}{\sqrt{(\Delta x)^2 + (\Delta y)^2}} \leq |\phi_x| \frac{|\Delta x|}{\sqrt{(\Delta x)^2 + (\Delta y)^2}} + |\phi_y| \frac{|\Delta y|}{\sqrt{(\Delta x)^2 + (\Delta y)^2}} + |\epsilon_1| \text{ is bounded} *
 \end{aligned}$$

$$\begin{aligned}
 u = f(x, y) &= f(r \cos \theta, r \sin \theta) \\
 \frac{\partial u}{\partial r} &= \frac{\partial u}{\partial x} x_r + \frac{\partial u}{\partial y} y_r = f_x \cos \theta + f_y \sin \theta
 \end{aligned}$$

$$\frac{\partial u}{\partial \theta} = u_x x_\theta + u_y y_\theta = -u_x r \sin \theta + u_y r \cos \theta$$

$$\Rightarrow (\Delta \xi, \Delta \eta) \rightarrow (0, 0) \quad (\Delta x, \Delta y) \rightarrow (0, 0)$$



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$$u = f(\xi, \eta) \quad , \quad \begin{cases} \xi = \phi(x, y) \\ \eta = \psi(x, y) \end{cases}$$

$$u_x = u_\xi \xi_x + u_\eta \eta_x$$

$$u_{yx} = (u_\xi \xi_x)_y + (u_\eta \eta_x)_y = u_{\xi\xi} \xi_y \xi_x + u_{\eta\xi} \eta_y \xi_x + u_{\xi\eta} \xi_y \eta_x + u_{\eta\eta} \eta_y \eta_x + u_\xi \eta_{yx} + u_\eta \xi_{yx}$$

$$u_{xx} = u_{\xi\xi} (\xi_x)^2 + u_{\eta\xi} \eta_x \xi_x + u_{\xi\eta} \xi_x \eta_x + u_{\eta\eta} (\eta_x)^2 + u_\xi \eta_{xx} + u_\eta \xi_{xx}$$

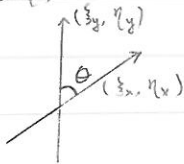
$$u_{yy} = \dots \dots \text{依此類推}$$

} assume C^2

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = u_{\xi\xi} (\xi_x^2 + \xi_y^2) + u_{\eta\eta} (\eta_x^2 + \eta_y^2) + 2 \cdot u_{\xi\eta} (\xi_x \eta_x + \xi_y \eta_y)$$

$$(x, y) \mapsto (\xi, \eta)$$

保角變換



$$\xi_x \xi_y + \eta_x \eta_y = 0$$

$$\xi_x^2 + \eta_x^2 = \xi_y^2 + \eta_y^2$$

$$(Ex) \quad \begin{matrix} \text{circle} \\ \text{INVERSION} \end{matrix} \quad (x, y) \mapsto \left(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2} \right) \quad \longleftarrow \quad f(\xi, \eta) = f\left(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2} \right)$$

$$\xi_x = \frac{x^2+y^2-2x^2}{(x^2+y^2)^2} = \frac{-x^2+y^2}{(x^2+y^2)^2}$$

$$\eta_x = \frac{-2xy}{(x^2+y^2)^2}$$

$$\xi_y = \frac{-2yx}{(x^2+y^2)^2}$$

$$\eta_y = \frac{x^2-y^2}{(x^2+y^2)^2}$$

$$\xi_x \eta_x + \xi_y \eta_y = 0 \quad , \quad \xi_x^2 + \xi_y^2 = \eta_x^2 + \eta_y^2$$

$$\xi_{xx} = \frac{-2x(x^2+y^2)^2 - (-x^2+y^2) \cdot 2 \cdot (x^2+y^2) \cdot 2x}{(x^2+y^2)^4} = \frac{2x^3 - 6xy^2}{(x^2+y^2)^3} \quad , \quad \xi_{yy} = \frac{-2x^3 + 6xy^2}{(x^2+y^2)^3}$$

$$\Rightarrow \xi_{xx} + \xi_{yy} = 0 = \eta_{xx} + \eta_{yy}$$

$$u = f(x, y) = f(r \cos \theta, r \sin \theta) \quad \text{with } r(\cos \theta + i \sin \theta)$$

$$\Delta u = u_{xx} + u_{yy}$$

$$\begin{cases} u_r = u_x x_r + u_y y_r \\ u_\theta = u_x x_\theta + u_y y_\theta \end{cases}$$

$$\begin{pmatrix} u_r \\ u_\theta \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix} \begin{pmatrix} u_x \\ u_y \end{pmatrix}$$

$$\text{with } -r \sin \theta + r \cos \theta$$



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Polar coordinate

$$u = u(x, y) \quad x = r \cos \theta, \quad y = r \sin \theta$$

$$\Delta u = u_{xx} + u_{yy}$$

$$u_x = u_r r_x + u_\theta \theta_x$$

$$= u_r \cdot \frac{-y}{r^2} + u_\theta \cdot \frac{-y}{r^2}$$

$$u_y = u_r \cdot \frac{x}{r^2} + u_\theta \cdot \frac{x}{r^2}$$

$$r = \sqrt{x^2 + y^2}, \quad \theta = \tan^{-1} \frac{y}{x}$$

$$r_x = \frac{x}{\sqrt{x^2 + y^2}}, \quad r_y = \frac{y}{\sqrt{x^2 + y^2}}$$

$$\theta_x = \frac{-y/x^2}{1 + (y/x)^2} = \frac{-y}{x^2 + y^2}, \quad \theta_y = \frac{x}{x^2 + y^2}$$



Rmk 非保角变换 $(r, \theta) \not\sim (x, y)$, So it's not a conformal change of coordinates

[Assume c^2]

$$u_{xx} = (u_r \cdot \frac{-y}{r^2} - u_\theta \cdot \frac{y}{r^2})_x$$

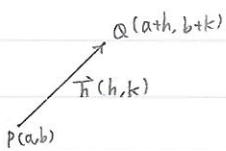
$$= u_{rr} \cdot \frac{x^2}{r^2} + u_{r\theta} \cdot \frac{-y}{r^2} \cdot \frac{-y}{r^2} + u_{r\theta} \cdot \frac{-y}{r^2} \cdot \frac{x}{r^2} - u_{\theta r} \cdot \frac{y}{r^2} \cdot \frac{x}{r^2} + u_{\theta\theta} \cdot (\frac{y}{r^2})^2 + u_{\theta\theta} \cdot \frac{2yx}{r^4}$$

$$= u_{rr} \cdot \frac{x^2}{r^2} + u_{\theta\theta} \cdot \frac{y^2}{r^2} - 2u_{r\theta} \cdot \frac{xy}{r^2} + u_r \cdot \frac{y^2}{r^2} + u_\theta \cdot \frac{2xy}{r^2}$$

$$u_{yy} = u_{rr} \cdot \frac{y^2}{r^2} + u_{\theta\theta} \cdot \frac{x^2}{r^2} + 2u_{r\theta} \cdot \frac{-yx}{r^2} + u_r \cdot \frac{x^2}{r^2} - u_\theta \cdot \frac{2xy}{r^2}$$

$$\rightarrow \Delta u = u_{xx} + u_{yy} = u_{rr} + \frac{1}{r^2} u_{\theta\theta} + \frac{1}{r} u_r$$

§1.7 Mean Value Theorem & Taylor expansion



$$f(Q) - f(P) = f(P + \vec{h}) - f(P)$$

$$[\text{Let } g(t) = f(P + t\vec{h})] = g(1) - g(0) = g'(0) \cdot (1-0) = \nabla f(P + \theta\vec{h}) \cdot \vec{h}$$

$$g'(t) = \frac{d}{dt} f(P + t\vec{h}) = f_x h + f_y k = \nabla f(h, k) = \nabla f \cdot \vec{h}$$

Taylor expansion

$$f(x, y) = \underbrace{f(a, b)}_{a_{00}} + \underbrace{a_{10}(x-a)}_{f_x(a,b)} + \underbrace{a_{01}(y-b)}_{f_y(a,b)} + \underbrace{a_{20}(x-a)^2}_{\frac{1}{2}f_{xx}(a,b)} + \underbrace{a_{11}(x-a)(y-b)}_{f_{xy}(a,b)} + \underbrace{a_{02}(y-b)^2}_{\frac{1}{2}f_{yy}(a,b)} + \dots$$

$$f(x, y) = a_{10} + 2a_{20}(x-a) + a_{11}(y-b) + \dots$$

$$\Rightarrow \underline{f_x(a, b) = a_{10}}$$



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$$* f(x, y) = f(a, b) + a_{10}(x-a) + a_{01}(y-b) + a_{20}(x-a)^2 + a_{11}(x-a)(y-b) + a_{02}(y-b)^2 + \dots$$

$$g(t) = f(P + t\vec{h})$$

$$g'(t) = \nabla f \cdot \vec{h} = f_x h + f_y k = (h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y}) f = \underline{d}f \text{ [differential operator 微分算子]}$$

$$g''(t) = (h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y})^2 f$$

$$\uparrow \frac{d}{dt} (f_x h + f_y k) = f_{xx} h^2 + f_{xy} h k + f_{yx} k h + f_{yy} k^2 = (h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y})^2 f$$

$$\Rightarrow \text{If } f \in C^k, \text{ the } g^{(k)}(t) = d^k f = (h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y})^k f$$

$$g(t) = g(0) + g'(0)t + \frac{g''(0)}{2!} t^2 + \dots + \frac{g^{(n)}(0)}{n!} t^n + R_n$$

$$\text{Assume that } g \in C^{n+1} \rightarrow R_n = \frac{g^{(n+1)}(0)}{(n+1)!} t^{n+1}$$

$$g^{(k)}(0) = h^k \frac{\partial^k f}{\partial x^k} (a, b) + \dots + C_{\vec{h}}^k h^i k^{k-i} \frac{\partial^k f}{\partial x^i \partial y^{k-i}} (a, b) + \dots$$

$$\Rightarrow f(x, y) = f(a, b) + f_x(a, b) \cdot (x-a) + f_y(a, b) \cdot (y-b)$$

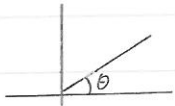
$$+ \frac{1}{2!} [f_{xx}(a, b) (x-a)^2 + 2f_{xy}(a, b) \cdot (x-a)(y-b) + f_{yy}(a, b) \cdot (y-b)^2]$$

$$+ \frac{1}{3!} [\dots]$$

conformal mapping

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{bmatrix} a & b \\ -b & a \\ a & b \\ b & -a \end{bmatrix}$$

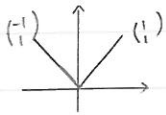


$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} a \\ c \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} a+b \\ c+d \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} b \\ -a \end{pmatrix}$$

$$\begin{pmatrix} -1 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} -a+b \\ -c+d \end{pmatrix}$$



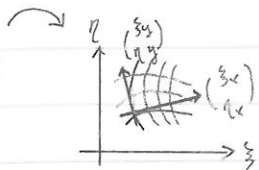
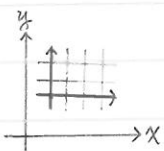
$$ab+cd=0 \Rightarrow ab=-cd$$

$$b^2-a^2+d^2-c^2=0 \Rightarrow b^2-a^2=c^2-d^2$$

$$\Rightarrow b^4-2ab^2+a^4=c^4-2cd^2+d^4$$

$$(\text{since } ab=-cd) \Rightarrow b^4+2a^2b^2+a^4=c^4+2c^2d^2+d^4 \Rightarrow (a^2+b^2)^2=(c^2+d^2)^2$$

$$\begin{cases} b^2+a^2=c^2+d^2 \\ b^2-a^2=c^2-d^2 \end{cases} \Rightarrow \begin{cases} b^2=c^2 \\ a^2=d^2 \end{cases}$$



$$u = f(\xi, \eta) \quad \begin{pmatrix} \xi(x, y) \\ \eta(x, y) \end{pmatrix}$$

$$\begin{pmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{pmatrix} \text{ Jacobian}$$

$$\textcircled{1} \begin{cases} \xi_x = \eta_y \\ \xi_y = -\eta_x \end{cases}$$

$$\textcircled{2} \begin{cases} \xi_x = -\eta_y \\ \xi_y = \eta_x \end{cases}$$

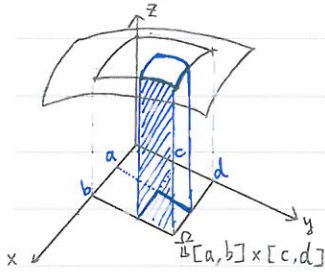


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§1.8 Integrals of functions with parameters



$$\int_c^d f(x,y) dy$$

↑
parameter

→ Let $f(x,y)$ be continuous

eg] $\int_a^b y^{\frac{1}{2}} dy = \frac{1}{\frac{1}{2}+1} y^{\frac{1}{2}+1} \Big|_a^b$

① $g(x)$ is continuous

$$|g(x+h) - g(x)| = \left| \int_c^d (f(x+h,y) - f(x,y)) dy \right| \leq \epsilon (d-c)$$

uniform continuity for continuous function with motivations

Assume that $f_x(x,y)$ exists and is continuous

$$g(x) = \int_c^d f(x,y) dy$$

$$g'(x) \stackrel{?}{=} \int_c^d f_x(x,y) dy$$

↓
Ans: Yes!

eg] $g(k) = \int_0^1 (x-1) \frac{x^k}{\log x} dx \quad [k > -1, k \in \mathbb{R}]$

$$\frac{d}{dk} g(k) = \int_0^1 \frac{x-1}{\log x} \frac{d}{dk} (x^k) dx$$

↓
 $x^k = e^{\log x^k} = e^{k \log x}$

pf] $g'(x) = \lim_{h \rightarrow 0} \frac{1}{h} [g(x+h) - g(x)]$

$$= \lim_{h \rightarrow 0} \frac{1}{h} \int_c^d \underbrace{(f(x+h,y) - f(x,y))}_{h \cdot f_x(x+\theta h, y)} dy \stackrel{?}{=} \int_c^d f_x(x,y) dy \quad (P. 75)$$

$$\rightarrow \int_c^d f_x(x+\theta h, y) dy - \int_c^d f_x(x, y) dy = \int_c^d (f_x(x+\theta h, y) - f_x(x, y)) dy \leq \epsilon (d-c) \quad \text{when } |h| < \delta \quad \#$$



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Subject : f_x conti, ϕ_1, ϕ_2 diff'ble

$$g(x) = \int_{\phi_1(x)}^{\phi_2(x)} f(x, y) dy$$

$$g'(x) = f(x, \phi_2(x)) \cdot \phi_2'(x) - f(x, \phi_1(x)) \cdot \phi_1'(x) + \int_{\phi_1(x)}^{\phi_2(x)} f_x(x, y) dy$$

$$F(x, u, v) = \int_u^v f(x, y) dy \quad g(x) = F(x, \phi_1(x), \phi_2(x)) \downarrow$$

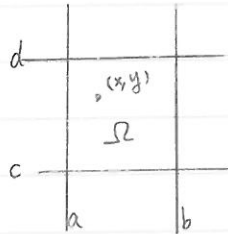
$$g'(x) = F_x \frac{dx}{dx} + F_u \frac{du}{dx} + F_v \frac{dv}{dx} = \int_u^v f_x(x, y) dy - f(x, u) \cdot \phi_1'(x) + f(x, v) \cdot \phi_2'(x)$$

↑
substitute $u = \phi_1(x), v = \phi_2(x)$

P. 76

$$\tilde{F}(x, u) = \int_a^u f(x, y) dy$$

$$g'(x) = \tilde{F}(x, \phi_2(x)) - \tilde{F}(x, \phi_1(x))$$



$$\int_a^b dx \int_c^d f(x, y) dy \neq \int_c^d dy \int_a^b f(x, y) dx$$

Ans: Yes, if $f(x, y)$ is continuous < Fubini theorem >

$$v(x, y) = \int_c^y f(x, \eta) d\eta \rightarrow v_y = f(x, y) \text{ conti.}$$

$$u(x, y) = \int_a^x v(\xi, y) d\xi = \int_a^x d\xi \int_c^y f(\xi, \eta) d\eta$$

$$u_y(x, y) = \int_a^x v_y(\xi, y) d\xi = \int_a^x f(\xi, y) d\xi = \int_a^x f(\xi, y) d\xi$$

$$\frac{u(x, y) - u(x, c)}{y - c} = \int_a^x d\xi \int_c^y f(\xi, \eta) d\eta \quad \neq$$

$$\int_a^x d\xi \int_c^y f(\xi, \eta) d\eta$$



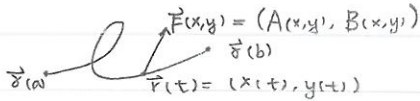
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§ 1.9 Differential and Line integrals

<Recall> arc length, work



$$\vec{r}: [a, b] \rightarrow \mathbb{R}^2$$

$$\int_a^b \vec{F} \cdot d\vec{r} = \int_a^b \left(A(x,y) \frac{dx}{dt} + B(x,y) \frac{dy}{dt} \right) dt = \int_{\Gamma} A dx + B dy$$

$$\downarrow$$

$$\vec{r}(t) dt = \left(\frac{dx}{dt}, \frac{dy}{dt} \right) dt$$

→ this is independent of the parameter "t" as long as the orientation of Γ is preserved.

This is a general form of "1-differential form" = 1 微分形式

[eg] Total differential $df = f_x dx + f_y dy$

* usually (in this book), we denote by Γ^* a curve with a fixed orientation

* Γ with the reverse orientation is denoted by $-\Gamma^*$

$$\left(\int_{-\Gamma^*} = - \int_{\Gamma^*} \right)$$

Let $L := A dx + B dy + C dz$

A, B, C are functions in $x, y, z \in \mathbb{C}^1$

If $L = df$ for some f

i.e. $A = f_x, B = f_y, C = f_z$ [or equivalently $(A, B, C) = \nabla f$]

$$\text{then } \int_{\Gamma} L = \int_{\Gamma} df = \int_a^b \frac{df}{dt} dt = f(x(t), y(t), z(t)) \Big|_a^b = f(Q) - f(P)$$

$$\downarrow$$

$$f_x \frac{dx}{dt} + f_y \frac{dy}{dt} + f_z \frac{dz}{dt}$$

If such an f does exist,

then we must have $A \overset{f_x}{}, B \overset{f_y}{}, C \overset{f_z}{} [f \in \mathbb{C}^1]$

$$\left[\begin{array}{l} A_y = B_x \text{ (both} = f_{xy} \text{)} \\ B_z = C_y; C_x = A_z \end{array} \right] \star$$

Q: Does condition \star imply the existence of f ?



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(Examples) ① $L = y dx + z dy + x dz$

$$A_y = 1 \neq B_x = 0$$

② $L = yz dx + zx dy + xy dz = d(xyz) \Rightarrow f = xyz$

$$A_y = z = B_x \Rightarrow \dots \dots$$

③ Fake total differential

$$"d\theta" = d \tan^{-1}\left(\frac{y}{x}\right) = \frac{-y dx + x dy}{x^2 + y^2} \rightarrow \left(\tan^{-1}\left(\frac{y}{x}\right)\right)' = \frac{y' \frac{1}{x} + y \frac{-x'}{x^2}}{1 + \left(\frac{y}{x}\right)^2}$$

$$A = \frac{-y}{x^2 + y^2}, \quad B = \frac{x}{x^2 + y^2}$$

$$A_y = \frac{-(x^2 + y^2) - (-y) \cdot 2y}{(x^2 + y^2)^2} = \frac{-x^2 + y^2}{(x^2 + y^2)^2}$$

$$= \frac{-y x' + x y'}{x^2 + y^2}$$

$$B_x = \frac{-(-y^2 + x^2)}{(x^2 + y^2)^2} = A_y$$



Γ^* = unit circle

$$(x(t), y(t)) = (\cos \theta, \sin \theta)$$

$$\langle r=1 \rangle$$

but $\int_{\Gamma^*} \frac{-y dx + x dy}{x^2 + y^2}$

$$= \int_0^{2\pi} -\sin \theta (-\sin \theta) d\theta + \cos \theta \cos \theta d\theta$$

$$= \int_0^{2\pi} d\theta = 2\pi \neq 0$$

* Next time we will show the condition $\nabla \times \vec{F} = 0$ is sufficient if the domain $U \subset \mathbb{R}^3$ of $\vec{F} = (a, b)$ is simply connected (單連通)

(Example 2) $\vec{F}(x, y, z) = \left(\frac{x}{\sqrt{x^2 + y^2 + z^2}}, \frac{y}{\sqrt{x^2 + y^2 + z^2}}, \frac{z}{\sqrt{x^2 + y^2 + z^2}} \right)$

$$\nabla \cdot \vec{F} \quad f(x, y, z) = \frac{-1}{\sqrt{x^2 + y^2 + z^2}}$$

$$\Rightarrow A_y = B_x, \quad B_z = C_y, \quad C_x = A_z$$

(Example 3) $\mathbb{R}^3 \setminus (0, 0, 0)$ is simply connected

$\mathbb{R}^3 \setminus \mathbb{R}$ is not simply connected



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Fact: The line integral \int_L is independent of path $\Leftrightarrow L = df$ for some f

pf " \Leftarrow " ok.

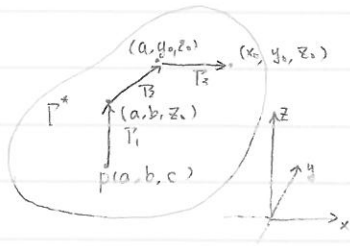
" \Rightarrow " we have to "define f " first

$$f(x, y, z) := \int_P L = \int_{P^*} A dx + B dy + C dz$$

↑
any piece-wise C^1 curve connecting P and (x, y, z)

fix $P \in \mathbb{R}^3$

$$\frac{\partial f}{\partial x} \Big|_{(x, y, z)} = \frac{\partial}{\partial x} \left(\int_{\Gamma_1} + \int_{\Gamma_2} + \int_{(a, y_0, z_0)}^{(x_0, y_0, z_0)} A dx + B dy + C dz \right) = A(x_0, y_0, z_0)$$



similarly, $B = f_y$, $C = f_z$



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Line integral



[1-form]

$$\int_{\gamma} L = \int_a^b (A \frac{dx}{dt} + B \frac{dy}{dt} + C \frac{dz}{dt}) dt$$

$\downarrow \quad \downarrow \quad \downarrow$
 $A dx + B dy + C dz \quad A(x(t), y(t), z(t))$

Last time: $\int_{\gamma} L$ is independent of path $\Leftrightarrow L = df = f_x dx + f_y dy + f_z dz$
 for some f (potential function)
 $\vec{F} = \nabla f$

$$f \quad \nabla f = \text{grad } f = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) f$$

$$\vec{F} = (A, B, C) \quad \text{div } f = \frac{\partial A}{\partial x} + \frac{\partial B}{\partial y} + \frac{\partial C}{\partial z} \quad (\text{divergence 散度}) = \nabla \cdot \vec{F}$$

$$\text{curl } \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A & B & C \end{vmatrix} = (C_y - B_z, A_z - C_x, B_x - A_y)$$

(旋度)

$\uparrow \downarrow$
 compatibility condition, coming from $f_{x_i x_j} = f_{x_j x_i}$

$$L = A dx + B dy + C dz \leftrightarrow \vec{F} = (A, B, C)$$

Elie Cartan's d-operator

$$\begin{aligned}
 dx dy & \quad \Delta x \Delta y & \rightarrow dA \wedge dx + dB \wedge dy + dC \wedge dz \\
 \rightarrow dx \wedge dy = -dy \wedge dx & & = (A_x dx + A_y dy + A_z dz) \wedge dx \\
 \begin{vmatrix} a & b \\ c & d \end{vmatrix} = - \begin{vmatrix} b & a \\ d & c \end{vmatrix} & & + (B_x dx + B_y dy + B_z dz) \wedge dy \\
 & & + (C_x dx + C_y dy + C_z dz) \wedge dz \\
 & & = (B_x - A_y) dx \wedge dy + (C_y - B_z) dy \wedge dz + (A_z - C_x) dz \wedge dx
 \end{aligned}$$

$$\begin{aligned}
 L = \sum_{i=1}^n A_i dx^i & \quad dL = \sum_{i=1}^n dA_i \wedge dx^i = 0 \\
 \left(\sum_{i=1}^n \left(\frac{\partial A_i}{\partial x_j} dx^j \right) \wedge dx^i \right) & = \sum_{i,j} \left(\frac{\partial A_j}{\partial x_i} - \frac{\partial A_i}{\partial x_j} \right) dx^i \wedge dx^j \quad [\text{closed 1-form}]
 \end{aligned}$$

Theorem

Let L be an C^1 one-form defined on a simply connected open set $U \subseteq \mathbb{R}^n$

$$dL = 0 \Leftrightarrow L = df \text{ for some } f$$

closed 1-form exact.

(Recall) \Leftarrow trivial

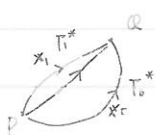
\Rightarrow is reduced to prove that the line integral is independent of path.



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<Reality>

Simply connectedness 單連通



$$\begin{aligned} x_0 : [0, 1] &\rightarrow \mathbb{R}^2 \\ x_1 : [0, 1] &\rightarrow \mathbb{R}^2 \end{aligned}$$

$$\begin{aligned} x_0(0) &= P, \quad x_0(1) = Q \\ x_1(0) &= P, \quad x_1(1) = Q \end{aligned}$$

$$\exists \text{e. } x : [0, 1] \times [0, 1] \rightarrow U \text{ conti.}$$

Defⁿ: U is 1-connected (simply) if any 2 curves with the same end points can be deformed to each other continuously.

$$x(t, s) \quad \text{s.t. } x(t, 0) = x_0(t), \quad x(t, 1) = x_1(t)$$



Ball: $B_p(r)$

$$x(t, s) = (1-s)x_0(t) + s x_1(t)$$

Fact: Any convex set is 1-connected

$$\int_{\Gamma_1} L - \int_{\Gamma_0} L = \int_0^1 \left(A \frac{\partial x}{\partial t} + B \frac{\partial y}{\partial t} + C \frac{\partial z}{\partial t} \right) \Big|_{s=1} dt + \int_0^1 \left(A \frac{\partial x}{\partial s} + B \frac{\partial y}{\partial s} + C \frac{\partial z}{\partial s} \right) \Big|_{s=0} dt$$

$$A \frac{\partial x}{\partial s} \Big|_{s=1} - A \frac{\partial x}{\partial s} \Big|_{s=0} = \int_0^1 \frac{\partial}{\partial s} \left(A \frac{\partial x}{\partial t} \right) ds$$

$$\rightarrow \left(A_x \frac{\partial x}{\partial s} + A_y \frac{\partial y}{\partial s} + A_z \frac{\partial z}{\partial s} \right) \frac{\partial x}{\partial t} + A \frac{\partial^2 x}{\partial s \partial t}$$

$$\int_0^1 dt \int_0^1 \begin{pmatrix} (A_x x_s + A_y y_s + A_z z_s) x_t + A x_{st} \\ + (B_x x_s + B_y y_s + B_z z_s) y_t + B y_{st} \\ + (C_x x_s + C_y y_s + C_z z_s) z_t + C z_{st} \end{pmatrix} ds$$

$$\stackrel{\#}{=} (A_x s + B_y s + C_z s) t$$

$$B_x = A_y, B_z = C_y, A_x = C_x$$

$$= \int_0^1 ds \int_0^1 (A_x s + B_y s + C_z s) t dt$$

$$= \int_0^1 ds (A_x s + B_y s + C_z s) \Big|_{t=1} - \Big|_{t=0} = 0$$

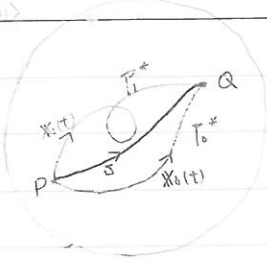


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◀ (Review) ▶

 $U \subset \mathbb{R}^n$ open set simply connectedin $\mathbb{R}^n \rightarrow (x^1, x^2, \dots, x^n)$

$$\int_{\Gamma_1} L$$

$$L = \sum_{i=1}^n A_i dx^i$$

$$dL = \sum_{i=1}^n dA_i \wedge dx^i = \sum_{i=1}^n \left(\sum_{j=1}^n \frac{\partial A_i}{\partial x^j} dx^j \right) \wedge dx^i \\ = \sum_{j < i} \left(\frac{\partial A_j}{\partial x^i} - \frac{\partial A_i}{\partial x^j} \right) dx^j \wedge dx^i$$

The necessary condition for the line integral to be independent of path

$$\text{i.e. } dL = 0 = \frac{\partial A_j}{\partial x^i} = \frac{\partial A_i}{\partial x^j}$$

$$\stackrel{\text{Poincaré}}{\Downarrow} \text{ [indep. of path } \equiv \exists f \text{ s.t. } L = df] \leftarrow \text{i.e. } A_i = \frac{\partial f}{\partial x^i} = f_i$$

$$(*) \int_{\Gamma_1} L = \int_{\Gamma_2} L$$

$$\exists X : [0,1] \times [0,1] \xrightarrow{\text{cont.}} U$$

$$X(t,s) = (x^1(t,s), x^2(t,s), \dots, x^n(t,s))$$

$$\text{s.t. } X(t,0) = X_0(t) = X(t,1) = X_1(t)$$

$$(*) = \int_0^1 dt \sum_{i=1}^n \left(A_i(X) \frac{\partial X^i}{\partial t} \Big|_{s=0} - A_i(X) \frac{\partial X^i}{\partial t} \Big|_{s=1} \right)$$

$$= \int_0^1 dt \int_0^1 ds \sum_{i=1}^n \frac{\partial}{\partial s} \left(A_i \frac{\partial X^i}{\partial t} \right)$$

$$= \int_0^1 dt \int_0^1 ds \sum_{i=1}^n \left(\frac{\partial A_i}{\partial x^j} \frac{\partial x^j}{\partial s} \frac{\partial x^i}{\partial t} + A_i \frac{\partial^2 x^i}{\partial t \partial s} \right)$$

$$= \int_0^1 ds \int_0^1 dt \sum_{i=1}^n \frac{\partial}{\partial t} \left(A_i \frac{\partial x^i}{\partial s} \right)$$

$$= \int_0^1 ds \left(\sum_{i=1}^n A_i \frac{\partial x^i}{\partial s} \Big|_{t=0}^{t=1} \right) = 0$$



Subject :

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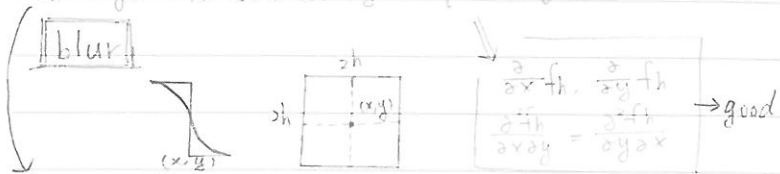
$$X(t,s) = (X^i(t,s))_{i=1}^n$$

↑
continuous in t,s

problem: $f(x,y)$ conti. in x,y

we want to approximate f by a C^2 function [h fixed small number]

$$f_h(x,y) = \frac{1}{4h^2} \int_{x-h}^{x+h} \int_{y-h}^{y+h} f(\xi,\eta) d\xi d\eta$$



check the text book

$$= [u(x+h, y+h) - u(x+h, y-h) - u(x-h, y+h) + u(x-h, y-h)] / 4h^2$$

$$|f_h(x,y) - f(x,y)| = \frac{1}{4h^2} \int_{x-h}^{x+h} \int_{y-h}^{y+h} (f(\xi,\eta) - f(x,y)) d\xi d\eta < \varepsilon$$

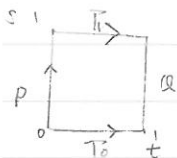
(if $\varepsilon < \varepsilon$)

"Homotopy"

$X^i(t,s)$ is now approximated by $\bar{X}^i(t,s)$, $i=1,2,\dots,n$

↑
conti.

↑
good function $C \rightarrow U$



$$\begin{aligned} \bar{X}(t,s) &= \bar{X}(t,s) - (1-s)(\bar{X}(t,s) - X_0(t)) - s(\bar{X}(t,s) - X_1(t)) \\ &= (1-t)(\bar{X}(t,s) - X_0(0)) - t(\bar{X}(t,s) - X_1(1)) \\ &\quad + (1-t)(1-s)(\bar{X}(0,0) - X_0(0)) \\ &\quad + (1-t)s(\bar{X}(0,1) - X_1(0)) \\ &\quad + (1-s)t(\bar{X}(1,0) - X_0(1)) \\ &\quad + st(\bar{X}(1,1) - X_1(1)) \end{aligned}$$



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§ Appendix

$$\mathbb{R}^1 \quad \mathbb{R}^n$$

$$[a, b] \quad [a_1, b_1] \times [a_2, b_2] \times \dots \times [a_n, b_n]$$



closed and bounded subset

[bounded means $S \subset B_0(R)$ for some R

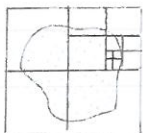
[closed means S contains all its boundary point ∂S

Theorem (Bolzano - Weirstrass)

Let $S \subset \mathbb{R}^n$ be a closed and bounded set,

then any sequence $P_n \in S$ ($n=1, 2, \dots$) has a convergent subsequence in S

[pf]



divided into 2^n subcube

\exists a subcube which still contain $\frac{1}{2}$ ∞ -many

Defⁿ: A set $S \subset \mathbb{R}^n$ is called (sequentially) compact iff it is closed and bounded

[Thm] Let $f: S \rightarrow \mathbb{R}$ be continuous with S being compact,
then $\exists p \in S$ s.t. $f(p) = \max f$

[pf]: claim $\exists M$ s.t. $f \leq M$,

if not, $\forall n \in \mathbb{N}$, $\exists P_n \in S$ s.t. $f(P_n) > n$

Let P_{n_i} be a convergent subsequence ~~fix~~ $P_{n_i} = p \in S$

$f(P_{n_i}) > n_i$

~~$\lim_{i \rightarrow \infty} f(P_{n_i}) \rightarrow \infty$~~

$f(\lim P_{n_i}) = f(p)$



Subject : chapter III.....

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Implicit functions 隱函數

(Example)

$$F(x,y) \rightarrow (x^2+y^2)^2 - 2x^2(x^2-y^2) = 0$$

find the maximal value of y ,

regard y is a function in x , " $y = f(x)$ "

Apply $\frac{d}{dx}$ to it = $2(x^2+y^2)(2x+2yf') - 2x^2(2x-2yf') = 0$

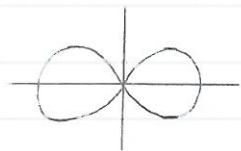
$f' = \dots$, Here we consider $f(x) = 0$

$$\Rightarrow (x^2+y^2)2x - x^2 - 2x^2 = 0$$

$$2x(x^2+y^2-x^2) = 0 \rightarrow x=0 \text{ or } x^2+y^2 = x^2$$

$$y^2 \geq 2y^2 = 0$$

$$x^2 \geq 2x^2 \Rightarrow x^2 = 0$$

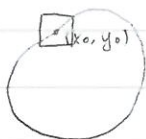


(Inverse)

Theorem (Implicit function Theorem)

Let $F(x,y)$ be C^1 , and $F(x_0, y_0) = 0$, $F_y(x_0, y_0) = m \neq 0$,

then \exists nbd of (x_0, y_0) s.t. $\exists!$ $y = f(x)$ s.t. $F(x, f(x)) = 0$ and $f \in C^1$



$$F(x,y) = 0$$

$$F_x + F_y \frac{dy}{dx} = 0$$

$$\Rightarrow \frac{dy}{dx} = -\frac{\partial F / \partial x}{\partial F / \partial y} = -\frac{F_x}{F_y}$$

[pf]:

<step1> " $\exists!$ "

$$\exists R = [x_0 - \alpha, x_0 + \alpha] \times [y_0 - \beta, y_0 + \beta]$$

s.t. $F_y > \frac{m}{2}$ on R and let $|F_x| \leq M$ on R

Notice that $F(x,y) \uparrow$ in y for any fixed x

$$|F(x, y_0) - F(x_0, y_0)| = |F_x(\xi, \xi_0)| \cdot |x - x_0| \leq M|x - x_0|$$

$$F_y(x, y) \geq \frac{m}{2}$$

$$F(x, y_0 + \beta) = (F(x, y_0 + \beta) - F(x, y_0)) + F(x, y_0) > \frac{m\beta}{2} - M|x - x_0| \rightsquigarrow > 0$$

$$F(x, y_0 - \beta) = (F(x, y_0 - \beta) - F(x, y_0)) + F(x, y_0) < -\frac{m\beta}{2} + M|x - x_0| \rightsquigarrow < 0$$

$$F_y(x, y) \geq \frac{m}{2}$$

we just require that $|x - x_0| < \frac{m\beta}{2M} =: \delta$

$\Rightarrow \exists!$ y s.t. $F(x, y) = 0$

call this $x \mapsto y$ by $y = f(x)$



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<step 1> " $f \in C^1$ " Let x be fixed

$$f(x+h) - f(x) = k$$

$$0 = F(x+h, \frac{f(x+h)}{y+k}) - F(x, \frac{f(x)}{y}) = F_x(x+\theta h, y+\theta k)h + F_y(x+\theta h, y+\theta k)k$$

$\Rightarrow |k| \leq \frac{\partial M}{\partial y} |h| \Rightarrow f$ is Lip. continuous

$$\frac{f(x+h) - f(x)}{h} = \frac{k}{h} = -\frac{F_x(x+\theta h, y+\theta k)}{F_y(x+\theta h, y+\theta k)}$$

$$= -\frac{F_x(x, y)}{F_y(x, y)} \quad \# \text{ Q.E.D.}$$

Multi-variable case

$F(x^1, x^2, \dots, x^n, y)$ st. $F(\bar{x}_0, y_0) = 0$; $F_y(\bar{x}_0, y_0) = m > 0$

<step 1> change x into \bar{x}

<step 2> $0 = F(\bar{x} + \bar{h}, f(\bar{x} + \bar{h})) - F(\bar{x}, f(\bar{x}))$

$$= \sum_{i=1}^n F_{x^i}(\bar{x} + \theta \bar{h}_i, y + \theta k) h^i + F_y(\bar{x} + \theta \bar{h}, y + \theta k) k$$

$$\left[\frac{\partial f}{\partial x^i} = -\frac{F_{x^i}}{F_y} \right] f(x, y) = 0, \quad f' = -\frac{F_x}{F_y}, \quad f'' = \frac{F_{xx} F_y + F_y^2 \left(-\frac{F_x}{F_y}\right) - F_x F_{yy} + F_{yy} \left(-\frac{F_x}{F_y}\right)}{-F_y^2}$$

Q.E.D.



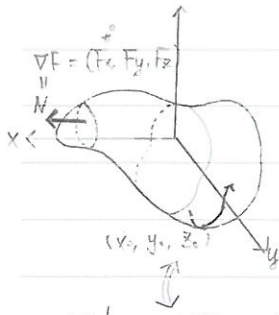
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$$u = F(x, y, z)$$

level set, $u = \text{constant} = 0$



$\subset \mathbb{R}^3$ "surface"

$$F(x_0, y_0, z_0) = 0, \quad F_x(x_0, y_0, z_0) \neq 0$$

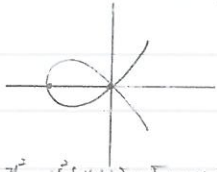
$\Rightarrow \exists!$ implicit function $x = f(y, z)$ near (x_0, y_0, z_0)
st. $(f(y, z), y, z) = 0$

* What happens if $\nabla f(x_0, y_0, z_0) = 0$

consider any curve through (x_0, y_0, z_0) on $F=0$

$$F(x(t), y(t), z(t)) = 0$$

$$0 = \nabla F \cdot (x'(t), y'(t), z'(t)) \Big|_{t=t_0}$$

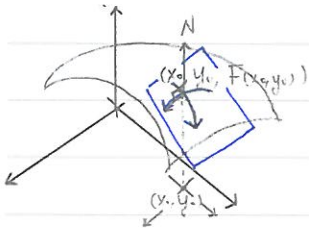


Defⁿ = A point $p \in \{x \mid F(x) = 0\}$ is a ^(奇異) singular point if the tangent vectors of p span the whole space ($\Leftrightarrow \nabla F(p) = 0$)

$$y^2 - x^2(x+1) = F(x, y)$$

$$\nabla F = (-2x^2, 2y)$$

(Example 1) : $z = f(x, y)$



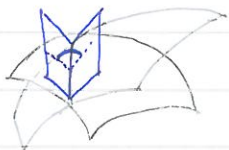
① By definition $z - z_0 = f_x(x_0, y_0) \cdot (x - x_0) + f_y(x_0, y_0) \cdot (y - y_0)$

$$\textcircled{2} \begin{matrix} (x, y, f(x, y)) \\ \begin{matrix} \uparrow \\ \text{z} \\ \downarrow \\ (x_0, y_0, f(x_0, y_0)) \end{matrix} \end{matrix} \begin{matrix} (1, 0, f_x) \\ (0, 1, f_y) \end{matrix} \rightarrow (-f_x, -f_y, 1)$$

$$(x - x_0, y - y_0, z - z_0) \cdot (-f_x, -f_y, 1) = 0$$

③ $F(x, y, z) := z - f(x, y) = 0$; $F=0$ level set $\Rightarrow \nabla F = (-f_x, -f_y, 1)$

(Example 2) $F=0, G=0$ in \mathbb{R}^3



$$\nabla F = N_1, \quad \nabla G = N_2$$



$$\cos w = \frac{\nabla F \cdot \nabla G}{|\nabla F| \cdot |\nabla G|} = \frac{F_x G_x + F_y G_y + F_z G_z}{\sqrt{F_x^2 + F_y^2 + F_z^2} \cdot \sqrt{G_x^2 + G_y^2 + G_z^2}}$$



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Trivial linear model

$$u = a_1 x_1 + a_2 x_2 + \dots + a_n x_n + b y$$

when $b \neq 0$, $u = 0$, $u \leftrightarrow y$

$$y = -\frac{a_1}{b} x_1 - \frac{a_2}{b} x_2 - \dots - \frac{a_n}{b} x_n + \frac{u}{b}$$

Non-linear version

$$u = F(\vec{x}, y) \text{ for a fixed } (\vec{x}_0, y_0), \quad \frac{\partial u}{\partial y} = F_y \neq 0$$

$$\Rightarrow y = G(\vec{x}, u) \text{ s.t. } u = F(\vec{x}, G(\vec{x}, u))$$

<Cor.> set $u = 0$, get $y = g(\vec{x})$ implicit function

Actually, \star follows from the $u = 0$ case

[pf] Let $H(\vec{x}, u, y) := u - F(\vec{x}, y)$

$$H_y = -F_y \neq 0 \Rightarrow y = G(\vec{x}, u)$$

$$\text{s.t. } H(\vec{x}, u, G(\vec{x}, u)) = 0 \quad \star \text{ Q.E.D.}$$

Theorem General form of IFT ^(Inverse) (implicit function theorem)

$$u = F(\vec{x}, y, z) \quad \text{with } D := \begin{vmatrix} F_y & F_z \\ G_y & G_z \end{vmatrix} \neq 0 \text{ at } (\vec{x}_0, y_0, z_0)$$

$$v = G(\vec{x}, y, z)$$

Then in a nbd. of (\vec{x}_0, y_0, z_0) , $\exists y = A(\vec{x}, u, v)$, $z = B(\vec{x}, u, v)$

$$\text{s.t. } u = F(\vec{x}, A(\vec{x}, u, v), B(\vec{x}, u, v))$$

$$v = G(\vec{x}, A(\vec{x}, u, v), B(\vec{x}, u, v))$$

[pf] May assume that $F_y \neq 0$ (otherwise change $y \leftrightarrow z$)

$$\frac{\partial u}{\partial y} = F_y \neq 0 \Rightarrow \exists y = \Phi(\vec{x}, u, z) \text{ s.t. } u = F(\vec{x}, \Phi(\vec{x}, u, z), z)$$

Now, the variables are u, z , and \vec{x}

$$v = G(\vec{x}, \Phi(\vec{x}, u, z), z), \text{ Need to compute } \frac{\partial v}{\partial z} = G_y \Phi_z + G_z$$

$$0 = \frac{\partial u}{\partial z} = F_y \Phi_z + F_z \Rightarrow \frac{\partial v}{\partial z} \neq 0 \Rightarrow \exists z = \Psi(\vec{x}, u, v)$$

$$\text{s.t. } u = F(\vec{x}, \Phi(\vec{x}, u, \Psi(\vec{x}, u, v)), \Psi(\vec{x}, u, v))$$

for any (\vec{x}, u, v) in the nbd.

$$v = G(\vec{x}, \Phi(\vec{x}, u, \Psi(\vec{x}, u, v)), \Psi(\vec{x}, u, v))$$

<2 special case >

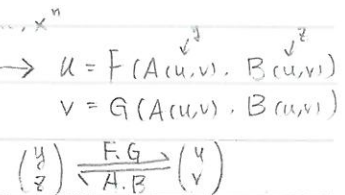
(I.) set $u = v = 0$, get $y(\vec{x}), z(\vec{x})$ (II.) let $n = 0$ (i.e. no \vec{x})

$$\text{s.t. } F(\vec{x}, y(\vec{x}), z(\vec{x})) = 0$$

$$G(\vec{x}, y(\vec{x}), z(\vec{x})) = 0$$

$$u = F(y, z) \quad v = G(y, z)$$

$$\text{if } D = \begin{vmatrix} u_y & u_z \\ v_y & v_z \end{vmatrix} \neq 0$$





Subject : $F(x, y, z)$

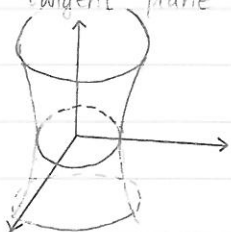
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(Eq) $\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$

$N = \nabla F = \left(\frac{2x_0}{a^2}, \frac{2y_0}{b^2}, \frac{-2z_0}{c^2} \right)$ at P

tangent plane at $P = (x_0, y_0, z_0)$



$N_p \cdot (x - x_0, y - y_0, z - z_0) = 0$

$\Rightarrow \frac{x_0(x - x_0)}{a^2} + \frac{y_0(y - y_0)}{b^2} - \frac{z_0(z - z_0)}{c^2} = 0$

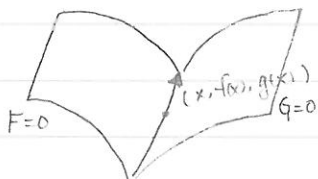
$\Rightarrow \frac{x_0 x}{a^2} + \frac{y_0 y}{b^2} - \frac{z_0 z}{c^2} = 1$

$u = F(x, y, z), \quad v = G(x, y, z), \quad c'$

condition $D = \begin{vmatrix} F_x & F_z \\ G_y & G_z \end{vmatrix} \neq 0$ at (x_0, y_0, z_0)

(Eq) $u = v = 0$

$\Rightarrow y = f(x, u, v) \quad z = g(x, u, v) \Rightarrow$ get $y = f(x), \quad z = g(x)$



st. $F(x, f(x), g(x)) = 0$

$G(x, f(x), g(x)) = 0$



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§ 3.7 Maxima and minima problem

$y = f(x)$, $f'(x) = 0$

(Eq) $f(x, y) = (ax^2 + by^2) e^{-(x^2 + y^2)}$ $[a, b \neq 0]$

(x_0, y_0) is an extremal point

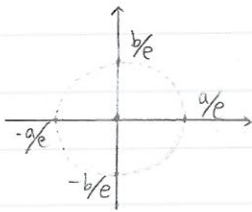
$\Rightarrow f_x(x_0, y_0) = f_y(x_0, y_0) = 0$

$\nabla f = 0 \leftarrow N = (-\nabla f, 1)$

$f_x = 2ax \cdot e^{-(x^2 + y^2)} + (ax^2 + by^2) e^{-(x^2 + y^2)} (-2x) = e^{-(x^2 + y^2)} \cdot 2x(a - ax^2 - by^2)$

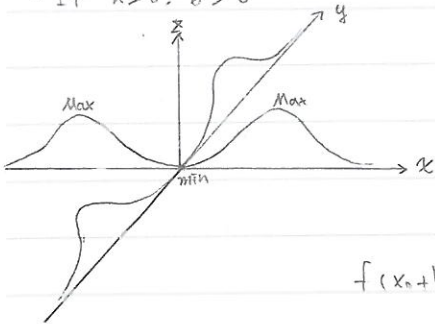
$f_y = 2by \cdot e^{-(x^2 + y^2)} + (ax^2 + by^2) e^{-(x^2 + y^2)} (-2y) = e^{-(x^2 + y^2)} \cdot 2y(b - ax^2 - by^2)$

$\nabla f = 0 \Leftrightarrow \begin{cases} y = 0 \\ x = 0 \\ x \neq 0 \Rightarrow a - ax^2 - by^2 = 0 \end{cases} \begin{cases} y \neq 0 \Rightarrow b(1 - y^2) = 0 \Rightarrow y = \pm 1 \\ y = 0 \Rightarrow x = \pm 1 \\ y \neq 0 \Rightarrow \begin{cases} b - ax^2 - by^2 = 0 \\ a - ax^2 - by^2 = 0 \end{cases} \end{cases}$



$a = b \begin{cases} \text{if } a \neq b, \text{ no such case} \\ \text{if } a = b, x^2 + y^2 = 1 \end{cases} [f_{x,y} = a^2 e^{-1}]$

• If $a > 0, b > 0$



$[a = b]$



$[a \neq b]$



Taylor expansion

$f(x, y) = f(x_0, y_0) + \frac{1}{2} [f_{xx}(x-x_0)^2 + 2f_{xy}(x-x_0)(y-y_0) + f_{yy}(y-y_0)^2]$

$f(x_0+h, y_0+k) = f(x_0, y_0) + \frac{1}{2} \begin{pmatrix} h & k \end{pmatrix} \begin{pmatrix} f_{xx} & f_{xy} \\ f_{xy} & f_{yy} \end{pmatrix} \begin{pmatrix} h \\ k \end{pmatrix} + \dots$

$\frac{1}{2} \vec{A} \vec{x}$
quadratic form

↑
symmetric matrix at (x_0, y_0)

$\vec{y}^T (\lambda_1 \dots \lambda_n) \vec{y}$ Z



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Next, we consider min/max problem with side conditions.

eg. $\frac{x^2+y^2+z^2}{3} \geq \sqrt[3]{x^2y^2z^2}$

Think as the min/max problem for $f(x,y,z) = x^2+y^2+z^2$ under $x^2+y^2+z^2 = C$

* Lagrange multiplier (乘子)

$u = f(x, y, z)$

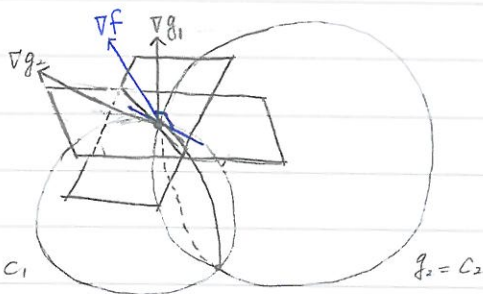
$v = g(x, y, z) = \text{constant}$

$\nabla f = \lambda \nabla g$ for some λ $\left[\begin{array}{l} (f_x, f_y, f_z) = \lambda (g_x, g_y, g_z) \\ g = \text{constant} \end{array} \right.$

$u = f(x, y, z)$

$g_1(x, y, z) = 0, g_2(x, y, z) = 0$

$\nabla f = \lambda_1 \nabla g_1 + \lambda_2 \nabla g_2$ $\left\{ \begin{array}{l} \nabla f = \lambda_1 \nabla g_1 + \lambda_2 \nabla g_2 \\ g_1 = 0 \\ g_2 = 0 \end{array} \right.$



$u = f(x, y, z) \big|_{h(x,y)} = f(x, y, h(x,y))$

$v = g(x, y, z) = \text{constant}$

$\left\{ \begin{array}{l} 0 = \frac{\partial u}{\partial x} = f_x + f_z h_x \\ 0 = \frac{\partial u}{\partial y} = f_y + f_z h_y \end{array} \right\} \parallel \left\{ \begin{array}{l} g_x + g_z h_x = 0 \\ g_y + g_z h_y = 0 \end{array} \right.$

$u = f(x, h(x), k(x))$ $\left\{ \begin{array}{l} g_1(x, h(x), k(x)) = 0 \\ g_2(x, h(x), k(x)) = 0 \end{array} \right.$

$0 = \frac{\partial u}{\partial x^i} = f_{x^i} + f_y h_{x^i} + f_z k_{x^i}$

$\forall i = 1, 2, \dots, n$

$0 = g_{1x^i} + g_{1y} h_{x^i} + g_{1z} k_{x^i}$

$0 = g_{2x^i} + g_{2y} h_{x^i} + g_{2z} k_{x^i}$



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(Ex1) $\frac{x_1 + x_2 + \dots + x_n}{n} \geq \sqrt[n]{x_1 x_2 \dots x_n}$

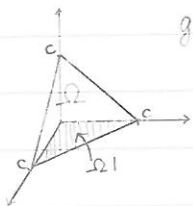
method ① Let $x_1 + \dots + x_n = C > 0$ fixed constant

$f(x_1, \dots, x_n) = x_1 \cdot x_2 \cdot \dots \cdot x_n$

equiv. to consider $g(x_1, \dots, x_{n-1}) = x_1 \cdot \dots \cdot x_{n-1} \cdot (C - x_1 - x_2 - \dots - x_{n-1})$

for simplicity we write out the case $n=3$

$g(x_1, x_2) = x_1 x_2 (C - x_1 - x_2)$



$x_1 + x_2 + x_3 = C \quad x_i > 0$

$f \equiv 0$ on $\partial\Omega$, the maxima of f exists and is in the interior of Ω

$g \equiv 0$ on $\partial\Omega_1$, the maxima of g exists and is in the interior of Ω .

$\frac{\partial g}{\partial x_1} = x_2(C - x_1 - x_2) - x_1 x_2 = x_2(C - 2x_1 - x_2) \stackrel{!}{=} 0$

$\frac{\partial g}{\partial x_2} = x_1(C - x_1 - 2x_2) \stackrel{!}{=} 0$

$\Rightarrow \begin{cases} 2x_1 + x_2 = C \\ x_1 + 2x_2 = C \end{cases} \Rightarrow x_1 = x_2$ in this case \approx

method ② Let $h(x) = x_1 + x_2 + \dots + x_n - C$

under $h(x) = 0$, solve maxima of f

$(\frac{1}{x_1}, \dots, \frac{1}{x_n}) = \nabla f = \lambda \nabla h = (\lambda, \lambda, \dots, \lambda) \Rightarrow x_1 = \dots = x_n \approx$

(Ex2) Holder inequality

$uv \leq \frac{1}{\alpha} u^\alpha + \frac{1}{\beta} v^\beta \leftarrow f(u,v) \quad \langle u, v \geq 0, \frac{1}{\alpha} + \frac{1}{\beta} = 1 \rangle$

fix $h(u,v) = uv = C > 0$

$(u^{\alpha-1}, v^{\beta-1}) = \nabla f = \lambda \nabla h = (\lambda v, \lambda u) \Rightarrow u^\alpha = v^\beta$

$v^\beta = u^\alpha = (\lambda v) u = \lambda uv = \lambda C \quad \begin{cases} u = (\lambda C)^{1/\alpha} \\ v = (\lambda C)^{1/\beta} \end{cases} \Rightarrow uv = (\lambda C)^{\frac{1}{\alpha} + \frac{1}{\beta}} = \lambda C$
 $\Rightarrow \lambda = 1 \rightarrow (\frac{1}{\alpha} + \frac{1}{\beta}) \lambda C = C$
 "="" holds

[general form] $\sum_{i=1}^n a_i v_i = \left(\sum_{i=1}^n u_i^\alpha\right)^{1/\alpha} \cdot \left(\sum_{i=1}^n v_i^\beta\right)^{1/\beta} \quad * \alpha = \beta = 2 \rightarrow \text{cauchy}$

[pf] let $u = \frac{u_i}{A}$, $v = \frac{v_i}{B}$

$\frac{u_i v_i}{AB} = uv \leq \frac{1}{\alpha} \frac{u_i^\alpha}{A^\alpha} + \frac{1}{\beta} \frac{v_i^\beta}{B^\beta}$

" \sum " $\rightarrow \frac{\sum u_i v_i}{AB} \leq \frac{1}{\alpha} + \frac{1}{\beta} = 1 \quad \approx \text{A.E.D.}$



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(Ex 3) More constraints

$$u = f(x, y, z) \quad g(x, y, z) = 0, \quad h(x, y, z) = 0$$

assume that $\begin{vmatrix} g_y & g_z \\ h_y & h_z \end{vmatrix} \neq 0$ at the extremal point

$$\Rightarrow \text{get } y = A(x), \quad z = B(x)$$

$$\Rightarrow 0 = \frac{\partial u}{\partial x_i} = f_{x_i} + f_y A_{x_i} + f_z B_{x_i} \quad \forall i = 1, 2, \dots, n$$

$$0 = g_{x_i} + g_y A_{x_i} + g_z B_{x_i}$$

$$0 = h_{x_i} + h_y A_{x_i} + h_z B_{x_i}$$

$$\Rightarrow \nabla f - \lambda_1 \nabla g + \lambda_2 \nabla h$$

$$\begin{pmatrix} f_{x_i} & f_y & f_z \\ g_{x_i} & g_y & g_z \\ h_{x_i} & h_y & h_z \end{pmatrix} \begin{pmatrix} 1 \\ A_{x_i} \\ B_{x_i} \end{pmatrix} = 0$$

$$\Rightarrow \det \begin{pmatrix} f_{x_i} & f_y & f_z \\ g_{x_i} & g_y & g_z \\ h_{x_i} & h_y & h_z \end{pmatrix} = 0 \Rightarrow \begin{cases} (f_y, f_z) (g_y, g_z) (h_y, h_z) \text{ linear dependent} \\ g, h \text{ linear independent } (\because \begin{vmatrix} g_y & g_z \\ h_y & h_z \end{vmatrix} \neq 0) \end{cases}$$

$$\Rightarrow (f_{x_i}, f_y, f_z) = \lambda_1 (g_{x_i}, g_y, g_z) + \lambda_2 (h_{x_i}, h_y, h_z)$$

λ_1, λ_2 are uniquely determined by the (y, z) components

(indep of $i = 1, 2, \dots, n$)

$$\Rightarrow \nabla f = \lambda_1 \nabla g + \lambda_2 \nabla h \quad \#$$



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§ 3.3 systems of functions, transformation and mappings

we had proved the inverse function theorem by a composition of primitive mappings.

i.e. replace one variable each time

$$\mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$F = \begin{pmatrix} f \\ g \end{pmatrix} \quad (x, y) \mapsto \begin{pmatrix} f(x, y) \\ g(x, y) \end{pmatrix} = \begin{pmatrix} \xi \\ \eta \end{pmatrix}$$

under the assumption that

$$F \text{ is } C^1 \text{ and } \begin{vmatrix} f_x & f_y \\ g_x & g_y \end{vmatrix} \neq 0 \quad \text{at } (x_0, y_0)$$

(Ex 1) curvilinear coordinates

$$\xi = f(x, y) = x^2 - y^2$$

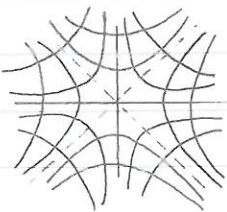
$$\eta = g(x, y) = 2xy$$

$$D \equiv J \equiv \begin{vmatrix} 2x & -2y \\ 2y & 2x \end{vmatrix} = 4(x^2 + y^2) \neq 0$$

unless $(x, y) = (0, 0)$

Jacobian

$(x, y) \rightarrow (-x, -y)$ give the same (ξ, η)

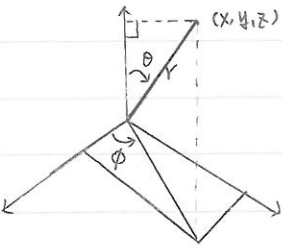


$$\xi + i\eta = x^2 - y^2 + 2i xy = (x + iy)^2 = z^2$$

$$\mathbb{R}^2 \xrightarrow{\begin{pmatrix} \xi \\ \eta \end{pmatrix}} \mathbb{R}^2 \xrightarrow{\begin{pmatrix} x \\ y \\ z \end{pmatrix}}$$

$$X(u, v) = (x(u, v), y(u, v), z(u, v))$$

(Ex 2) spherical coordinates



$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta =$$

$$\phi =$$

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

$$J = \det [X_r, X_\theta, X_\phi]$$

$$= \begin{vmatrix} \sin \theta \cdot \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \cdot \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{vmatrix} = r^2 \sin \theta$$



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matrix notation & chain rule

$$\begin{cases} dx = x_u du + x_v dv \\ dy = y_u du + y_v dv \end{cases}$$

$$\begin{pmatrix} dx \\ dy \end{pmatrix} = \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} \begin{pmatrix} du \\ dv \end{pmatrix}$$

$$dx = [x_u \quad x_v] d\vec{u} \quad \begin{matrix} \nearrow x' = D_x \\ \nearrow \begin{pmatrix} u \\ v \end{pmatrix} \end{matrix}$$

$$x(p+\vec{h}) - x(p) = A\vec{h} + o(|\vec{h}|) \quad \begin{matrix} \uparrow \\ x'(p) \end{matrix}$$

$$\begin{pmatrix} \vec{x} \\ \begin{pmatrix} x \\ y \end{pmatrix} \end{pmatrix} \xrightarrow[\begin{pmatrix} G \\ \psi \end{pmatrix}]{\begin{pmatrix} \vec{u} \\ \begin{pmatrix} u \\ v \end{pmatrix} \end{pmatrix}} \xrightarrow[\begin{pmatrix} F \\ \varphi \end{pmatrix}]{\begin{pmatrix} \vec{z} \\ \begin{pmatrix} z \\ r \end{pmatrix} \end{pmatrix}}$$

$$d\vec{u} = G' dx$$

$$d\vec{z} = F' du = F' G' d\vec{x} \stackrel{\text{By Def.}}{=} (F \circ G)' d\vec{x}$$

chain rule: $(F \circ G)'(p) = F'(G(p)) G'(p)$

If $F = G^{-1}$ i.e. $F \circ G = id$. $[(id)' = id]$

$$F'(G(\vec{x})) \cdot G'(\vec{x}) = I_n$$

[Ex] $\begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} \begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

$$\begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} = \frac{1}{D} \begin{pmatrix} v_y & -u_y \\ -u_x & u_x \end{pmatrix}$$



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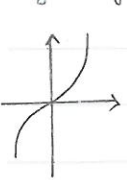
§ 3.3 continued

Dependent functions

$$D = \begin{vmatrix} \phi_x & \phi_y \\ \psi_x & \psi_y \end{vmatrix} = 0$$

$D \neq 0$ at $(x_0, y_0) \Rightarrow \exists$ inverse locally near (x_0, y_0) (IFT)

eg 1 $y = f(x) = x^3$



$$\frac{dy}{dx} = 3x^2 = 0 \quad \text{at } x=0$$

$x = y^{1/3}$ still exists, though it's not differentiable

$$u = x^3 \quad v = y \quad D = \begin{vmatrix} 3x^2 & 0 \\ 0 & 1 \end{vmatrix} = 3x^2$$

$D = 0$ along the y -axis

eg 2
$$\begin{cases} u = x + y + z \\ v = x^2 + y^2 + z^2 \\ w = xy + yz + zx \end{cases}$$

$$\Rightarrow v + 2w = u^2$$

$$D = \begin{vmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ 2x & 2y & 2z \\ yz & xz & xy \end{vmatrix} = 0$$

(condition):

If $u = \phi(x, y)$ satisfies $\begin{vmatrix} \phi_x & \phi_y \\ \psi_x & \psi_y \end{vmatrix} \equiv 0$
 $v = \psi(x, y)$

If $\phi_x \equiv 0 \equiv \phi_y$, then $\phi = \text{constant}$

otherwise, we may assume that $\phi_x \neq 0$ in $u \rightarrow (x_0, y_0)$

Then, we may solve $x = X(u, y)$ s.t. $u = \phi(X(u, y), y)$ for any (u, y)
 $v = \psi(X(u, y), y) = \chi(u, y)$

$$\frac{\partial v}{\partial y} = \psi_x X_y + \psi_y = \psi_x \left(-\frac{\phi_y}{\phi_x}\right) + \psi_y = \frac{D}{\phi_x} = 0$$

$$= \frac{\partial u}{\partial y} = \phi_x X_y + \phi_y \quad \phi_x \psi_y - \phi_y \psi_x \equiv 0$$

\uparrow
 (u, y) indep. variables

$$\Rightarrow v = \chi(u, y) = \chi(u) \text{ is indep. of } y$$

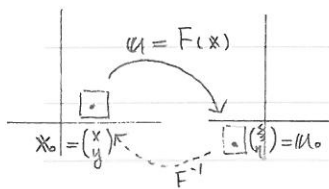
$$\text{i.e. } \psi(X(u, y), y) = \chi(u) = \chi(\phi(X(u, y), y))$$



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$$\text{If } \frac{d(\xi, \eta)}{d(x, y)} = D(x, y) = \det F'(x, y) \neq 0$$

$\exists F^{-1}$ locally

$$F' = \begin{bmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{bmatrix}$$

Solve the inverse mapping near $u_0 = F(x_0)$

Assumption: $F \in C^1$, $F'(x_0)$ is invertible as a matrix

Given u near u_0 , we want to solve $x = G(x) := x - A(u - F(x))$
 expect to hold for some x

$x \mapsto G(x)$ is a dynamical system

fixed point: $x = G(x) \Leftrightarrow u = F(x)$

$$G' = I - AF'(x) \quad [\text{pick } F'(x_0)^{-1} = A, \text{ then } G'(x_0) = 0] \quad \checkmark < \frac{1}{2} = \frac{1}{2n^2} \cdot \frac{1}{2n^2}$$

$$|G(y) - G(x)| \leq \sum_{i=1}^n |\nabla g_i(x + \theta(y-x)) \cdot (y-x)| \leq \left(\sum_{i=1}^n \frac{\max}{x, y} |\nabla g_i| \right) |y-x|$$

$\begin{pmatrix} g_1(x, y) \\ \vdots \\ g_n(x, y) \end{pmatrix} = \begin{pmatrix} F_1(x, y) \\ \vdots \\ F_n(x, y) \end{pmatrix}$ pick $\delta > 0$ small, s.t.

$$\textcircled{1} |x - x_0| < \delta \Rightarrow \frac{\partial g_i}{\partial x_j}(x) < \frac{1}{2n} \quad \forall i, j$$

$$\textcircled{2} |G(x_0) - x_0| < \frac{\delta}{2}, \text{ i.e. } |u - F(x_0)| < \frac{\delta}{2|A|}$$

(ok since $G'(x_0) = 0$)

Let $x_{n+1} = G(x_n) \quad n = 0, 1, 2, \dots$

$$(*) \quad |x_{n+1} - x_0| \leq |x_{n+1} - x_n| + |x_n - x_0|$$

$$\frac{1}{2} |x_n - x_0| \geq |G(x_n) - G(x_0)| \quad G'(x_0) = 0$$

claim: $x_n \in B_\delta(x_0) \quad \forall n$

$$\text{If } n=0, \quad |G(x_0) - x_0| = |A(u - F(x_0))| \leq |A| \cdot |u - F(x_0)| < \frac{\delta}{2}$$

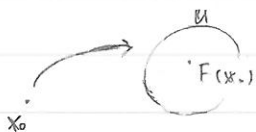
by induction,

$$(*) \Rightarrow |x_{n+1} - x_0| \leq \frac{1}{2} |x_n - x_0| + \frac{1}{2} |x_1 - x_0| < \delta$$

$$x = \sum_{k=0}^{\infty} x_k \quad x_0 + (x_1 - x_0) + (x_2 - x_1) + \dots < \delta$$

$$|x_{k+1} - x_k| \leq \frac{1}{2} |x_k - x_{k-1}|$$

$$< \dots < \frac{1}{2^n} |x_1 - x_0|$$



$$x_{n+1} = G(x_n)$$

$$\lim_{n \rightarrow \infty} x_n \Rightarrow x = G(x)$$



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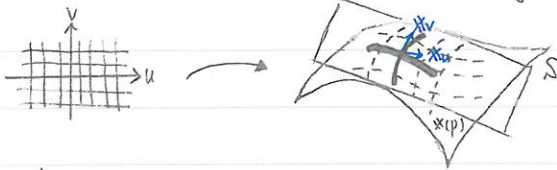
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§ 3.4 Geometric applications :

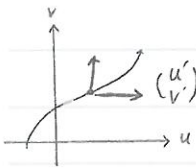
To describe surface in \mathbb{R}^3

$$(u, v) \in U \subset \mathbb{R}^2 \longmapsto \mathbb{R}^3 \ni (x(u, v), y(u, v), z(u, v))^t = \mathbf{x}(u, v)$$



x_u, x_v form a basis of $T_x(p) S$

$$\frac{d}{dt} \mathbf{x}(u(t), v(t)) = x_u u'(t) + x_v v'(t) = \mathbf{x}' \begin{pmatrix} u' \\ v' \end{pmatrix}$$



$$\left(\frac{ds}{dt}\right)^2 = \frac{dx}{dt} \cdot \frac{dx}{dt}$$

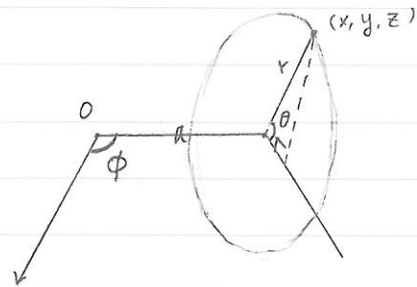
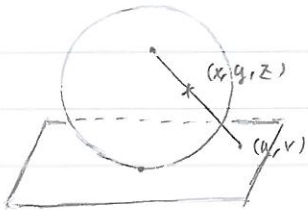
$$= (x_u \frac{du}{dt} + x_v \frac{dv}{dt}) \cdot (x_u \frac{du}{dt} + x_v \frac{dv}{dt})$$

$$= \underbrace{(x_u \cdot x_u)}_{E} \left(\frac{du}{dt}\right)^2 + 2 \underbrace{(x_u \cdot x_v)}_{F} \frac{dv}{dt} \frac{du}{dt} + \underbrace{(x_v \cdot x_v)}_{G} \left(\frac{dv}{dt}\right)^2$$

$$ds^2 = E du^2 + 2F dv du + G dv^2 \quad \Leftarrow 1^{st} \text{ fundamental form}$$

$$(du \ dv) \begin{pmatrix} E & F \\ F & G \end{pmatrix} \begin{pmatrix} du \\ dv \end{pmatrix}$$

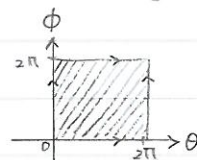
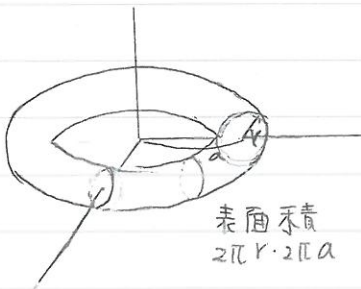
$$ds^2 = \sum_{i,j=1}^2 g_{ij} du^i dv^j$$



$$x = (a + r \cos \theta) \cos \phi$$

$$y = (a + r \cos \theta) \sin \phi$$

$$z = r \sin \theta$$





Subject :

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Chapter 4: Multiple integrals

• definition of area, volume, ... etc

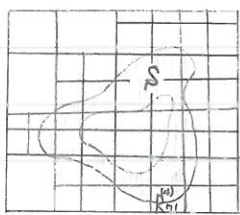
$$A \subset \mathbb{R}^2, |A| \equiv \text{area } A$$

• for (closed) rectangle

$$R = [a, b] \times [c, d], |R| = (b-a) \times (d-c)$$

• If S_1, S_2, \dots, S_n are disjoint sets

$$\text{and } |S_i| \text{ is defined, then } | \cup S_i | = \sum |S_i|$$



(recall on $\mathbb{R} \supset \mathbb{Q}$
does not have length)

"Jordan measurable set"

outer measure $A_n^+(S) \downarrow$

the sum of area of those sub. rectangles containing points of S .

inner measure $A_n^-(S) \uparrow$

the sum of $R_{ij}^{(n)} \subset S$

S is Jordan measure if $A^+(S) = A^-(S) < \mathbb{Q} \text{ is not } >$

• But it has Lebesgue measure = 0

\mathbb{Q} is countable $\mathbb{Q}_1, \mathbb{Q}_2, \dots$

Fact: S has a Jordan measure $\Leftrightarrow |\partial S| = 0$

[pf] " \Leftarrow " $0 \leq A_n^+(S) - A_n^-(S) \leq A_n^+(\partial S) < A_n^-(\partial S) = 0 >$

we may have $R_{ij}^{(n)} \subset S$ but ...

$$n \rightarrow \infty, \text{ get } A^+(S) = A^-(S) \quad R_{ij}^{(n)} \cap \partial S \neq \emptyset$$

$$\Rightarrow \boxed{3} (A_n^+(S) - A_n^-(S)) \neq A_n^+(\partial S) \quad n \rightarrow \infty \text{ done } \neq \text{Q.E.D.}$$

Tarski's paradox

$$\exists \text{ partition } S^2 = \bigsqcup_{i=1}^N A_i$$

$$\exists T_i \in SO(3) \quad T_i^t T_i = I_3$$

$$\bigsqcup_{i=1}^N T_i(A_i) = S^2 \sqcup S^2$$



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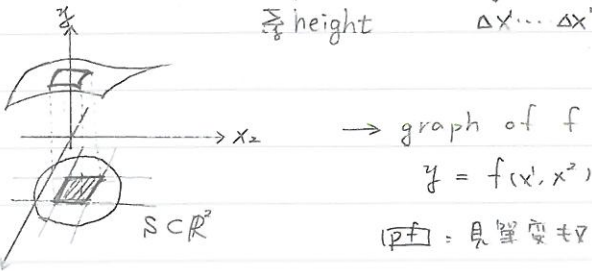
(Example) Definition of Riemann integral over a Jordan measurable set

$$S \subset \mathbb{R}^n \text{ s.t. } |S| \text{ exists}$$

$f: S \rightarrow \mathbb{R}$ continuous function

$$\int_S f(x_1, x_2, \dots, x_n) dx_1 \dots dx_n$$

$\underbrace{\hspace{10em}}_{\substack{\text{height} \\ \frac{1}{n} |S|}}$
 $\underbrace{\hspace{10em}}_{\Delta x_1 \dots \Delta x_n = |R_{ij}^{(n)}|}$



x_1
Theorem (Fubini) <the simple form>

$$R = [a, b] \times [c, d] \rightarrow \phi(y)$$

$$\int_R f(x, y) dx dy = \int_c^d \left[\int_a^b f(x, y) dx \right] dy$$

(Example) $I = \int_0^{\infty} \frac{e^{-ax}}{x} e^{-bx} dx = \log b/a$

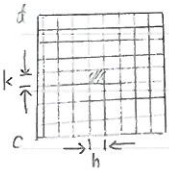
$$\left(-\frac{e^{-xy}}{y} \Big|_0^{\infty} = \frac{1 - e^{-Tb}}{y} \right)$$

$$\begin{aligned} \lim_{T \rightarrow \infty} \int_0^T dx \int_a^b e^{-xy} dy &= \int_a^b dy \int_0^T e^{-xy} dx \\ &= \log y \Big|_a^b - \left(\int_a^b \frac{e^{-Ty}}{y} dy \right) \xrightarrow{T \rightarrow \infty} = \log b/a \end{aligned}$$

(pf) LHS = $\lim_{m, n \rightarrow \infty} \sum_{i=1}^m \sum_{j=1}^n f(a + \mu h, c + \nu k) h k$

$$h = \frac{b-a}{m}, \quad k = \frac{d-c}{n}$$

$$\forall \epsilon > 0, \exists N \text{ s.t. } m, n \geq N \Rightarrow \left| \sum f(\cdot, \cdot) h k - \int \right| < \epsilon$$



Denote by $\Phi_j = \sum_{i=1}^m f(a + \mu h, c + \nu k) h$

$$\left| \int_R f(x, y) dx dy - \left(\sum_{\nu=1}^n \Phi_{\nu} \right) k \right| < \epsilon$$

true $\forall m, n \geq N$

Let $m \rightarrow \infty$, $\lim_{m \rightarrow \infty} \Phi_{\nu} = \int_a^b f(x, c + \nu k) dx$

$$\left| \int_R f(x, y) dx dy - \sum_{\nu=1}^n \phi(c + \nu k) k \right| \leq \epsilon$$

$$\int_R f(x, y) dx dy = \int_c^d dy \int_a^b f(x, y) dx = \int_c^d \phi(y) dy$$



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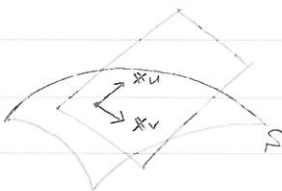
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Subject :

Review Conformal mapping

$$x: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

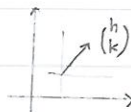
$$\begin{matrix} \downarrow & \downarrow \\ (u,v)^t & (x,y,z)^t \end{matrix}$$



$$x' = [x_u, x_v]$$

$$x'(u,v) \begin{pmatrix} h \\ k \end{pmatrix} = x_u \cdot h + x_v \cdot k$$

\uparrow
 $T_x(u,v)\mathbb{R}^2$

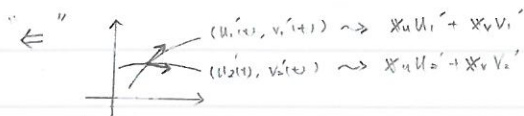


Theorem: x is conformal $\Leftrightarrow ds^2 = E(du^2 + dv^2)$ i.e. $E=G$ & $F=0$

pf " \Rightarrow " $e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto x_u$, $e_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto x_v$

$e_1 \perp e_2$, $F = x_u \cdot x_v = 0$

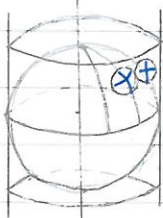
$e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $e_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow (x_u + x_v) \cdot (-x_u + x_v) = 0 = G - E$



$$\cos \theta = \frac{(x_u u_1' + x_v v_1') \cdot (x_u u_2' + x_v v_2')}{\|x_u u_1' + x_v v_1'\| \cdot \|x_u u_2' + x_v v_2'\|}$$

$$= \frac{E(u_1 u_2' + v_1 v_2')}{\sqrt{E(u_1^2 + v_1^2)} \sqrt{E(u_2^2 + v_2^2)}} = \cos \text{ of the original angle on } (u,v) \text{ plane}$$

保長 $A^t A = I$



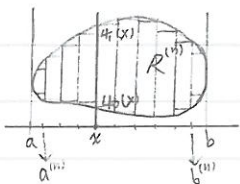
check the radius' cancel out to get 1

$$z = \sqrt{r^2 - x^2 - y^2}$$

$\cdot R = [a,b] \times [c,d]$

$$\int_R f(x,y) \, dA = \int_c^d dy \int_a^b f(x,y) \, dx$$

$\cdot R$ is a convex set



$$\int_R \int dA = \int_a^b dx \int_c^d f(x,y) \, dy$$

$$\int_{R_1 \cup R_2} f \, dA = \int_{R_1} f \, dA + \int_{R_2} f \, dA$$

If $R_1 \cap R_2 = \emptyset$
This holds for $\mathbb{R}^{(n)}$

$$\int_{\mathbb{R}^{(n)}} f \, dA = \int_a^{(n)} dx \int_c^{(n)} f(x,y) \, dy$$

(now let $n \rightarrow \infty$)

$$\int_R f \, dA = \int_a^b dx \int_c^d f(x,y) \, dy$$

$$\left(\left| \int_{R^{(n)}} f \, dA - \int_R f \, dA \right| = M \cdot A^{(n)}(\partial R) \right)$$

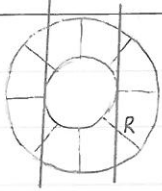
$|f| \leq M$



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Mean Value Thm: $f \in C^0 \Rightarrow$

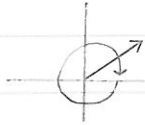
$$A(R) \rightarrow \frac{1}{|R|} \int_R f \, dA = f(p) \quad \text{for some } p \in R$$

(Example)

$$I = \int_{-\infty}^{\infty} e^{-x^2} \, dx$$

$$I^2 = \int_{-\infty}^{\infty} e^{-x^2} \, dx \int_{-\infty}^{\infty} e^{-y^2} \, dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-(x^2+y^2)} \, dx \, dy = \int_0^{2\pi} \int_0^{\infty} e^{-r^2} r \, dr \, d\theta$$

$dA = r \, dr \, d\theta$



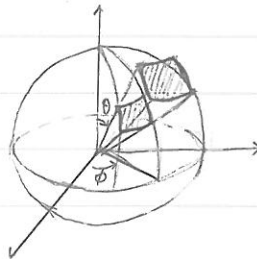
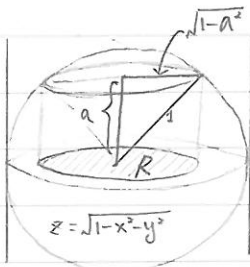
$$r \in (0, \infty)$$

$$\theta \in (0, 2\pi)$$

$$= 2\pi \left(-\frac{1}{2} e^{-r^2} \Big|_0^{\infty} \right) = \pi$$

$$\Rightarrow I = \sqrt{\pi}$$

$$\left(\begin{aligned} \Delta A &= \frac{1}{2} ((r+\Delta r)^2 - r^2) \Delta \theta \\ &= r \Delta r \Delta \theta + \frac{1}{2} \Delta r^2 \Delta \theta \\ \Delta A &= \frac{1}{2} (r_{i+1}^2 - r_i^2) \Delta \theta = \frac{r_{i+1} + r_i}{2} \Delta r \Delta \theta \end{aligned} \right)$$



$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

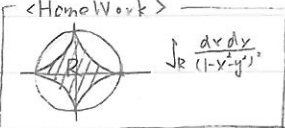
$$z = r \cos \theta$$

$$\int_R (\sqrt{1-x^2-y^2} - a) \, dx \, dy$$

$$\{x^2+y^2 \leq 1-a^2\} = \int_0^{2\pi} \int_0^{\sqrt{1-a^2}} (\sqrt{1-r^2} - a) r \, dr \, d\theta$$

$$(dr)(r \, d\theta)(r \sin \theta \, d\phi) = r^2 \sin \theta \, dr \, d\theta \, d\phi$$

<HomeWork>



$$\int_R \frac{dx \, dy}{(1-x^2-y^2)^2}$$

$$v_1, v_2, v_3 \in \mathbb{R}^5$$

$$\text{Area} \rightarrow |V| = \sqrt{a_1^2 + \dots + a_5^2} = \sqrt{v \cdot v} = \sqrt{v^T v}$$

$|v_1 \wedge v_2|$ "image", the parallelogram spanned by v_1 & v_2

$$\text{i.e. } v_1 \wedge v_2 = \{t \cdot v_1 + s \cdot v_2 \mid 0 \leq t, s \leq 1\}$$

$$V = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \\ a_3 & b_3 \end{bmatrix} \quad \sqrt{\begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \\ a_3 & b_3 \end{bmatrix}^T \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \\ a_3 & b_3 \end{bmatrix}} = \sqrt{\det(V^T V)}$$

$$\mathbb{R}^n \quad V = [v_1, \dots, v_n]$$

$$\text{体积} = \sqrt{\det(V^T V)}$$



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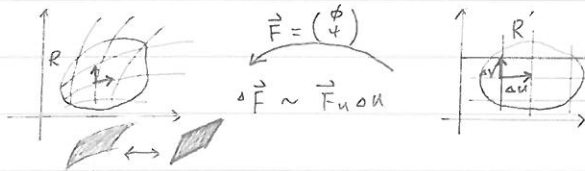
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change of variable formula for multiple integrals

$$\int_R f(x,y) dx dy = \int_{R'} f(\phi(u,v), \psi(u,v)) \cdot \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

Assume $\begin{cases} x = \phi(u,v) \\ y = \psi(u,v) \end{cases}$ $D = \frac{\partial(x,y)}{\partial(u,v)}$ is a C^2 mapping from R' to R with $D \neq 0$



$$|\vec{F}_u \Delta u, \vec{F}_v \Delta v| = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| \Delta u \Delta v$$

↑
at some point

primitive mapping

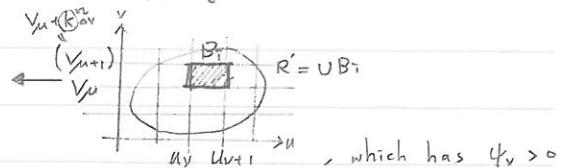
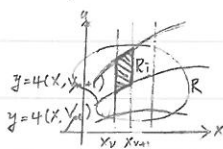
e.g. $\vec{x} = \vec{u} \in R^{n-1}$
 $\psi = \psi(\vec{u}, v)$

$$\frac{\partial(\vec{x}, y)}{\partial(\vec{u}, v)} = \begin{vmatrix} I_{n-1} & \psi_u \\ 0 & \psi_v \end{vmatrix} = \psi_v$$

$$\forall u_i, \psi_{u_i} = \frac{\partial \psi}{\partial u_i} \dots \frac{\partial \psi}{\partial u_{i-1}} \text{ in } R_i'$$

* proof of CVF for primitive mapping

Assume $\begin{cases} x = u \\ y = \psi(u,v) \end{cases}$ gives a 1-1 C^1 mapping between



Area of R_i

$$\begin{aligned} \Delta R_i &= \int_{x_v}^{x_v+h} (\psi(x, v_v+k) - \psi(x, v_v)) dx \\ &= h \cdot (\psi(\tilde{x}_v, v_v+k) - \psi(\tilde{x}_v, v_v)) \\ &= hk \cdot \psi_v(\tilde{x}_v, \tilde{v}_v) \end{aligned}$$

↑
 P_i

$$\begin{cases} \tilde{x}_v \in [x_v, x_v+h] \\ \tilde{v}_v \in [v_v, v_v+k] \end{cases}$$

, which has $\psi_v > 0$

Riemann Sum

$$\sum_i f(\tilde{x}_v, \psi(\tilde{x}_v, \tilde{v}_v)) \Delta R_i = \sum_i f(\tilde{x}_v, \psi(\tilde{x}_v, \tilde{v}_v)) \cdot \psi_v(P_i) h \cdot k$$

<let $(h,k) \rightarrow (0,0)$ >

$$\rightarrow \lim_{h,k \rightarrow 0} \sum_i f(\tilde{x}_v, \psi(\tilde{x}_v, \tilde{v}_v)) \Delta R_i = \int f(x,y) dx dy$$

$$\lim_{h,k \rightarrow 0} \sum_i f(\tilde{x}_v, \psi(\tilde{x}_v, \tilde{v}_v)) \cdot \psi_v(P_i) h k = \int f \cdot \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

↓
 $|\psi_v|$



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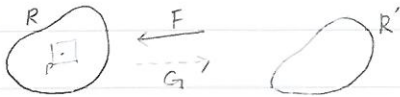
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Lemma: If CVF holds for $(x, y) = F_1(u, v)$
 $(u, v) = F_2(\xi, \eta)$

Then it holds for $(x, y) = (F_1 \circ F_2)(\xi, \eta) \cdot \left| \frac{\partial(x, y)}{\partial(\xi, \eta)} \right|$

[pf:] $\int_R f(x, y) dx dy = \int_{R'} (f \circ F_1 \circ F_2)(\xi, \eta) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| F_2(\xi, \eta) \left| \frac{\partial(u, v)}{\partial(\xi, \eta)} \right| d\xi d\eta$

<for general case =>



$\forall p \in R, \exists$ cube $C_p(R)$

s.t. F can be decomposed into primitive maps.

(Problem = v could vary when p varies)

$$\prod_{i=1}^n [P_i - v, P_i + v]$$

• Assume R is compact (closed & bounded) and

Jordan measurable. Then $\{C_p^{\text{interior}}(R)\}$ is an open cover of R

Heire-Borel Theorem

Any open cover of a compact set admit a finite sub cover

$$\bigcup_{i \in \mathbb{N}} U_i \supset R \Rightarrow \exists \bar{1}, \dots, \bar{N} \text{ (finite) s.t. } U_{\bar{1}} \cup \dots \cup U_{\bar{N}} \supset R$$

By Heire-Borel, $\exists p^{(1)}, \dots, p^{(N)} \in R$

s.t. $R \subset C_{p^{(1)}}(r_{p^{(1)}}) \cup \dots \cup C_{p^{(N)}}(r_{p^{(N)}})$

pick $r = \min(r_{p^{(i)}}), 1 \leq i \leq N$

Note the "1st step" can applied to $R^{(i)} \cap C_{p^{(i)}}(r_{p^{(i)}})$

↓
 when F is decomposable into primitive mappings. $i = 1, 2, \dots, N$

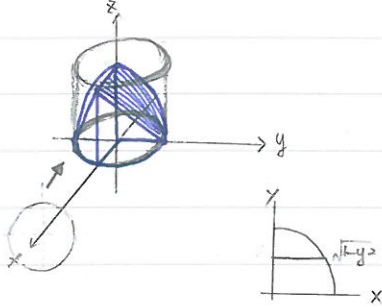


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find the volume of the intersection of 2 cylinders in \mathbb{R}^3
 $\{x^2 + y^2 \leq 1\}$ and $\{y^2 + z^2 \leq 1\}$



$$\begin{aligned}
 8 &= \int_{\mathbb{R}^2} \sqrt{1-y^2} \, dx \, dy \\
 &\Rightarrow \begin{cases} x^2 + y^2 \leq 1 \\ x \geq 0, y \geq 0 \end{cases} \\
 &= 8 \int_0^1 \sqrt{1-y^2} \left(\int_0^{\sqrt{1-y^2}} dx \right) dy \\
 &= 8 \int_0^1 (1-y^2) dy = 8 \left(y - \frac{1}{3}y^3 \right) \Big|_0^1 = \frac{16}{3}
 \end{aligned}$$

$$\left(\begin{array}{l} \text{Diagram of a surface } x(u,v) \text{ with differential vectors } x_u \Delta u, x_v \Delta v \\ \text{Diagram of a grid in the } uv \text{-plane} \end{array} \right)$$

$$|x_u \wedge x_v| \Delta u \Delta v = \sqrt{EG-F^2} \Delta u \Delta v$$

$$A(\mathcal{S}) = A(x(\mathcal{R})) \stackrel{\text{Def}}{=} \int_{\mathcal{R}} |x_u \wedge x_v| \, du \, dv$$

$$\left(\begin{array}{l} \text{Diagram of a surface } z=f(x,y) \text{ with points } (0,0,f_z), (1,0,f_x), (0,1,f_y) \\ \text{Diagram of a grid in the } xy \text{-plane} \end{array} \right)$$

$$\sqrt{1+f_x^2+f_y^2} \, dx \, dy$$

$$EG-F^2 = (1+f_x^2)(1+f_y^2) - f_x^2 f_y^2$$

$$\left(\begin{array}{l} \text{Diagram of a sphere with radius } l \text{ and angles } \theta, \phi \\ \text{Coordinates: } x = r \sin \theta \cos \phi, y = r \sin \theta \sin \phi, z = r \cos \theta \\ \text{Force vector: } \vec{F} = -\frac{GMm}{r^2} \vec{r} \end{array} \right)$$

$$dM = \rho \, dV$$

$$\vec{F} = -\frac{GMm}{r^2} \vec{r} \quad \text{x,y components integrate to 0}$$

$$2\pi \rho \int_B \frac{(r \cos \theta - l) r^2 \sin \theta}{\sqrt{l^2 + r^2 - 2rl \cos \theta}} \, dr \, d\theta \, d\phi$$

$$r^2 \sin^2 \theta + (r \cos \theta - l)^2 = r^2 - 2rl \cos \theta + l^2$$

$$\begin{aligned}
 &[\text{we integrate } \theta \text{ first} \Rightarrow u \quad du = 2rl \sin \theta \, d\theta] \\
 &= \int \frac{1}{2l} \cdot \frac{1}{2l} (r^2 - l^2 - u) u^{\frac{5}{2}} \, du \, dr \quad \left[\cos \theta = \frac{r^2 + l^2 - u}{2rl} \right] \\
 &= \frac{1}{4l^2} \int r \, dr \int (r^2 - l^2) u^{\frac{3}{2}} - u^{\frac{5}{2}} \, du = \frac{2(r^2 - l^2) u^{\frac{7}{2}}}{\frac{7}{2}} \Big|_{u=0}^{\theta=\pi} - \frac{2u^{\frac{7}{2}}}{\frac{7}{2}} \Big|_{\theta=0}^{\theta=\pi} \\
 &\quad \downarrow \quad \quad \quad \downarrow \\
 &= 2(r^2 - l^2) \left(\frac{1}{2l} - \frac{1}{2l} \right) = 2(l+r)(l-r) = -4r = -4r
 \end{aligned}$$

$$= -\frac{2}{l^2} \int_0^l r^2 \, dr = -\frac{2}{3} \frac{R^3}{l^2}$$

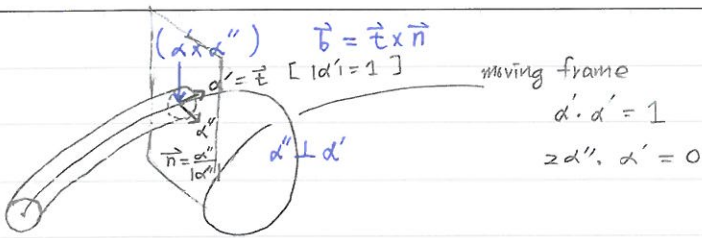
$$\Rightarrow -Gmp \frac{4\pi}{3} R^3 = -\frac{GmM}{l^2}$$



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C : curve

$$\alpha(s), \quad s \in [0, l]$$

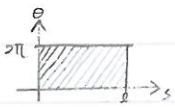
↑
any length $l = \text{length}(C)$

$$X(s, \theta) = \alpha(s) + r(\cos \theta \vec{n} + \sin \theta \vec{b})$$

$$\left\{ \vec{t}, \vec{n}, \vec{b} \right\}$$

$$\alpha'' = \frac{\alpha'}{|\alpha'|} = \vec{t} \times \vec{n}$$

$$\int_0^{2\pi} \int_0^l |X_s \times X_\theta| ds d\theta$$



$$X_s = \vec{t} + r(\cos \theta \vec{n}' + \sin \theta \vec{b}')$$

$$X_\theta = r(-\sin \theta \vec{n} + \cos \theta \vec{b})$$

$$\left(\begin{aligned} \vec{b} &= \vec{t} \times \vec{n} \\ \vec{b}' &= \vec{t}' \times \vec{n} + \vec{t} \times \vec{n}' = \vec{t} \times \vec{n}'' \end{aligned} \right)$$

$$X_s \times X_\theta = r(-\sin \theta \vec{b} - \cos \theta \vec{n}) + \dots$$

$$= -r(\cos \theta \vec{n} + \sin \theta \vec{b}) + \dots$$

$$\alpha = \vec{b}' \cdot \vec{t} = (\vec{b} \cdot \vec{t})' - \vec{b} \cdot \vec{t}' = 0$$

$$\begin{pmatrix} \vec{t}' \\ \vec{n}' \\ \vec{b}' \end{pmatrix} = \begin{pmatrix} 0 & k & 0 \\ -k & 0 & -\tau \\ 0 & \tau & 0 \end{pmatrix} \begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix}$$



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§ 4.7 Improper integrals

① $A(R) < \infty$



f could be not continuous or even $\nearrow \infty$ at some points $P_i \in R$

$$\int_R \frac{dx dy}{(1-x^2-y^2)^2}$$



② $A(R) = \infty$

$R = \mathbb{R}^2$

$$\int_{\mathbb{R}^2} e^{-x^2-y^2} dx dy$$

Theorem Let R be bounded with area (i.e. R is Jordan-measurable)

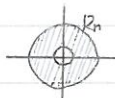
(i) $R_n \nearrow R$ st. f is conti on $R_n \quad \forall n$

↳ closed set, i.e. $R_n \subset R_{n+1}$ & $A(R_n) \rightarrow A(R)$

(ii) and $\int_{R_n} |f| \leq \mu \quad \forall n \quad (*)$

Then $I = \lim_{n \rightarrow \infty} \int_{R_n} f$ exists and independent of choices of $\{R_n\}$ in (i)

(Ex 1)



$$\int_{R=B_0(1)} \frac{dv}{|\vec{r}|^d} \quad \left[\vec{r} = (x, y, z) \right]$$

$$= \lim_{n \rightarrow \infty} \int_{R_n} r^{-d} \cdot r^2 \sin \theta \, dr d\theta d\phi = 2\pi [-\cos \theta]_0^\pi \cdot \int_0^1 r^{2-d} dr$$

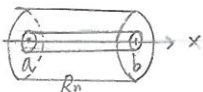
$$\{ |\vec{r}| \leq r \leq 1 \}$$

require $2-d > -1$
 \Rightarrow i.e. $d < 3$

Q: on \mathbb{R}^2 , $1-d > -1 \Rightarrow$ i.e. $d < 2$

How about \mathbb{R}^3 ?

(Ex 2)



need only $d < 2$

$$\text{if } f(x, y, z) \leq \frac{M}{\sqrt{y^2+z^2}}$$

$$R = [a, b] \times "B_0(1)"$$

on yz -plane



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[pf] "step 1" $I_n^+ := \int_{R_n} |f|$ bounded by μ

$\Rightarrow I_n^+ \rightarrow I^+$ exists. (and is a Cauchy sequence)

$\Rightarrow I_n := \int_{R_n} f$ is also a Cauchy sequence

$$\text{because } |I_n - I_m| = \left| \int_{R_n} f - \int_{R_m} f \right| = \left| \int_{R_n \setminus R_m} f \right| \quad (n > m)$$

$$\leq \int_{R_n \setminus R_m} |f| = I_n^+ - I_m^+ < \epsilon \quad \text{for } n, m > N(\epsilon)$$

$\Rightarrow I = \lim_{n \rightarrow \infty} I_n$ exists.

"step 2" Now, for any $S \subset R$, closed, J -m, $f|_S$ is conti.

Need to check $(*)$: " $\int_S |f| \leq \mu$ "

$$\left| \int_S f - \int_{S \cap R_n} f \right| \leq A(S \setminus R_n) \cdot \sup |f| \xrightarrow{n \rightarrow \infty} 0 \quad (**)$$

similarly to $|f|$, get $\int_S |f| = \lim_{n \rightarrow \infty} \int_{S \cap R_n} |f| \leq \mu$
 S 不属于 R_n 還是符合 (ii)

$$\left| \int_S f - \int_{S \cap R_n} f \right| = \lim_{m \rightarrow \infty} \left| \int_{S \cap R_m} f - \int_{S \cap R_n} f \right| \leq \lim_{m \rightarrow \infty} \int_{R_m \setminus R_n} |f| < \epsilon$$

$$\int_{S \cap (R_m \setminus R_n)}$$

for $m, n > N(\epsilon)$ indep of ϵ

now, for another sequence $(*)$

$S_m \uparrow R$ satisfying (i) then (ii) is also satisfied

so $J = \lim_{m \rightarrow \infty} \int_{S_m} f$ exists.

$$\left| J - \int_{S_m \cap R_n} f \right| \leq \underbrace{\left| J - \int_{S_m} f \right|}_{\leq \epsilon} + \underbrace{\left| \int_{S_m} f - \int_{S_m \cap R_n} f \right|}_{\leq \epsilon} \leq 2\epsilon$$

as long as $m, n > N(\epsilon)$

$$\text{similarly, } \left| I - \int_{S_m \cap R_n} f \right| \leq 2\epsilon \Rightarrow |I - J| \leq 4\epsilon$$

$$\Rightarrow I = J \quad \# \text{O.E.D.}$$

* The case with unbounded R

$$\lim_{n \rightarrow \infty} \int_{R_n} f = \lim_{m \rightarrow \infty} \int_{S_m} f$$

(i) $R_n \uparrow R$ now requires the "exhaustion condition"

(opt. J-m)

(every compactum must be contained in R_n for n large)

(ii) $\int_{R_n} |f| \leq \mu \quad \forall n$

Then $I := \lim_{n \rightarrow \infty} \int_{R_n} f$ exists and indep. of the choices of $\{R_n\}$

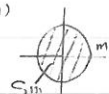
$$R_n = [-n, n] \times [-n, n]$$

(Ex 3)

Gauss' integral

$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$$

$$\lim_{n \rightarrow \infty} \int_{R_n} e^{-(x^2+y^2)} dx dy = \lim_{m \rightarrow \infty} \int_{S_m} = \text{Boole's}$$





Subject :

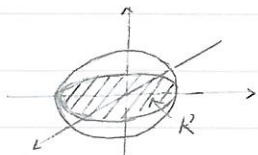
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§ 4.8 more geometric applications

(Ex 4)

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} \leq 1 \quad \begin{cases} x = a \cos \theta \\ y = b r \sin \theta \\ z = z \end{cases} \Rightarrow \frac{\partial(x,y)}{\partial(r,\theta)} = abr$$



$$\begin{aligned} V &= 2 \int_R c \sqrt{1 - \left(\frac{x}{a}\right)^2 - \left(\frac{y}{b}\right)^2} dx dy \\ &= 2 abc \int_0^{2\pi} \int_0^1 \sqrt{1-r^2} r dr d\theta \\ &= \frac{4}{3} \pi abc \quad \# \end{aligned}$$

(Ex 5) Cylindrical coordinates

$$(x, y, z) \leftrightarrow (r, \theta, z)$$

surface (solid) of revolution

$$V = \int_R dV = \int_a^b dz \underbrace{\int_0^{2\pi} d\theta \int_0^{\phi(z)} r dr}_{2\pi \cdot \frac{1}{2} r^2}$$

$$= \pi \int_a^b \phi^2(z) dz$$

$$\tilde{r} = \int_a^b dz \cdot \sqrt{1 - \phi'(z)^2} \cdot 2\pi \cdot \phi(z)$$

in fact, $\mathbf{x}(z, \theta) = (\phi(z) \cos \theta, \phi(z) \sin \theta, z)$

$$\mathbf{x}_z = (\phi' \cos \theta, \phi' \sin \theta, 1)$$

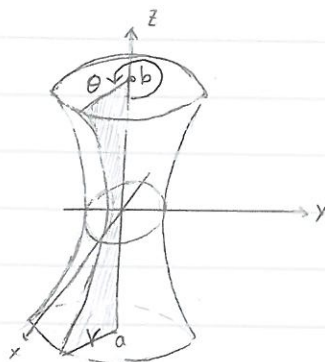
$$\mathbf{x}_\theta = (-\phi \sin \theta, \phi \cos \theta, 0)$$

$$\mathbf{F} = \mathbf{x}_z \cdot \mathbf{x}_\theta = 0$$

$$E = |\mathbf{x}_z|^2 = 1 + (\phi')^2, \quad G = |\mathbf{x}_\theta|^2 = \phi^2$$

$$dA = \sqrt{EG - F^2} d\theta dz = \sqrt{1 - \phi'^2} \phi d\theta dz$$

$$\tilde{S} = 2\pi \int_a^b \sqrt{1 - \phi'^2} \phi dz$$





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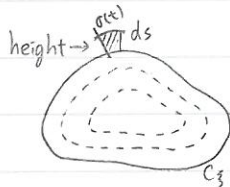
§ 4.10 Multiple integrals in Curvilinear coordinates.

(等高線積分法)



$$V(r) = \frac{4}{3} \pi r^3$$

$$A(r) = 4 \pi r^2$$



$$\phi(x, y) = \xi \rightarrow \text{constant}$$

$$\phi(x(t), y(t)) = \xi$$

$$d\xi = \left(\phi_x \frac{dx}{dt} + \phi_y \frac{dy}{dt} \right) dt = \nabla \phi \cdot \underbrace{\vec{\sigma}'(t)}_{d\vec{\sigma}} dt$$

$$\int f(x, y) ds \quad \left[\frac{d\xi}{|\nabla \phi|} = \frac{d\xi}{\sqrt{\phi_x^2 + \phi_y^2}} \right]$$

The more rigorous deduction of the "co-Area formula"

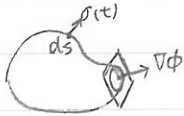
[pf]. consider $\begin{cases} \xi = \phi(x, y) \\ \eta = y \end{cases}$

$$\frac{\partial(\xi, \eta)}{\partial(x, y)} = \begin{vmatrix} \phi_x & \phi_y \\ 0 & 1 \end{vmatrix} = \phi_x \Rightarrow \frac{\partial(x, y)}{\partial(\xi, \eta)} = \frac{1}{\phi_x}$$

$$\int_{\mathcal{R}} f dx dy = \int f \frac{d\xi d\eta}{|\phi_x|} = \int f \frac{d\xi}{\sqrt{\phi_x^2 + \phi_y^2}} \left(\frac{\sqrt{\phi_x^2 + \phi_y^2}}{|\phi_x|} dy \right) \leftarrow$$

$$\begin{aligned} y &= f(x) \\ ds &= \sqrt{1+f_x^2} dx & ds &= \sqrt{1+\frac{\phi_y^2}{\phi_x^2}} dx \\ \phi(x, y) &= \xi \leftarrow \text{fixed} & & = \frac{\sqrt{\phi_x^2 + \phi_y^2}}{|\phi_x|} dx \\ \phi_x + \phi_y f_x &= 0 \rightarrow f_y = -\frac{\phi_y}{\phi_x} & & \# \text{Q.E.D.} \end{aligned}$$

<3D case>



$$\begin{aligned} \phi(x, y, z) &= \xi \\ \int f dv &= \int \frac{f}{|\nabla \phi|} ds d\xi \end{aligned}$$



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(Example) $f \equiv 1$

$$\phi(x, y, z) = r$$

$$|\nabla \phi| = |\nabla r| = 1$$

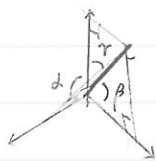
$$\downarrow$$

$$\left(\frac{x}{\sqrt{x^2+y^2+z^2}}, \frac{y}{\sqrt{x^2+y^2+z^2}}, \frac{z}{\sqrt{x^2+y^2+z^2}} \right)$$

$$\begin{cases} \xi = \phi(x, y, z) \\ y = y \\ z = z \end{cases} \Rightarrow \frac{\partial(\xi, y, z)}{\partial(x, y, z)} = \begin{vmatrix} \phi_x & \phi_y & \phi_z \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = \phi_x$$

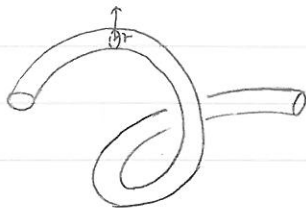
$$\Rightarrow \frac{\partial(x, y, z)}{\partial(\xi, y, z)} = \frac{1}{\phi_x} \quad \downarrow \frac{1}{\cos \alpha}$$

$$\int_P f \, dx \, dy \, dz = \int f \frac{d\xi \, dy \, dz}{\phi_x} = \int f \frac{d\xi}{\sqrt{\phi_x^2 + \phi_y^2 + \phi_z^2}} \underbrace{\left(\frac{\sqrt{\phi_x^2 + \phi_y^2 + \phi_z^2}}{|\phi_x|} \right)}_{ds} \, dy \, dz$$



$$ds = \sqrt{1 + f_y^2 + f_z^2} \, dy \, dz \quad \cdot ds = |x_u \times x_v| \, du \, dv = \sqrt{EG - F^2} \, du \, dv$$

$$\frac{(\phi_x, \phi_y, \phi_z)}{\sqrt{\phi_x^2 + \phi_y^2 + \phi_z^2}} = \frac{\nabla \phi}{|\nabla \phi|} = (\cos \alpha, \cos \beta, \cos \gamma)$$

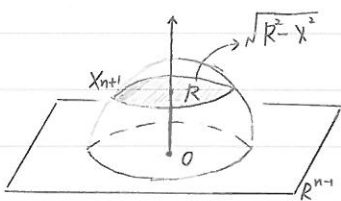


$$V^n(1) \cdot R^n \quad \int \{ \vec{x} \in R^n \mid |\vec{x}| \leq R \}$$

$$V^n(R) = |B_o^n(R)|$$

$$A^{n-1}(R) = |S_o^{n-1}(R)|$$

$$\uparrow \{ \vec{x} \in R^n \mid |\vec{x}| = R \}$$



$$V(R) = 2R$$

$$2 \int_0^R \frac{V^{n-1}(\sqrt{R^2 - x^2})}{\sqrt{R^2 - x^2}} \, dx$$

$V(R)$

$$2V^{n-1}(1) \int_0^R (R^2 - x^2)^{\frac{n}{2}} \, dx$$



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$$V^n(R) = n\text{-dim'l volume of } B_0(R) = V^n(1) \cdot R^n$$

$$A^{n-1}(R) = (n-1)\text{-dim'l area of } S_0^{n-1}(R) = A^{n-1}(1) \cdot R^{n-1}$$

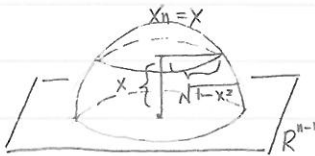
$$\frac{d}{dR} (V^n(R)) = A^{n-1}(R) \Rightarrow nV^n(1) = A^{n-1}(1)$$

$$V^n(1) = 2 \int_0^1 dx V^{n-1}(\sqrt{1-x^2})$$

$$V^{n-1}(1) \cdot (1-x^2)^{\frac{n-1}{2}}$$

$$= V^{n-1}(1) \cdot 2 \int_0^1 (1-x^2)^{\frac{n-1}{2}} dx \quad [\text{Let } x = \sin \theta]$$

$$= V^{n-1}(1) \cdot 2 \int_0^{\frac{\pi}{2}} \cos^2 \theta d\theta \quad \begin{cases} (n \text{ even}) & \frac{n-1}{n} \cdot \frac{n-3}{n-2} \cdots \frac{1}{2} \cdot \pi \\ (n \text{ odd}) & \frac{n-1}{n} \cdot \frac{n-3}{n-2} \cdots \frac{2}{3} \cdot 2 \leftarrow 2 \times 1 \end{cases}$$



< for $n = 2k$ >

$$V^{2k}(1) = V^{2k-1}(1) \cdot \frac{2k-1}{2k} \cdots \frac{1}{2} \times \pi$$

$$= V^{2k-2}(1) \cdot \frac{1}{2k} \cdot 2\pi = \frac{\pi^k}{k!} *$$

$$W_n \stackrel{\text{def}}{=} A^{n-1}(1)$$

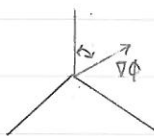
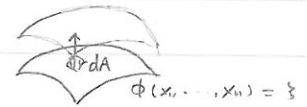
co-area formula :

$$\int_R f(x_1, \dots, x_n) dx_1 \cdots dx_n$$

$$= \int_R \frac{f}{|\nabla \phi|} d\xi dA$$

$$\hookrightarrow dA = \left(\frac{\sqrt{\phi_{x_1}^2 + \dots + \phi_{x_{n-1}}^2}}{|\phi_{x_n}|} \right) dx_1 \cdots dx_{n-1}$$

$$x_n = f(x_1, \dots, x_{n-1})$$



$$dA = \sqrt{1 + f_{x_1}^2 + \dots + f_{x_{n-1}}^2} dx_1 \cdots dx_{n-1}$$

$$r = \xi = \phi = \sqrt{x_1^2 + \dots + x_n^2}, \quad |\nabla \phi| = 1$$

$$\int_{R^n} f dV = \int_{R^n} f dr dA \leftarrow \text{area element on } S_0^{n-1}(r)$$

$$\text{pick : } f = e^{-(x_1^2 + \dots + x_n^2)} = e^{-r^2}$$

$$\pi^{\frac{n}{2}} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} e^{-x_i^2} dx_i = A^{n-1}(1) \cdot \int_0^{\infty} \underbrace{e^{-r^2} r^{n-1}}_{dr} dr$$

$$[\text{let } s = r^2, ds = 2r dr]$$

$$\rightarrow \frac{1}{2} \int_0^{\infty} e^{-s} s^{\frac{n-1}{2} - \frac{1}{2}} ds = \frac{1}{2} \Gamma\left(\frac{n}{2}\right)$$

$$\Rightarrow A^{n-1}(1) = \frac{2\pi^{\frac{n}{2}}}{\Gamma\left(\frac{n}{2}\right)}$$

$$\uparrow$$

$$* \Gamma(s+1) = s \Gamma(s)$$



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Integration / Differentiation of improper integrals with a parameter

$$F(x) = \int_0^{\infty} f(x,y) dy \quad x \in [a,b]$$

converges uniformly is $\forall \epsilon > 0, \exists A$ s.t. $|\int_B^{\infty} f(x,y) dy| < \epsilon \quad \forall B \geq A$

Simple test:

$$|f(x,y)| < \frac{M}{y^{\alpha}} \text{ for } y \geq y_0 \Rightarrow \text{unif. conv.} \quad , \text{ since } \alpha > 1$$

Thm unif. conv. $\Rightarrow f(x)$ is conti on $[a,b]$

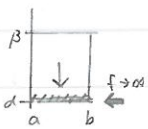
[P.F.] Given $\epsilon > 0$

$$|F(x+h) - F(x)| < \left| \int_0^A (f(x+h,y) - f(x,y)) dy \right| + 2\epsilon < 3\epsilon \quad \text{Q.E.D.}$$

choose h small (depend on A)
s.t. $|f(x+h,y) - f(x,y)| < \frac{\epsilon}{A}$



similarly, $f(x) = \int_a^{\beta} f(x,y) dy$



But $y \rightarrow \alpha$ has ∞ -discontinuity

unif. conv. \iff st. $|\int_{\alpha}^{\alpha+h} f(x,y) dy| < \epsilon$
given $\epsilon > 0, \exists \kappa \quad \forall h \leq \kappa$

$$\text{Test: } |f(x,y)| < \frac{M}{(y-\alpha)^{\nu}} \quad (\nu < 1)$$

$$\boxed{\text{Integrals}} \quad \int_a^{\beta} dx \int_0^{\infty} f(x,y) dy \stackrel{?}{=} \int_0^{\infty} dy \int_a^{\beta} f(x,y) dx$$

$$\Rightarrow \int_a^{\beta} dx \int_0^A f(x,y) dy = \int_0^A dy \int_a^{\beta} f(x,y) dx$$

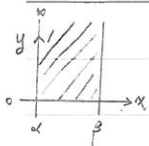
$A \rightarrow \infty \quad \text{Q.E.D.}$



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$$\int_0^{\infty} f(x,y) dy = \int_0^B f(x,y) dy + R_B(x)$$

$F(x)$ uniformly convergent $\Rightarrow F(x)$ continuous

$$\forall \epsilon > 0, \exists A \text{ s.t. } \forall B \geq A \Rightarrow |R_B(x)| < \epsilon$$

$$\int_a^b dx \int_0^{\infty} f(x,y) dy \stackrel{?}{=} \int_0^{\infty} dy \int_a^b f(x,y) dx$$

Yes, By Theorem (需要均匀收敛)

$$\rightarrow \left| \int_a^b R_B(x) dx \right| \leq (b-a) \epsilon$$

$$\int_a^b dx \int_0^B f(x,y) dy + \int_a^b R_B(x) dx = \int_0^B dy \int_a^b f(x,y) dx + \int_a^b R_B(x) dx$$

(Let $B \rightarrow \infty$) This "=" holds \forall

• for exchange of integral $\int_0^{\infty} dy \int_0^{\infty} dx f(x,y)$

so far, we only know that it holds if $\int_{\mathbb{R}^2} |f(x,y)| dx dy$ exists

< Differentiation >

suppose that $f(x,y)$ is piece-wise continuous on $x \in [a, \beta]$

and $F(x) = \int_0^{\infty} f(x,y) dy$, $G(x) = \int_0^{\infty} f_x(x,y) dy$ exist & uniformly

Then $F'(x) = G(x)$

$$\textcircled{1} F'_B(x) = G_B(x)$$

$$\textcircled{2} \text{Let } B \rightarrow \infty, F_B(x) = \int_0^B f(x,y) dy$$

$$\boxed{\text{pf}} \int_a^{\xi} G(x) dx = \int_a^{\xi} dx \int_0^{\infty} f_x(x,y) dy$$

$$= \int_0^{\infty} dy \int_a^{\xi} f_x(x,y) dx = \int_0^{\infty} [f(\xi,y) - f(a,y)] dy$$

$$= F(\xi) - F(a) \Rightarrow F'(x) = G(x) \quad \forall \text{ Q.E.D.}$$

$$\text{(Remark)} \frac{d}{dx} \left(\int_{\delta(x)}^{\infty} f(x,y) dy \right) = \int_{\delta(x)}^{\infty} f_x(x,y) dy + \int_{\delta(x)}^{\delta(x)} f(x,y) dy$$

(Example 1)

$$\int_0^{\infty} e^{-xy} dy = \left[-\frac{e^{-xy}}{x} \right]_0^{\infty} \quad (x > 0)$$

\uparrow
unif. conv.

diff' in x :

$$\int_0^{\infty} \underbrace{y e^{-xy}}_{} dy \stackrel{?}{=} \frac{1}{x^2}$$

\uparrow
require unif. conv of $y e^{-xy}$

$$\int_0^{\infty} \underbrace{y^n}_{M^{-1}} \cdot e^{-\frac{xy}{2}} \cdot e^{-\frac{xy}{2}} = \frac{n!}{x^{n+1}}$$

\uparrow
unif. conv.



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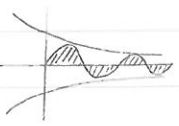
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(Example 2)

$$\int_0^{\infty} \frac{\sin y}{y} dy = \frac{\pi}{2} \quad \text{Thm}$$

e^{-xy} (去進法 \rightarrow unif. conv)

$$\int_0^{\infty} 1 \leq \int_0^{\infty} e^{-xy} = \left. \frac{-e^{-xy}}{x} \right|_0^{\infty}$$



Let $f(x) = \int_0^{\infty} e^{-xy} \frac{\sin y}{y} dy$

$$f'(x) = -\int_0^{\infty} e^{-xy} \sin y dy = \frac{-1}{1+x^2}$$

$(x \geq 0)$
unif. conv. ($x \geq \delta$)

$f(x) = C - \tan^{-1} x$ Let $x \rightarrow \infty$

$$0 = C - \frac{\pi}{2} \Rightarrow F_{(0)} = C = \frac{\pi}{2}$$

(Example 3)

Fresnel's integral

$$F_1 = 2 \int_0^{\infty} \sin(x^2) dx = \int_0^{\infty} \frac{\sin t}{\sqrt{t}} dt$$

(Let $t=x^2, dt=2x dx$)



HW completed yourself

Fourier transpose	
$f(x) \mapsto \hat{f}(y) := \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) e^{-ixy} dx$	
\uparrow oscillation mode (phase)	
$f(x) \mapsto \hat{f}(y) \mapsto f(-x)$	
$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{f}(y) e^{+ixy} dy$	
$\left(\frac{d}{dx}\right)^3$	$(iy)^3$
Picani	

$$v_1, \dots, v_m \in \mathbb{R}^n, \quad v_1^{\wedge} \dots v_m^{\wedge} = \left\{ \sum_{i=1}^m t_i v_i \mid 0 \leq t_i \leq 1 \right\}$$

$$V = [v_1 \dots v_m]_{n \times m}, \quad V^t V = [v_i^t \cdot v_j]_{m \times m}$$

$$\begin{pmatrix} v_1^t \\ \vdots \\ v_m^t \end{pmatrix} [v_1 \dots v_m]$$

$$m\text{-dim'l area} = \sqrt{\det V^t V}$$

$$T \begin{matrix} \nearrow v_1 \dots v_m \\ \circlearrowleft \end{matrix}, \quad TV = \begin{pmatrix} \square \\ \circlearrowleft \end{pmatrix}_{m \times m}$$

$$\mathbb{R}^m \subset \mathbb{R}^n$$

$$(a_1, \dots, a_m, 0, \dots, 0)$$

$$(TV)^t (TV) = V^t T^t TV = V^t V \quad \Leftrightarrow \quad (\square^t)(\square) = \square^t \square$$

$$\det V^t V = \det \square^t \square = (\det \square)^2$$

$$\mathbb{R}^m \xrightarrow{x} \mathbb{R}^n$$

$$x(u_1, \dots, u_m)$$

$$\begin{vmatrix} x_1 \cdot x_1 & x_1 \cdot x_2 \\ x_2 \cdot x_1 & x_2 \cdot x_2 \end{vmatrix}^{\frac{1}{2}} = \begin{vmatrix} E & F \\ F & G \end{vmatrix}^{\frac{1}{2}} = \sqrt{EG - F^2}$$



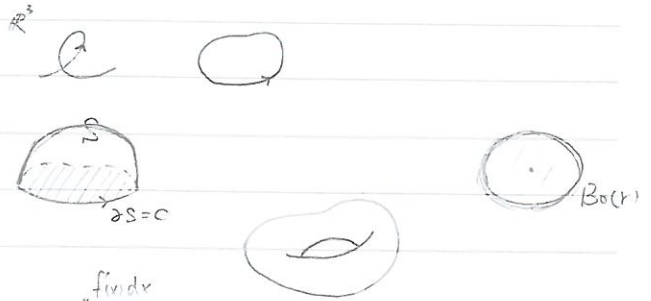
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"vector calculus"

- Green's theorem
- Gauss' theorem (divergence thm)
- Stokes' theorem



⇒ integration by parts

$$\int_a^b f dg = fg - \int_a^b g df$$

(let $f = g \cdot h$) $\int_a^b f dx = f \Big|_a^b$

Green's theorem

$$\int_C p dx + q dy = \int_{\Omega} \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dx dy$$

$$\vec{F} \cdot dx = (P, Q) \cdot (dx, dy)$$

$$C = C_1 \cup (-C_2)$$

on \mathbb{R}^2 $\left[\begin{array}{l} w = p dx + q dy \\ C = \partial \Omega \end{array} \right]$ 1-form

$$\int_{\partial \Omega} w = \int_{\Omega} dw$$

$$\left(\begin{array}{l} \Omega = [a, b] \\ w = f(x) dx \text{ (1-form)} \\ \int_a^b w = \int_a^b f(x) dx \end{array} \right)$$

$$dw = dp \wedge dx + dq \wedge dy = (P_x dx + P_y dy) \wedge dx + (Q_x dx + Q_y dy) \wedge dy$$

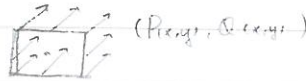
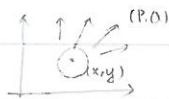
$$= (Q_x - P_y) dx \wedge dy$$

$$\left(\begin{array}{l} dx \wedge dy = -dy \wedge dx \\ df = \sum_i \frac{\partial f}{\partial x_i} dx_i \\ \uparrow \\ \text{total d=4} \end{array} \right)$$

* An equivalent form 2-dim'l divergence thm

$$\vec{F} = (P, Q)$$

$$\text{div } \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y}$$

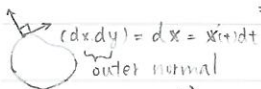


[假定已有 $\int_C p dx + q dy = \int_{\Omega} \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dx dy$]

$$\int_{\Omega} (P_x + Q_y) dx dy = \int_{\partial \Omega} -Q dx + P dy$$

$$\int_{\Omega} \text{div } \vec{F} dx dy = \int_{\Omega} (P_x + Q_y) dx dy = \int_{\partial \Omega} (-Q dx + P dy)$$

$$= \int_{\partial \Omega} \vec{F} \cdot (dy - dx) = \int_{\partial \Omega} \vec{F} \cdot \vec{n} ds$$



$\vec{n} \cdot \vec{t} = \frac{1}{|t|} (y'(t) - x'(t)) dt$, length = $|x'(t)| dt = ds$

$$\lim_{\epsilon \rightarrow 0} \frac{1}{|\Omega|} \int_{\partial \Omega} \vec{F} \cdot \vec{n} ds$$

$$= \frac{1}{|\Omega|} \int_{\Omega} \text{div } \vec{F} dA = \text{div } \vec{F} \text{ at } P$$

→ 通量 flux



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$$\int_{\partial\Omega} \omega = \int_{\Omega} d\omega$$

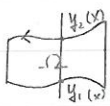
$$* \int_{\partial\Omega} P dx + Q dy = \int_{\Omega} (Q_x - P_y) dx dy$$

↑ for any two C^2 functions P, Q in Ω $\rightarrow \partial\Omega = \cup C_i$
 It's enough to prove * for P & Q separately

$C_i \in PC^1$ curve

[pf] Green's thm for P

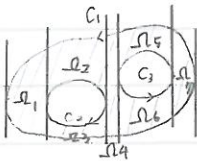
< case 1 > Ω is a region of the form



$$\begin{aligned} \text{RHS} &= \int_{\Omega} -P_y dx dy = - \int_a^b dx \int_{y_1(x)}^{y_2(x)} P(x, y) dy \\ &= \int_a^b P(x, y_1(x)) dx - \int_a^b P(x, y_2(x)) dx = \int_{\partial\Omega} P dx = \text{LHS} \end{aligned}$$

< case 2 > Divide Ω into subregions Ω_i .

s.t. exist Ω_i is of the form in step 1



$$\partial\Omega = C_1 - C_2 - C_3 \text{ (orientation)}$$

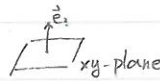
$$\text{Then RHS} = \int_{\Omega} -P_y dx = \sum_{i=1}^N \int_{\Omega_i} -P_y dx$$

similar pf works for Q , but with step 1 modified to be ~~the same~~

* Q.E.D.

$$\textcircled{1} \int_{\Omega} \text{div } \vec{F} dA = \int_{\partial\Omega} \vec{F} \cdot \vec{n} ds$$

$$\textcircled{2} \int_{\Omega} \underbrace{(\text{curl } \vec{F})}_{Q_x - P_y} \cdot \vec{e}_z dA = \int_{\partial\Omega} \vec{F} dx$$



$$\vec{F} = \nabla f \text{ (grad } f) \quad \text{div } \nabla f = (f_x)_x + (f_y)_y = \Delta f$$

$$\textcircled{1}: \int_{\Omega} \Delta f dA = \int_{\partial\Omega} \nabla f \cdot \vec{n} ds$$

" $\frac{\partial f}{\partial n}$ " special notation for normal derivating

$$\vec{F} = \nabla f, \quad \text{div } \vec{F} = \nabla \cdot (\nabla f) = \nabla g \nabla f + g \Delta f$$

Green's formula

$$\text{div } \vec{F} = \nabla \cdot \vec{F} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right) \cdot (P, Q)$$

$$\int_{\Omega} \nabla g \cdot \nabla f + g \Delta f = \int_{\Omega} g \frac{\partial f}{\partial n} ds$$

$$\rightarrow \int_{\Omega} \nabla f \cdot \nabla g + f \Delta g = \int_{\Omega} f \frac{\partial g}{\partial n} ds$$

$$\int_{\Omega} f \Delta g - g \Delta f = \int_{\partial\Omega} \left(f \frac{\partial g}{\partial n} - g \frac{\partial f}{\partial n} \right) ds$$

Stokes' Thm

$$\int_{\partial\Omega} \omega = \int_{\Omega} d\omega$$



Subject :

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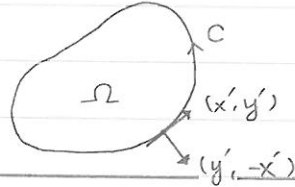
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$$\int_C \omega = \int_{\text{closed curve}} P dx + Q dy \stackrel{\text{Green's thm}}{=} \int_{\Omega} (Q_x - P_y) dx dy$$

$\leftarrow P(x,y) \& Q(x,y) \in C^1$

$$\left\{ \begin{array}{l} \int_C \vec{F} \cdot d\vec{x} \\ \text{circulation} \end{array} \right. \quad \begin{array}{l} * (t) = (x(t), y(t)) \\ \vec{F} = (P, Q) \end{array}$$

$$\left\{ \begin{array}{l} \int_C \vec{F} \cdot \vec{n} ds \\ \text{flux integral} \end{array} \right. \quad \vec{F} = (Q, -P)$$



1. change of variable formula (CVF)

$$I = \int_R f dx dy \quad [x = x(u,v), y = y(u,v) \in C^2]$$

<step 1> Let $f = Q_x$ for some Q 單變數積分 change of variable

$$\begin{aligned} \text{<step 2> } I &= \int_R Q_x dx dy = \int_C Q \frac{dy}{dx} dt = \int_C Q (y_u du + y_v dv) \\ &= \int_C (Q y_u) du + (Q y_v) dv \end{aligned}$$

$$\text{(apply Green's thm)} = \int_{R'} [(Q y_v)_u - (Q y_u)_v] du dv$$

$$\begin{aligned} f &\leftarrow (Q_x x_u + Q_y y_u) y'_v + Q_y y'_{uv} - (Q_x x_v + Q_y y_v) y'_u - Q_y y'_{vu} \\ &= \int_{R'} Q_x \begin{vmatrix} x_u & y_u \\ x_v & y_v \end{vmatrix} \end{aligned}$$

+ problem: y must be C^2 !

#

2. the area enclosed by a curve C

$$A = -\int_C y dx = \int_C x dy = \frac{1}{2} \int_C x dy - y dx$$

3. isoperimetric inequality 等周不等式

Q Fix a length of a curve, find the maximal area enclosed by all such curve

$$A \quad 4\pi A \leq L^2$$

"=" holds iff C is a circle



Subject :

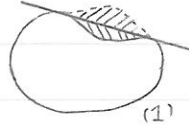
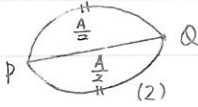
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[pf 1 (古希臘)]

If C bounds Ω with the maximal area

<step 1> Ω is convex



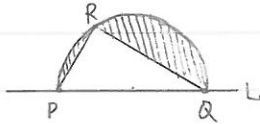
<step 2> for any $\overline{PQ} = \frac{l}{2}$

若否則鏡射處理

\overline{PQ} divide Ω into 2 pieces of equal area

<step 3> only need to consider $P, Q \in L$

$\angle PRQ = \frac{\pi}{2} \quad \forall R \in \overline{PQ}$ [with $|\overline{PQ}| = \frac{l}{2}$ fixed]



fixed the shadow with P, Q allowed to move $\Rightarrow \overline{PQ}$ is a half circle

* problem: maxima Ω exist or not

* Q.E.D.

[Poincare']

$$\rightarrow \int_0^l f^2 dx \stackrel{?}{=} \int_0^l (f')^2 dx$$

suppose that $\int_0^l f dx = 0$

then, $\int_0^l f^2 dx \leq \int_0^l (f')^2 dx$; "=" holds iff $f = a \cos t + b \sin t$

$$[pf] f = (a_1 \cos t + b_1 \sin t) + (a_2 \cos 2t + b_2 \sin 2t) + \dots$$

$$f' = (-a_1 \sin t + b_1 \cos t) + (-2a_2 \sin t + 2b_2 \cos t) + \dots$$

$$\frac{1}{\pi} \int_0^{2\pi} |f|^2 = a_1^2 + b_1^2 + a_2^2 + b_2^2 + \dots$$

$$\frac{1}{\pi} \int_0^{2\pi} |f'|^2 = a_1^2 + b_1^2 + 2^2(a_2^2 + b_2^2) + \dots$$

[pf 2] $l^2 \geq 4\pi A$, For simply, Let's assume $l = 2\pi$

$$\begin{cases} A = \int_C xy' dx & \text{[use arc length } s \text{ as parameter of } C \\ 2\pi = \int_0^{2\pi} \underbrace{(x'^2 + y'^2)}_1 ds \end{cases}$$

$$\Rightarrow 2(\pi - A) = \int_0^{2\pi} (x'^2 + y'^2 - 2xy') ds$$

$$= \int_0^{2\pi} \underbrace{(x'^2 - x^2)}_{\geq 0} ds + \int_0^{2\pi} \underbrace{(y'^2 - y^2)}_{\geq 0} ds$$

$\pi \geq A$

"=" holds iff $\begin{cases} x(s) = a \cos s + b \sin s \\ y(s) = a \sin s - b \cos s + c \end{cases}$

* Q.E.D.

Poincare
(Fourier)



Subject :

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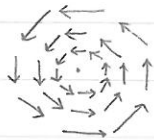
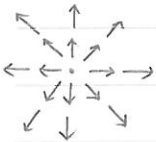
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$$\int_{\partial\Omega} \vec{F} \cdot \vec{n} \, ds = \int_{\Omega} \operatorname{div} \vec{F} \, dA$$

$$\int_{\partial\Omega} \vec{F} \cdot \vec{t} \, ds = \int_{\Omega} (\operatorname{curl} \vec{F})_z \, dA$$

↑ 旋度 vorticity (vortex)

$$* \operatorname{curl} \vec{F} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$



$$\Delta f = \operatorname{div} \vec{F} = 0$$

$\Delta f = 0$ harmonic function

special case: $f = f(r)$

$$\Delta f = \frac{\partial^2 f}{\partial r^2} + \frac{1}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

$$r f'' + f' = (r f')' = 0 \Rightarrow r f' = C$$

$$\Rightarrow f' = \frac{C}{r}$$

$$\Rightarrow f = C \log r + C_1$$

$$\vec{F} = \nabla f = \left(\frac{C}{2} \frac{2x}{x^2+y^2}, \frac{C}{2} \frac{2y}{x^2+y^2} \right)$$

(-y) (x)



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Green's theorem $\int_C P dx + Q dy$

→ Stokes' theorem $\int_C \vec{F} \cdot d\vec{x} = \int_\Omega (\text{curl } \vec{F})_z dA$

(for dim = 2) → if $(\text{curl } \vec{F})_z = 0$, then "locally" $\vec{F} = \nabla \Phi$
 $\approx Q_x - P_y$ (flux integral) $(P, Q) \quad (f_x, f_y)$

→ Gauss' theorem $\int \vec{F} \cdot \vec{n} ds = \int \text{div } \vec{F} dA$

→ when $\vec{F} = \nabla \Phi \Rightarrow \text{div } \nabla \Phi = \Delta \Phi$

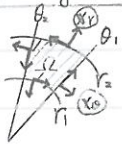
" $\Delta \Phi = 0$ " laplace equation (harmonic function)

$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$$

⇒ Green's formula (integration by parts)

$$\int_\Omega \Delta f dA = \int_C \nabla f \cdot \vec{n} ds = \int_C \frac{\partial f}{\partial n} ds \quad (\vec{F} = \nabla f)$$

$$\int_\Omega (g \Delta f + \nabla g \cdot \nabla f) dA = \int_C g \frac{\partial f}{\partial n} ds$$



$$\int_\Omega \Delta f dA = \int_C \frac{\partial f}{\partial n} ds \quad \begin{matrix} ds = r d\theta \\ \text{unit normal vector} \end{matrix}$$

$$= \int_{\theta_1}^{\theta_2} \left(\frac{\partial f}{\partial r} r \Big|_{r=r_2} - \frac{\partial f}{\partial r} r \Big|_{r=r_1} \right) d\theta + \int_{r_1}^{r_2} \left(\frac{\partial f}{\partial \theta} \Big|_{\theta=\theta_2} - \frac{\partial f}{\partial \theta} \Big|_{\theta=\theta_1} \right) dr \quad \because |\vec{x}| = r$$

$$\begin{aligned} \vec{x}(r, \theta) &= (x, y) = (r \cos \theta, r \sin \theta) \\ \vec{x}_r &= (\cos \theta, \sin \theta) \quad \vec{x}_\theta = (-r \sin \theta, r \cos \theta) \end{aligned}$$

$$= \int_\Omega \left[\frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(\frac{1}{r} \frac{\partial f}{\partial \theta} \right) \right] dr d\theta$$

$$= \int_\Omega \left\{ \frac{1}{r} \left[\frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(r \frac{\partial f}{\partial \theta} \right) \right] \right\} dA \quad \leftarrow r dr d\theta$$

Δf (let $\Omega \rightarrow$ a point) ~~\vec{x}_i~~



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Subject :

* Divergence thm in \mathbb{R}^3 / which can be partitioned into a finite union of simple regions Ω_i (x, y, z directions)

Let Ω be a bounded open set in \mathbb{R}^3 with $\partial\Omega$ be a surface Σ , and Let \vec{F} be a C^1 vector field, then ↓ which is C^1

$$\int_{\Omega} \text{div } \vec{F} \, dV = \int_{\partial\Omega} \vec{F} \cdot \vec{n} \, dS$$
$$\int_{\Omega} (a_x + b_y + c_z) \, dx \, dy \, dz = \int_{\Sigma} a \, dy \, dz + b \, dz \, dx + c \, dx \, dy$$



$\Omega \cup \partial\Omega = \bar{\Omega}$ closed set

In order to talk about the "boundary of surface" we need to consider the "induced topology" from \mathbb{R}^3 to Σ

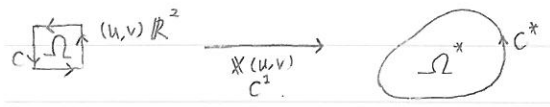
Definition A set $u \subset \Sigma$ is open iff $u = v \cap \Sigma$ for some open set $v \subset \mathbb{R}^3$



"manifold"

- a point $p \in \Sigma$ is an interior if \exists open set $u \ni p$ st. u looks like a disk
- a point $p \in \Sigma$ is a boundary point of Σ if $\nexists u \ni p$ st. u looks like a disk

* 2-dim Green theorem



$$\int_{\Omega^*} (Q_x - P_y) \, dx \, dy = \int_{\Omega^*} P \, dx + Q \, dy = \int_{\Omega} P(xu + xv) + Q(yu + yv) \, du \, dv$$

$$= \int_{\Omega} (P_x u + Q_y u) \, du + (P_x v + Q_y v) \, dv$$

$$= \int_{\Omega} [(P_x v + Q_y v) u - (P_x u + Q_y u) v] \, du \, dv$$

$$= \int_{\Omega} (P_x v + P_x v - P_x u - P_x u + Q_y v + Q_y v - Q_y u - Q_y u) \, du \, dv$$

$$= \int_{\Omega} \left((P_x u + P_y y_u) x_v - (P_x v + P_y y_v) x_u + (Q_x x_u + Q_y y_u) y_v - (Q_x v + Q_y y_v) y_u \right) \, du \, dv$$

$$\hookrightarrow Q_x \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} - P_y \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix}$$

$$= (Q_x - P_y) \frac{\partial(x, y)}{\partial(u, v)} \, du \, dv$$

$$= \int_{\Omega^*} (Q_x - P_y) \, dx \, dy$$



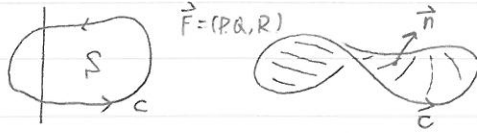
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Subject :

* Stokes' thm in \mathbb{R}^3

$$\int_C \vec{F} \cdot d\vec{x} = \int_S \underbrace{(\text{curl } \vec{F})_z}_{\hookrightarrow \text{curl } \vec{F} \cdot \vec{n}} dA$$



$S \subset \mathbb{R}^3$ be an oriented surface

(i.e. with a given continuously defined normal vector)

" $C = \partial S$ " has the induced (positive) orientation

Its primitive form is $\int_C P dx + Q dy + R dz$

$$\nabla \times \vec{F} = \text{curl } \vec{F}$$

$$\text{curl } \vec{F} \cdot \vec{n} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \cdot (\cos \alpha, \cos \beta, \cos \gamma)$$

$$= \int_S \begin{pmatrix} (R_y - Q_z) \cos \alpha \, ds \\ + (P_z - R_x) \cos \beta \, ds \\ + (Q_x - P_y) \cos \gamma \, ds \end{pmatrix}$$

$$= \int_S (R_y - Q_z) \, dy \, dz + (P_z - R_x) \, dz \, dx + (Q_x - P_y) \, dx \, dy$$

parameterise S by $x(u, v) \stackrel{\Omega}{\mathbb{R}^2} \rightarrow \mathbb{R}^3$



[PFI] $\int_C P dx + Q dy + R dz$

Green's thm $= \int_C (P_x u + Q_y u + R_z u) du + (P_x v + Q_x v + R_x v) dv$

$$= \int_{\Omega} [(P_x v + Q_y u + R_z u) - (P_x u + Q_y v + R_z v)] \, du \, dv$$

$$= \int_{\Omega} \begin{pmatrix} P_u X_v + Q_u Y_v + R_u Z_v \\ -P_v X_u - Q_v Y_u - R_v Z_u \end{pmatrix} \, du \, dv$$

$$= \int_{\Omega} \begin{pmatrix} P_y Y_u X_v + P_z Z_u X_v \\ -P_y Y_v X_u - P_z Z_v X_u \end{pmatrix} \, du \, dv + \begin{pmatrix} Q_x X_u Y_v + Q_z Z_u Y_v \\ -Q_x X_v Y_u - Q_z Z_v Y_u \end{pmatrix} \, du \, dv + \begin{pmatrix} R_x X_u Z_v + R_y Y_u Z_v \\ -R_x X_v Z_u - R_y Y_v Z_u \end{pmatrix} \, du \, dv$$

$$= \int_{\Omega} \begin{pmatrix} (Q_x - P_y) \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} \\ (P_z - R_x) \begin{vmatrix} z_u & z_v \\ x_u & x_v \end{vmatrix} \\ (R_y - Q_z) \begin{vmatrix} y_u & y_v \\ z_u & z_v \end{vmatrix} \end{pmatrix} \, du \, dv \rightarrow dx \, dy = \cos \gamma \, ds$$

$$\rightarrow dx \, dz = \cos \beta \, ds$$

$$\rightarrow dy \, dz = \cos \alpha \, ds$$

$$ds = |x_u \times x_v| \, du \, dv$$

$$(\cos \alpha, \cos \beta, \cos \gamma) = \vec{n} = \frac{x_u \times x_v}{|x_u \times x_v|}$$

$$\int_C P dx + Q dy + R dz = \int_S (R_y - Q_z) \, dy \wedge dz + (P_z - R_x) \, dz \wedge dx + (Q_x - P_y) \, dx \wedge dy$$



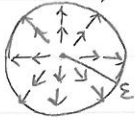
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Q. what kind of f do we have?

< case 1 > if $f = f(r)$



$$f'' + \frac{1}{r} f' = 0$$

$$(rf')' = 0 \Rightarrow rf' = c \Rightarrow f = c \log r + c$$

$$\vec{F} = \nabla f = c \left(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2} \right) \quad r = (x^2+y^2)^{1/2}$$

$c=1$

$$\int_{c_\epsilon} \vec{F} \cdot \vec{n} \, ds = \int_0^{2\pi} \frac{\sqrt{x^2+y^2}}{x^2+y^2} \epsilon \, d\theta = \int_0^{2\pi} d\theta = 2\pi$$

↑ this is independent of ϵ !!



$$\int_C \vec{F} \cdot \vec{n} \, ds$$

$$\partial\Omega = C - C_\epsilon$$

$$\Rightarrow \int_C \vec{F} \cdot \vec{n} \, ds = \int_A \text{div } \vec{F} \, dA = 0$$

無硬邊

(Remark)

$$f(x(r, \theta))$$

$$\frac{\partial f}{\partial \theta} = \nabla f \cdot x_\theta$$

not unit vector $|x_\theta| = r$

$$\Delta = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(-\frac{\partial f}{\partial \theta} \right)$$

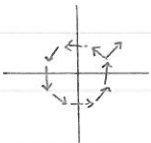
< case 2 > if $f = f(\theta)$

$$\Rightarrow f(\theta) = a\theta + b = a \tan^{-1} \frac{y}{x} + b \quad (\text{is not a well-defined function of } (x, y))$$

$$\nabla f = a \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right)$$

$$\int_C \vec{F} \cdot \vec{n} \, ds = 0 \quad \leftarrow (\text{沒有 flux integral})$$

$$\int_C \vec{F} \cdot dx = f \Big|_{\theta=0}^{\theta=2\pi} = (a\theta + b) \Big|_{\theta=0}^{\theta=2\pi} = a \cdot 2\pi$$





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Green's thm : $\int_{\Omega} P dx + Q dy = \int_{\Omega} (Q_x - P_y) dx dy$

$\int_{\Omega} P dy - Q dx = \int_{\Omega} \underbrace{(P_x + Q_y)}_{\text{div } \vec{F}} dx dy$

$\vec{F} = (a, b, c)$

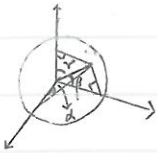
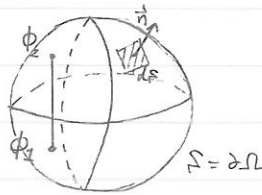
$\text{div } \vec{F} = a_x + b_y + c_z$

3D divergence theorem (Gauss' thm)

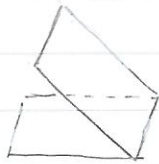
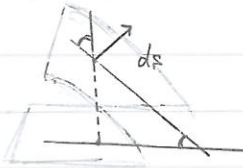
$\int_{\Omega} \text{div } \vec{F} \, dV = \int_{\partial \Omega} \vec{F} \cdot \vec{n} \, dS$

bounded any surface. area on $\partial \Omega = S$

i.e. $\int_{\Omega} (\frac{\partial a}{\partial x} + \frac{\partial b}{\partial y} + \frac{\partial c}{\partial z}) dx dy dz$

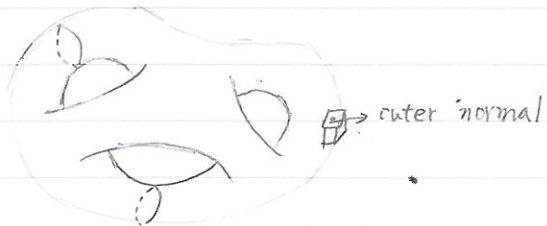
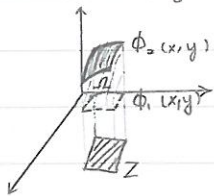


$\int_{\Omega} \vec{F} \cdot \vec{n} \, dS = \int_{\Omega} (a \cos \alpha + b \cos \beta + c \cos \gamma) \, dS$
 $= \int_{\Omega} a \, dy dz + b \, dz dx + c \, dx dy$



[PF] of div. thm: (we prove the thm for "c")

<step 1> Ω is bounded by two graphs of functions $\phi_1(x,y)$ and $\phi_2(x,y)$ over some region in xy-plane



<step 2> For given Ω

Find a partition $\Omega = \cup \Omega_i$

each Ω_i is as in step 1, $\partial \Omega = \partial \Omega_i$ #D.E.D.

• Mobius band

不可定向曲面



非-orientable

[Thm] Jordan curve theorem

Any "closed" surface S in \mathbb{R}^3 is orientable and $S = \partial \Omega$ for a bounded region Ω



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$$R \xrightarrow{g} R'$$

$$(x,y) \longmapsto (u,v)$$

$$\int_{R'} f(u,v) du dv = \int_R f \frac{\partial(u,v)}{\partial(x,y)} dx dy$$

$$\uparrow \textcircled{1} \text{ if } g \text{ is 1-1 and } J(g) = \frac{\partial(u,v)}{\partial(x,y)} > 0$$

$$= \int_R f \frac{\partial(u,v)}{\partial(x,y)} dx dy$$

$$\uparrow \textcircled{2} \text{ if } g \text{ is 1-1 but } J(g) < 0$$

If g is 1-1

$$\text{Define } \epsilon_R(u,v) = \begin{cases} 0 & (u,v) \notin \text{Im } g \\ \text{sign}\left(\frac{\partial(u,v)}{\partial(x,y)}\right) & (u,v) = g(x,y) \end{cases}$$

$$\text{CVF: } \int f \epsilon_R du dv = \int_R f \frac{\partial(u,v)}{\partial(x,y)} dx dy$$

general case:

$$R \rightarrow R' \text{ not 1-1, but } R = \bigcup_{i=1}^m R_i \text{ st. } g \text{ is 1-1 on } R_i$$

(let $c_i = \partial R_i$)

$$\int_R f \frac{\partial(u,v)}{\partial(x,y)} dx dy = \sum_{i=1}^m \int_{R_i} f \frac{\partial(u,v)}{\partial(x,y)} dx dy$$

$$= \sum \int_{R^2} f \cdot \epsilon_{R_i} du dv$$

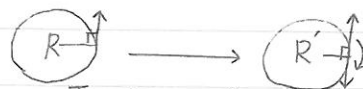
$$= \int_{R^2} f \underbrace{\sum_{i=1}^m \epsilon_{R_i}} du dv$$

$=: \chi_R(u,v)$: degree of the mapping g at (u,v)

$$\text{Identity: } (*) \chi_R(u,v) = \mu_c(u,v)$$

\hookrightarrow winding number of $c' = \text{image of } c \text{ at point } (u,v)$

(i) $*$ is true if $R \rightarrow R'$ is 1-1



$$J(g) > 0 \quad \mu_c = 1$$

$$J(g) < 0 \quad \mu_c = -1$$

(ii) $*$ is additive

$$R = \bigcup A_i = C$$

$$\partial R = \bigcup \partial A_i = C'$$



$$\chi_R(u,v) = \sum_i \chi_{A_i}(u,v)$$

$$= \sum_i \mu_{c_i}(u,v) = \mu_c(u,v)$$

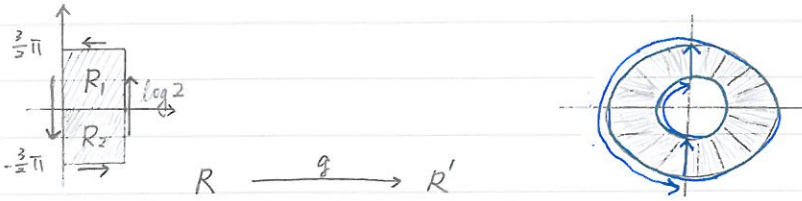


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(Example) $u = e^x \cos y$ $[u+iv = e^x (\cos y + i \sin y) = e^{x+iy}]$
 $v = e^x \sin y$



harmonic function

$$\Delta = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$$

$$\Delta f = 0 \quad " f=f(r), f=f(\theta) "$$

$(u(x,y), v(x,y))$ Cauchy - Riemann eqⁿ

$$\begin{cases} u_x = v_y \\ v_x = -u_y \end{cases} \quad \Delta u = u_{xx} + u_{yy} = v_{yx} + (-v_{xy}) = 0$$

$$\vec{F} = \nabla f$$

$$w = z^3 = (x+iy)^3, \quad w = e^z$$

in general we need "f(x) to be analytic"

i.e. $f(x) = \text{Taylor series}$ "f(z) well defined"

$$\begin{aligned} w &= x^3 + 3x^2 - iy - 3xy^2 - iy^3 \\ &= \underbrace{(x^3 - 3xy^2)}_{u(x,y)} + i \underbrace{(3x^2y - y^3)}_{v(x,y)} \end{aligned}$$

$$u_x = 3x^2 - 3y^2 = v_y, \quad u_y = -3x^2 = -v_x$$